

MA3H2 Markov Processes and Percolation theory

Stefan Adams

2011, update 13.03.2015

Contents

1	Simple random walk	1
1.1	Nearest neighbour random walk on \mathbb{Z}	1
1.2	How often random walkers return to the origin?	6
1.3	Transition function	9
1.4	Boundary value problems	15
1.5	Summary	20
2	Markov processes	21
2.1	Poisson process	23
2.2	Compound Poisson process on \mathbb{Z}^d	25
2.3	Markov processes with bounded rates	28
2.4	The Q -matrix and Kolmogorov's backward equations	30
2.5	Jump chain and holding times	41
2.6	Summary - Markov processes	44
3	Examples, hitting times, and long-time behaviour	46
3.1	Birth-and-death process	46
3.2	Hitting times and probabilities. Recurrence and transience	48
4	Percolation theory	61
4.1	Introduction	61
4.2	Some basic techniques	69
4.3	Bond percolation in \mathbb{Z}^2	69

Preface

These notes are from 2011-2015.

Stefan Adams

1 Simple random walk

1.1 Nearest neighbour random walk on \mathbb{Z}

Pick $p \in (0, 1)$, and suppose that $(X_n: n \in \mathbb{N})$ is a sequence (family) of $\{-1, +1\}$ -valued, identically distributed Bernoulli random variables with $\mathbb{P}(X_i = 1) = p$ and $\mathbb{P}(X_i = -1) = 1 - p = q$ for all $i \in \mathbb{N}$. That is, for any $n \in \mathbb{N}$ and sequence $E = (e_1, \dots, e_n) \in \{-1, 1\}^n$,

$$\mathbb{P}(X_1 = e_1, \dots, X_n = e_n) = p^{N(E)} q^{n-N(E)},$$

where $N(E) = \#\{m: e_m = 1\} = \frac{n + \sum_{m=1}^n e_m}{2}$ is the number of "1"s in the sequence E .

Imagine a walker moving randomly on the integers \mathbb{Z} . The walker starts at $a \in \mathbb{Z}$ and at every integer time $n \in \mathbb{N}$ the walker flips a coin and moves one step to the right if it comes up heads ($\mathbb{P}(\{\text{head}\}) = \mathbb{P}(X_n = 1) = p$) and moves one step to the left if it comes up tails. Denote the position of the walker at time n by S_n . The position S_n is a random variable, it depends on the outcome of the n flips of the coin. We set

$$S_0 = a \text{ and } S_n = S_0 + \sum_{i=1}^n X_i. \quad (1.1)$$

Then $S = (S_n)_{n \in \mathbb{N}}$ is often called a *nearest neighbour random walk on \mathbb{Z}* . The random walk is called *symmetric* if $p = q = \frac{1}{2}$. We may record the motion of the walker as the set $\{(n, S_n): n \in \mathbb{N}_0\}$ of Cartesian coordinates of points in the plane (x -axis is the time and y -axis is the position S_n). We write \mathbb{P}_a for the conditional probability $\mathbb{P}(\cdot | S_0 = a)$ when we set $S_0 = a$ implying $\mathbb{P}(S_0 = a) = 1$. It will be clear from the context which deterministic starting point we consider.

Lemma 1.1 (a) *The random walk is spatially homogeneous, i.e., $\mathbb{P}_a(S_n = j) = \mathbb{P}_{a+b}(S_n = j + b)$, $j, b, a \in \mathbb{Z}$.*

(b) *The random walk is temporally homogeneous, i.e., $\mathbb{P}(S_n = j | S_0 = a) = \mathbb{P}(S_{n+m} = j | S_m = a)$.*

(c) *Markov property*

$$\mathbb{P}(S_{m+n} = j | S_0, S_1, \dots, S_m) = \mathbb{P}(S_{m+n} = j | S_m), n \geq 0.$$

Proof. (a) $\mathbb{P}_a(S_n = j) = \mathbb{P}_a(\sum_{i=1}^n X_i = j - a) = \mathbb{P}_{a+b}(\sum_{i=1}^n X_i = j - a)$.
 (b)

$$\text{LHS} = \mathbb{P}\left(\sum_{i=1}^n X_i = j - a\right) = \mathbb{P}\left(\sum_{i=m+1}^{m+n} X_i = j - a\right) = \text{RHS}.$$

(c) If one knows the value of S_m , then the distribution of S_{m+n} depends only on the jumps X_{m+1}, \dots, X_{m+n} , and cannot depend on further information concerning the values of S_0, S_1, \dots, S_{m-1} . \square

Having that, we get the following stochastic process oriented description of $(S_n)_{n \in \mathbb{N}_0}$ replacing (1.1). Let $(S_n)_{n \in \mathbb{N}_0}$ be a family of random variables S_n taking values in \mathbb{Z} such that $P(S_0 = a) = 1$ and

$$\mathbb{P}(S_n - S_{n-1} = e | S_0, \dots, S_{n-1}) = \begin{cases} p, & \text{if } e = 1 \\ q, & \text{if } e = -1 \end{cases} . \quad (1.2)$$

Markov property: conditional upon the present, the future does not depend on the past.

The set of realisations of the walk is the set of sequences $\mathbf{S} = (\mathbf{s}_0, \mathbf{s}_1, \dots)$ with $\mathbf{s}_0 = a$ and $\mathbf{s}_{i+1} - \mathbf{s}_i = \pm 1$ for all $i \in \mathbb{N}_0$, and such a sequence may be thought of as a sample path of the walk, drawn as in figure 1.

Let us assume that $S_0 = 0$ and $p = \frac{1}{2}$. Natural questions to ask are:

- On the average, how far is the walker from the starting point?
- What is the probability that at a particular time the walker is at the origin?
- More generally, what is the probability distribution for the position of the walker?
- Does the random walker keep returning to the origin or does the walker eventually leave forever?

We easily get that $\mathbb{E}(S_n) = 0$ when $p = \frac{1}{2}$. For the average distance from the origin we compute the squared position at time n , i.e.,

$$\mathbb{E}(S_n^2) = \mathbb{E}((X_1 + \dots + X_n)^2) = \sum_{j=1}^n \mathbb{E}(X_j^2) + \sum_{i \neq j} \mathbb{E}(X_i X_j).$$

Now $X_j^2 = 1$ and the independence of the X_i 's gives $\mathbb{E}(X_i X_j) = \mathbb{E}(X_i)\mathbb{E}(X_j) = 0$ whenever $i \neq j$. Hence, $\mathbb{E}(S_n^2) = n$, and the expected distance from the origin is $\sim c\sqrt{n}$ for some constant $c > 0$.

In order to get more detailed information of the random walk at a given time n we consider the set of possible sample paths. The probability that the first n steps of the walk follow a given path $\mathbf{S} = (\mathbf{s}_0, \mathbf{s}_1, \dots, \mathbf{s}_n)$ is $p^r q^\ell$, where
 $r = \#$ of steps of \mathbf{S} to the right $= \#\{i: \mathbf{s}_{i+1} - \mathbf{s}_i = 1\}$
 $\ell = \#$ of steps of \mathbf{S} to the left $= \#\{i: \mathbf{s}_{i+1} - \mathbf{s}_i = -1\}$.

Hence, any event for the random walk may be expressed in terms of an appropriate set of paths.

$$\mathbb{P}(S_n = b) = \sum_r M_n^r(a, b) p^r q^{n-r}, \quad \mathbb{P}(S_0 = a) = 1,$$

where $M_n^r(a, b)$ is the number of paths $(\mathbf{s}_0, \mathbf{s}_1, \dots, \mathbf{s}_n)$ with $\mathbf{s}_0 = a$ and $\mathbf{s}_n = b$ having exactly r rightward steps. Note that $r + \ell = n$ and $r - \ell = b - a$. Hence,

$$r = \frac{1}{2}(n + b - a) \quad \text{and} \quad \ell = \frac{1}{2}(n - b + a).$$

If $\frac{1}{2}(n + b - a) \in \{0, 1, \dots, n\}$, then

$$\mathbb{P}(S_n = b) = \binom{n}{\frac{1}{2}(n + b - a)} p^{\frac{1}{2}(n + b - a)} q^{\frac{1}{2}(n - b + a)}, \quad (1.3)$$

and $\mathbb{P}(S_n = b) = 0$ otherwise, since there are exactly $\binom{n}{r}$ paths with length n having r rightward steps and $n - r$ leftward steps. Thus to compute probabilities of certain random walk events we shall count the corresponding set of paths. The following result is an important tool for this counting.

Notation: $N_n(a, b) = \#$ of possible paths from $(0, a)$ to (n, b) . We denote by $N_n^0(a, b)$ the number of possible paths from $(0, a)$ to (n, b) which touch the origin, i.e., which contain some point $(k, 0)$, $1 \leq k < n$.

Theorem 1.2 (The reflection principle) *If $a, b > 0$ then*

$$N_n^0(a, b) = N_n(-a, b).$$

Proof. Each path from $(0, -a)$ to (n, b) intersects the x -axis at some earliest point $(k, 0)$. Reflect the segment of the path with times $0 \leq m \leq k$ in the x -axis to obtain a path joining $(0, a)$ and (n, b) which intersects/touches the x -axis, see figure 2. This operation gives a one-one correspondence between the collections of such paths, and the theorem is proved. \square

Lemma 1.3

$$N_n(a, b) = \binom{n}{\frac{1}{2}(n+b-a)}.$$

Proof. Choose a path from $(0, a)$ to (n, b) and let α and β be the numbers of positive and negative steps, respectively, in this path. Then $\alpha + \beta = n$ and $\alpha - \beta = b - a$, so that $\alpha = \frac{1}{2}(n+b-a)$. Now the number of such paths is exactly the number of ways picking α positive steps out of n available steps. Hence,

$$N_n(a, b) = \binom{n}{\alpha}.$$

□

Corollary 1.4 (Ballot theorem) *If $b > 0$ then the number of paths from $(0, 0)$ to (n, b) which do not revisit the x -axis (origin) equals $\frac{b}{n}N_n(0, b)$.*

Proof. The first step of all such paths is to $(1, 1)$, and so the number of such paths is

$$\begin{aligned} N_{n-1}(1, b) - N_{n-1}^0(1, b) &= N_{n-1}(1, b) - N_{n-1}(-1, b) \\ &= \binom{n-1}{\frac{1}{2}(n-1+b-1)} - \binom{n-1}{\frac{1}{2}(n-1+b+1)}. \end{aligned}$$

Elementary computations give the result. □

What can be deduced from the reflection principle? We first consider the probability that the walk does not revisit its starting point in the first n steps.

Theorem 1.5 *Let $S_0 = 0, b \in \mathbb{Z}$, and $p \in (0, 1)$. Then*

$$\mathbb{P}(S_1 S_2 \cdots S_n \neq 0, S_n = b) = \frac{|b|}{n} \mathbb{P}(S_n = b),$$

implying $\mathbb{P}(S_1 S_2 \cdots S_n \neq 0) = \frac{1}{n} \mathbb{E}(|S_n|)$.

Proof. Pick $b > 0$. The admissible paths for the event in question do not visit the x -axis in the time interval $[1, n]$, and the number of such paths is by the Ballot theorem exactly $\frac{b}{n}N_n(0, b)$, and each path has $\frac{1}{2}(n+b)$ rightward and $\frac{1}{2}(n-b)$ leftward steps.

$$\mathbb{P}(S_1 S_2 \cdots S_n \neq 0, S_n = b) = \frac{b}{n} N_n(0, b) p^{\frac{1}{2}(n+b)} q^{\frac{1}{2}(n-b)} = \frac{b}{n} \mathbb{P}(S_n = b).$$

The case for $b < 0$ follows similar, and $b = 0$ is obvious. \square

Surprisingly, the last expression can be used to get the probability that the walk reaches a new maximum at a particular time. Denote by

$$M_n = \max\{S_i : 0 \leq i \leq n\}$$

the maximum value up to time n ($S_0 = 0$).

Theorem 1.6 (Maximum and hitting time theorem) *Let $S_0 = 0$ and $p \in (0, 1)$.*

(a) *For $r \geq 1$ it follows that*

$$\mathbb{P}(M_n \geq r, S_n = b) = \begin{cases} \mathbb{P}(S_n = b) & \text{if } b \geq r \\ \left(\frac{q}{p}\right)^{r-b} \mathbb{P}(S_n = 2r - b) & \text{if } b < r \end{cases} .$$

(b) *The probability $f_b(n)$ that the walk hits b for the first time at the n -th step is*

$$f_b(n) = \frac{|b|}{n} \mathbb{P}(S_n = b).$$

Proof. (a) The case $b \geq r$ is clear. Assume $r \geq 1$ and $b < r$. Let $N_n^r(0, b)$ denote the number of paths from $(0, 0)$ to (n, b) which include some point having height r (i.e., some point (i, r) with time $0 < i < n$). Call such a path π and (i_π, r) the earliest such hitting point of the height r . Now reflect the segment with times larger than i_π in the horizontal height axis (x -axis shifted in vertical direction by r), see figure 3. The reflected path π' (with his segment up to time i_π equal to the one of π) is a path joining $(0, 0)$ and $(n, 2r - b)$. Here, $2r - b$ is the result of $b + 2(r - b)$ which is the terminal point of π' . There is again a one-one correspondence between paths $\pi \leftrightarrow \pi'$, and hence $N_n^r(0, b) = N_n(0, 2r - b)$. Thus,

$$\begin{aligned} \mathbb{P}(M_{n-1} \geq r, S_n = b) &= N_n^r(0, b) p^{\frac{1}{2}(n+b)} q^{\frac{1}{2}(n-b)} \\ &= \left(\frac{q}{p}\right)^{r-b} N_n(0, 2r - b) p^{\frac{1}{2}(n+2r-b)} q^{\frac{1}{2}(n-2r+b)} \\ &= \left(\frac{q}{p}\right)^{r-b} \mathbb{P}(S_n = b). \end{aligned}$$

(b) Pick $b > 0$ (the case for $b < 0$ follows similar). Then, using (a) and the fact that $\{M_{n-1} = b\} = \{M_{n-1} \geq b - 1\} \setminus \{M_{n-1} \geq b\}$, we get

$$\begin{aligned} f_b(n) &= \mathbb{P}(M_{n-1} = S_{n-1} = b - 1, S_n = b) \\ &= p(\mathbb{P}(M_{n-1} \geq b - 1, S_{n-1} = b - 1) - \mathbb{P}(M_{n-1} \geq b, S_{n-1} = b - 1)) \\ &= p(\mathbb{P}(S_{n-1} = b - 1) - \left(\frac{q}{p}\right) \mathbb{P}(S_{n-1} = b + 1)) = \frac{b}{n} \mathbb{P}(S_n = b). \end{aligned}$$

\square

1.2 How often random walkers return to the origin?

We are going to discuss in an heuristic way the question how often the random walker returns to the origin. The walker always moves from an even integer to an odd integer or from an odd integer to an even integer, so we know for sure the position S_n of the walker is at an even integer if n is even or an at an odd integer if n is odd.

Example. Symmetric Bernoulli random walk, $p = \frac{1}{2}$, $S_0 = 0$:

$$\mathbb{P}(S_{2n} = 2j) = \binom{2n}{n+j} 2^{-2n} = 2^{-2n} \frac{(2n)!}{(n+j)!(n-j)!}, \quad j \in \mathbb{Z},$$

and in particular

$$\mathbb{P}(S_{2n} = 0) = 2^{-2n} \frac{(2n)!}{n!n!},$$

and with Stirling's formula

$$n! \sim n^n e^{-n} \sqrt{2\pi n},$$

we finally get

$$\mathbb{P}(S_{2n} = 0) = 2^{-2n} \frac{(2n)!}{n!n!} \sim 2^{-2n} \frac{2^{2n}}{\sqrt{\pi} \sqrt{n}} = \frac{1}{\sqrt{\pi n}}.$$

This fact is consistent with what we already know. We know that the walker tends to go a distance about a constant times \sqrt{n} , and there are about $c\sqrt{n}$ such integer points that are in distance within \sqrt{n} from the origin. Henceforth, it is very reasonable that a particular one is chosen with probability a constant times $n^{-1/2}$.

We consider the number of times that the random walker returns to the origin. Define $J_n = \mathbb{1}\{S_n = 0\}$, $n \in \mathbb{N}_0$. Here the indicator function $\mathbb{1}$ is defined as follows. Let E be an event, then $\mathbb{1}\{E\}$ is the random variable that takes the value 1 if the event occurs and 0 if it does not occur. The total number of visits of the random walker to the origin is then

$$V = \sum_{n=0}^{\infty} J_{2n}.$$

We compute the expectation

$$\mathbb{E}(V) = \sum_{n=0}^{\infty} \mathbb{E}(J_{2n}) = \sum_{n=0}^{\infty} \mathbb{P}(S_{2n} = 0).$$

We know that $\mathbb{P}(S_{2n} = 0) \sim c/\sqrt{n}$ as $n \rightarrow \infty$ for some $c > 0$. Therefore, $\mathbb{E}(V) = \infty$. Note however that it is possible for a random variable to be finite yet have an infinite expectation, so we shall do more work to prove that V is actually infinite. For that, let q be the probability that the random walker ever returns to the origin after time 0.

Claim: $q = 1$.

We shall prove this claim by contradiction. Suppose that $q < 1$. Then we can give the distribution of V . $\mathbb{P}(V = 1) = (1 - q)$ since V is one if and only if the walker never returns after time zero.

$$\mathbb{P}(V = k) = q^{k-1}(1 - q), k = 1, 2, 3, \dots$$

Thus

$$\mathbb{E}(V) = \sum_{k=1}^{\infty} k\mathbb{P}(V = k) = \sum_{k=1}^{\infty} kq^{k-1}(1 - q) = \frac{1}{1 - q} < \infty.$$

The latter equation is easily seen by observing that

$$q^0(1 - q) + 2q(1 - q) + 3q^2(1 - q) + \dots = 1 - q + 2q - 2q^2 + 3q^2 - 3q^3 + \dots$$

We know that $\mathbb{E}(V) = \infty$ and henceforth $q = 1$. With the claim we have shown the following result.

Theorem 1.7 *The probability that a one-dimensional simple random walker returns to the origin infinitely often is one.*

Remark 1.8 (i) $\mathbb{E}(V) = 1 + q\mathbb{E}(V)$ leads to $\mathbb{E}(V) = (1 - q)^{-1}$. The 1 represents the first visit; q is the probability of returning to the origin; and the key observation is that the expected number of visits after the first visit, given there is a second visit, is exactly the expected number of visits starting at the origin.

(ii) If the random walker starts at $x \neq 0$, then the probability that he will get to the origin is one.

What happens in higher dimensions?

Let's consider $\mathbb{Z}^d, d \geq 1$, and $x \in \mathbb{Z}^d, x = (x^1, \dots, x^d)$. We study the simple random walk on \mathbb{Z}^d . The walker starts at the origin (i.e. $S_0 = 0$) and at each integer time n he moves to one of the nearest neighbours with equal probability. Nearest neighbour refers here to the Euclidean distance,

$|x| = (\sum_{i=1}^d (x^i)^2)^{1/2}$, and any lattice site in \mathbb{Z}^d has exactly $2d$ nearest neighbours. Hence, the walker jumps with probability $\frac{1}{2d}$ to one of its nearest neighbours. Denote the position of the walker after $n \in \mathbb{N}$ time steps by $S_n = (S_n^{(1)}, \dots, S_n^{(d)})$ and write $S_n = X_1 + \dots + X_n$, where $X_i = (X_i^{(1)}, \dots, X_i^{(d)})$ are independent random vectors with

$$\mathbb{P}(X_i = y) = \frac{1}{2d}$$

for all $y \in \mathbb{Z}^d$ with $|y| = 1$, i.e., for all $y \in \mathbb{Z}^d$ that are in distance one from the origin. We compute similarly as above

$$\mathbb{E}(|S_n|^2) = \mathbb{E}((S_n^{(1)})^2 + \dots + (S_n^{(d)})^2) = d\mathbb{E}((S_n^{(1)})^2),$$

and

$$\mathbb{E}((S_n^{(1)})^2) = \sum_{j=1}^n \mathbb{E}((X_j^{(1)})^2) + \sum_{i \neq j} \mathbb{E}(X_i^{(1)} X_j^{(1)}).$$

The probability that the walker moves within the first coordinate (either $+1$ or -1) is $\frac{1}{d}$, thus $\mathbb{E}((X_j^{(1)})^2) = \frac{1}{d}$ and $\mathbb{E}(|S_n|^2) = n$. Consider again an even time $2n$ and take n sufficiently large, then (law of large number, local central limit theorem) approximately $\frac{2n}{d}$ expected steps will be done by the walker in each of the d component directions. To be at the origin after $2n$ steps, the walker will have had to have an even number of steps in each of the d component directions. Now for n large the probability for this happening is about $(\frac{1}{2})^{d-1}$. Whether or not an even number of steps have been taken in each of the first $d-1$ component directions are almost independent events; however, we know that if an even number of steps have been taken in the first $d-1$ component directions then an even number of steps have been taken in the last component as well since the total number of steps taken is even. $\frac{2n}{d}$ steps in each component direction gives $\mathbb{P}(S_{2n}^{(i)} = 0) \sim \sqrt{\frac{d}{\pi}} \frac{1}{\sqrt{2n}}$, $i = 1, \dots, d$. Hence,

$$\mathbb{P}(S_{2n} = 0) \sim 2^{1-d} \left(\sqrt{\frac{d}{\pi}} \frac{1}{\sqrt{2n}} \right)^d = \left(\frac{d^{d/2}}{2^{d-1} 2^{d/2} \pi^{d/2}} \right) n^{-d/2}.$$

This is again consistent with what we already know. We know that the mean distance is \sqrt{n} from the origin, and there are about $n^{d/2}$ points in \mathbb{Z}^d that are within distance \sqrt{n} from the origin. Hence, we expect that the probability of choosing a particular one would be of order $n^{-d/2}$. As in $d = 1$ the expected number of visits to the origin up to time n is

$$\mathbb{E}(V) = \sum_{n=0}^{\infty} \mathbb{P}(S_{2n} = 0) = 1 + \text{const} \sum_{j=1}^{\infty} n^{-d/2} = \begin{cases} < \infty & , d \geq 3, \\ = \infty & , d = 1, 2. \end{cases}$$

We summarise these observations in the following theorem.

Theorem 1.9 *Let $(S_n)_{n \in \mathbb{N}_0}$ be the simple random walk in \mathbb{Z}^d with $S_0 = 0$. If $d = 1, 2$, the random walk is **recurrent**, i.e., with probability one it returns to the origin infinitely often. If $d \geq 3$, the random walk is **transient**, i.e., with probability one it returns to the origin only finitely often. In addition we have that*

$$\mathbb{P}(S_n \neq 0 \text{ for all } n > 0) > 0$$

if $d \geq 3$.

The statement for $d \geq 3$ is an application of the Borel-Cantelli Lemma which we recap here.

Lemma 1.10 (Borel-Cantelli Lemma) *Suppose E_1, E_2, \dots is a collection of events such that*

$$\sum_{n=1}^{\infty} \mathbb{P}(E_n) < \infty.$$

Then with probability one at most finitely many of the events occur.

For a proof we refer to standard books in probability or the first support class. We apply this Lemma to the simple random walk in dimension $d \geq 3$. We let E_n be the event that $S_n = 0$. From our previous consideration we get that $\sum_{n=1}^{\infty} \mathbb{P}(E_n) < \infty$, and hence with probability one, only finitely many of the events E_n occur. Henceforth with probability one the random walk revisits the origin only finitely often.

1.3 Transition function

We study random walks on \mathbb{Z}^d and connect them to a particular function, the so-called transition function or transition matrix. For each pair x and y in \mathbb{Z}^d we define a real number $P(x, y)$, and this function will be called transition function or transition matrix.

Definition 1.11 (Transition function/matrix) *Let $P: \mathbb{Z}^d \times \mathbb{Z}^d \rightarrow \mathbb{R}$ be given such that*

$$(i) \quad 0 \leq P(x, y) = P(0, y - x) \text{ for all } x, y \in \mathbb{Z}^d,$$

$$(ii) \quad \sum_{x \in \mathbb{Z}^d} P(0, x) = 1.$$

*The function P is called **transition function** or **transition matrix** on \mathbb{Z}^d .*

It will turn out that this function actually determines completely a random walk on \mathbb{Z}^d . That is, we are now finished - not in the sense that there is no need for further definitions, for there is, but in the sense that all further definitions will be given in terms of P . How is a random walk $S = (S_n)_{n \in \mathbb{N}_0}$ connected with a transition function (matrix)? We consider random walks which are homogeneous in time, that is

$$\mathbb{P}(S_{n+1} = j | S_n = i) = \mathbb{P}(S_1 = j | S_0 = i).$$

This motivates to define

$$P(x, y) = \mathbb{P}(S_{n+1} = y | S_n = x), \quad \text{for all } x, y \in \mathbb{Z}^d. \quad (1.4)$$

Hence, $P(0, x)$ corresponds to our intuitive notion of the probability of a 'one-step' transition from 0 to x . Then it is useful to define $P_n(x, y)$ as the ' n -step' transition probability, i.e., the probability that a random walker (particle) starting at the origin 0 finds itself at x after n transitions (time steps) governed by P .

Example. Bernoulli random walk: The n -step transition probability is given as

$$P_n(0, x) = p^{(n+x)/2} q^{(n-x)/2} \binom{n}{(n+x)/2}$$

when n is even, $|x| \leq n$, and $P_n(0, x) = 0$ otherwise. \diamond

Example. Simple random walk in \mathbb{Z}^d : Any lattice site in \mathbb{Z}^d has exactly $2d$ nearest neighbours. Hence, the transition function (matrix) reads as

$$P(0, x) = \begin{cases} \frac{1}{2d}, & \text{if } |x| = 1, \\ 0, & \text{otherwise.} \end{cases}$$

\diamond

Notation 1.12 *The n -step transition function (matrix) of the a random walk $S = (S_n)_{n \in \mathbb{N}_0}$ is defined by*

$$P_n(x, y) = \mathbb{P}(S_{m+n} = y | S_m = x), \quad m \in \mathbb{N}, x, y \in \mathbb{Z}^d,$$

and we write $P_1(x, y) = P(x, y)$ and $P_0(x, y) = \delta_{x,y}$.

The n -step transition function can be written as

$$P_n(x, y) = \sum_{x_i \in \mathbb{Z}^d, i=1, \dots, n-1} P(x, x_1) P(x_1, x_2) \cdots P(x_{n-1}, y), \quad n \geq 2. \quad (1.5)$$

This is proved in the following statement.

Theorem 1.13 For any pair $r, s \in \mathbb{N}_0$ satisfying $r + s = n \in \mathbb{N}_0$ we have

$$P_n(x, y) = \sum_{z \in \mathbb{Z}^d} P_r(x, z) P_s(z, y), \quad x, y \in \mathbb{Z}^d.$$

Proof. The proof for $n = 0, 1$ is clear. We give a proof for $n = 2$. Induction will give the proof for the other cases as well. The event of going from x to y in two transitions (time steps) can be realised in the mutually exclusive ways of going to some intermediate lattice site $z \in \mathbb{Z}^d$ in the first transition and then going from site $z \in \mathbb{Z}^d$ to y in the second transition. The Markov property implies that the probability of the second transition is $P(z, y)$, and that of the first transition is clearly $P(x, z)$. Using the Markov property and the relation

$$\mathbb{P}(A \cap B | C) = \mathbb{P}(A | B \cap C) \mathbb{P}(B | C),$$

we get for any $m \in \mathbb{N}$,

$$\begin{aligned} P_2(x, y) &= \mathbb{P}(S_{m+2} = y | S_m = x) = \sum_{z \in \mathbb{Z}^d} \mathbb{P}(S_{m+2} = y, S_{m+1} = z | S_m = x) \\ &= \sum_{z \in \mathbb{Z}^d} \mathbb{P}(S_{m+2} = y | S_{m+1} = z, S_m = x) \mathbb{P}(S_{m+1} = z | S_m = x) \\ &= \sum_{z \in \mathbb{Z}^d} \mathbb{P}(S_{m+2} = y | S_{m+1} = z) \mathbb{P}(S_{m+1} = z | S_m = x) \\ &= \sum_{z \in \mathbb{Z}^d} P(x, z) P(z, y). \end{aligned}$$

□

The probability interpretation of $P_n(x, y)$ is evident, it represents the probability that a 'particle', executing a random walk and starting at the lattice site x at time 0, will be at the lattice site $y \in \mathbb{Z}^d$ at time n . We now define a function of a similar type, namely, we are asking for the probability (starting at x at time 0), that the **first** visit to the lattice site y should occur at time n .

Definition 1.14 For all $x, y \in \mathbb{Z}^d$ and $n \geq 2$ define

$$\begin{aligned} F_0(x, y) &:= 0, \\ F_1(x, y) &:= P(x, y), \\ F_n(x, y) &:= \sum_{\substack{x_i \in \mathbb{Z}^d \setminus \{y\} \\ i=1, \dots, n-1}} P(x, x_1) P(x_1, x_2) \cdots P(x_{n-1}, y). \end{aligned}$$

Important properties of the function $F_n, n \geq 2$, are summarised as follows.

Proposition 1.15 For all $x, y \in \mathbb{Z}^d$:

$$(a) \quad F_n(x, y) = F_n(0, y - x).$$

$$(b) \quad \sum_{k=1}^n F_k(x, y) \leq 1.$$

$$(c) \quad P_n(x, y) = \sum_{k=1}^n F_k(x, y)P_{n-k}(y, y).$$

Proof. (a) is clear from the definition and the known properties of P . (b) The claim is somehow obvious. However, we shall give a proof. For $n \in \mathbb{N}$ put $\Omega_n = \{\omega = (x_0, x_1, \dots, x_n) : x_0 = x, x_i \in \mathbb{Z}^d, i = 1, \dots, n\}$. Clearly, Ω_n is countable, and we define a probability for any 'elementary event' $\omega \in \Omega_n$ by

$$p(\omega) := P(x, x_1)P(x_1, x_2) \cdots P(x_{n-1}, x_n), \quad \omega = (x_0, x_1, \dots, x_{n-1}) \in \Omega_n.$$

Clearly,

$$\sum_{\omega \in \Omega : x_n = y} p(\omega) = P_n(x, y),$$

and $\sum_{\omega \in \Omega_n} p(\omega) = \sum_{y \in \mathbb{Z}^d} P_n(x, y) = 1$. The sets A_k ,

$$A_k = \{\omega \in \Omega_n : x_1 \neq y, x_2 \neq y, \dots, x_{k-1} \neq y, x_k = y\}, \quad 1 \leq k \leq n,$$

are disjoint subsets of Ω_n and $F_k(x, y) = \sum_{\omega \in A_k} p(\omega)$ implies that

$$\sum_{k=1}^n F_k(x, y) \leq \sum_{\omega \in \Omega_n} p(\omega) = 1.$$

(c) This can be proved in a very similar fashion, or by induction. We skip the details. \square

We come up now with a third (and last) function of the type above. This time we are after the expected number of visits of a random walk to a given point within a given time. More precisely, we denote by $G_n(x, y)$ the expected number of visits of the random walk, starting at x , to the point y up to time n .

Notation 1.16

$$G_n(x, y) = \sum_{k=0}^n P_k(x, y), \quad n \in \mathbb{N}_0, x, y \in \mathbb{Z}^d.$$

One can easily convince oneself that $G_n(x, y) \leq G_n(0, 0)$ for all $n \in \mathbb{N}_0$, $x, y \in \mathbb{Z}^d$: it suffices to consider $x \neq 0$, using Proposition 1.15(c) we get that

$$\begin{aligned} G_n(x, 0) &= \sum_{k=1}^n P_k(x, 0) = \sum_{k=1}^n \sum_{j=0}^k F_{k-j}(x, 0) P_j(0, 0) \\ &= \sum_{j=0}^n P_j(0, 0) \sum_{i=0}^{n-j} F_i(x, 0) \leq \sum_{j=0}^n P_j(0, 0) = G_n(0, 0). \end{aligned}$$

We are now in the position to classify the random walks according to whether they are **recurrent** or **transient** (non-recurrent). The idea is that $\sum_{k=1}^n F_k(0, 0)$ represents the probability of a return to the origin before or at time n . The sequence of sums $\sum_{k=1}^n F_k(0, 0)$ is non-decreasing as n increases, and by Proposition 1.15 bounded by one. Call the limit by $F \leq 1$. Further, call G the limit of the monotone sequence $(G_n(0, 0))_{n \in \mathbb{N}_0}$.

Notation 1.17 (a) $G(x, y) = \sum_{n=0}^{\infty} P_n(x, y) \leq \infty$ for all $x, y \in \mathbb{Z}^d$, $G_n(0, 0) := G_n$ and $G := G(0, 0)$.

(b) $F(x, y) = \sum_{n=1}^{\infty} F_n(x, y) \leq 1$ or all $x, y \in \mathbb{Z}^d$, $F_n(0, 0) := F_n$ and $F := F(0, 0)$.

Definition 1.18 The random walk (on \mathbb{Z}^d) defined by the transition function P is said to be **recurrent** if $F = 1$ and **transient** if $F < 1$.

Proposition 1.19

$$G = \frac{1}{1 - F} \quad \text{with } G = +\infty \text{ when } F = 1 \text{ and } F = 1 \text{ when } G = +\infty.$$

Proof. (The most convenient way is to prove it is using generating functions). We sketch a direct method.

$$P_n(0, 0) = \sum_{k=0}^n F_k P_{n-k}(0, 0), \quad n \in \mathbb{N}. \quad (1.6)$$

Summing (1.6) over $n = 1, \dots, m$, and adding $P_0(0, 0) = 1$ gives

$$G_m(0, 0) = \sum_{k=0}^m F_k G_{m-k}(0, 0) + 1, \quad m \in \mathbb{N}. \quad (1.7)$$

Letting $m \rightarrow \infty$ we get

$$G = 1 + \lim_{m \rightarrow \infty} \sum_{k=0}^m F_k G_{m-k} \geq 1 + G \sum_{k=0}^N F_k, \quad \text{for all } N \in \mathbb{N},$$

and thus $G \geq 1 + GF$. Now (1.7) gives

$$1 = G_m - \sum_{k=0}^m G_k F_{m-k} \geq G_m - G_m \sum_{k=1}^m F_{m-k} \geq G_m(1 - F),$$

and henceforth $1 \geq G(1 - F)$. \square

Example. Bernoulli random walk: $P(0, 0) = p$, and $P(0, -1) = q = 1 - p$, $p \in [0, 1]$.

$$\mathbb{P}(S_{2n} = 0) = P_{2n}(0, 0) = (pq)^n \binom{2n}{n} = (-1)^n (4pq)^n \binom{-\frac{1}{2}}{n},$$

where we used that

$$\binom{2n}{n} = (-1)^n 4^n \binom{-\frac{1}{2}}{n} \quad (1.8)$$

holds for any $n \in \mathbb{N}$. The binomial coefficients for general numbers r are defined as

$$\binom{r}{k} = \frac{r(r-1)\cdots(r-k+1)}{k!}, \quad k \in \mathbb{N}_0.$$

We prove the claim (1.8) by induction: For $n = 1$ the LHS = $\frac{2!}{1!1!}$ and RHS = $(-1)4^{\frac{-1/2}{1!}}$. Suppose the claim is valid for $n \in \mathbb{N}$. We shall show the claim for $n + 1$ as well. We get

$$\begin{aligned} \binom{2(n+1)}{n+1} &= \frac{(2n)!(2n+1)(2(n+1))}{(n+1)n!(n+1)n!} \\ &= (-1)^n 4^n \binom{-1/2}{n} 2 \frac{(2n+1)}{n+1} \\ &= \frac{(-4)^{n+1} (-n-1/2)(-1/2)(-1/2-1)\cdots(-1/2-n+1)}{(n+1)!} \\ &= (-1)^{n+1} 4^{n+1} \binom{-1/2}{n+1}. \end{aligned}$$

Further, using Newton's generalised Binomial theorem, that is,

$$(x+y)^r = \sum_{k=0}^{\infty} \binom{r}{k} x^{r-k} y^k, \quad (1.9)$$

we - noting that $0 \leq p = 1 - q$ implies that $4pq \leq 1$ - get that

$$\sum_{n=0}^{\infty} t^n P_{2n}(0, 0) = (1 - 4pqt)^{-1/2}, \quad |t| < 1.$$

Thus

$$\lim_{t \rightarrow 1, t < 1} \sum_{n=0}^{\infty} t^n P_{2n}(0, 0) = \sum_{n=0}^{\infty} P_{2n}(0, 0) = \sum_{n=0}^{\infty} P_n(0, 0) = G \leq \infty,$$

henceforth

$$G = \begin{cases} (1 - 4pq)^{-1/2} < \infty, & \text{if } p \neq q, \\ +\infty, & \text{if } p = q. \end{cases}$$

The Bernoulli random walk (on \mathbb{Z}) is recurrent if and only if $p = q = \frac{1}{2}$. \diamond

Example. Simple random walk in \mathbb{Z}^d :

The simple random walk is for

$d = 1$ recurrent,

$d = 2$ recurrent,

$d \geq 3$ transient. \diamond

1.4 Boundary value problems

We give a brief introduction to boundary value problems. We start off with the so-called gambler's ruin. Suppose N is a positive integer and a random walker ($p = \frac{1}{2}$) starts at $x \in \{0, 1, \dots, N\}$. Let S_n denote the position of the walker at time n . Suppose that the random walker stops when he reaches 0 or N . Define the random time

$$T = \min\{n \in \mathbb{N} : S_n = 0 \text{ or } S_n = N\}.$$

Then the position of the walker at time n is $\widehat{S}_n = S_{n \wedge T}$, where $n \wedge T$ denotes the minimum of n and T . We can easily see that with probability one $T < \infty$, that is, the walker eventually reaches 0 or N and then stops. Define the function $F: \{0, 1, \dots, N\} \rightarrow [0, 1]$ by

$$F(x) = \mathbb{P}(S_T = N | S_0 = x).$$

The gambling interpretation is as follows. Suppose S_n is the amount of pounds currently held by the gambler (after n games). The gambler is playing a fair game (starting with exactly x pounds) where at each time duration the gambler wins or loses one pound. The gambler plays until he or she

has N pounds or has gone bankrupt. The chance the gambler does not go bankrupt before attaining N is $F(x)$. Clearly, $F(0) = 0$ and $F(N) = 1$. Let now $0 < x < N$. After the first game, the gambler has either $x - 1$ or $x + 1$ pounds, and each of these outcomes is equally likely. Therefore,

$$F(x) = \frac{1}{2}F(x - 1) + \frac{1}{2}F(x + 1), \quad x = 1, \dots, N - 1. \quad (1.10)$$

A function F that satisfies (1.10) with the boundary conditions $F(0) = 0$ and $F(N) = 1$ is the linear function $F(x) = \frac{x}{N}$. The next theorem shows that this is the only solution to (1.10) with the given boundary conditions.

Theorem 1.20 *Let $a, b \in \mathbb{R}$ and $N \in \mathbb{N}$. Then the only function*

$$F: \{0, 1, \dots, N\} \rightarrow \mathbb{R}$$

satisfying (1.10) with $F(0) = a$ and $F(N) = b$ is the linear function

$$F_0(x) = a + \frac{x(b - a)}{N}, \quad x \in \{0, 1, \dots, N\}.$$

Proof. The proof is relatively easy and there are many different ways to prove it. We immediately see that F_0 solves the equation with the given boundary conditions. We will give two different proofs.

Version 1: Suppose F is a solution to (1.10). Then for each $0 < x < N$,

$$F(x) \leq \max\{F(x - 1), F(x + 1)\}.$$

With this we can easily see that the maximum of F is attained at 0 or N . Similarly, we can show that F attains its minimum at $\{0, N\}$. Suppose that $F(0) = F(N) = 0$. Henceforth F is identical zero. Suppose now $F(0) = a$ and $F(N) = b$ and with at least one of a and b not equal to zero. Let F_0 be the linear function with these same boundary conditions. Then $F - F_0$ satisfies (1.10) with zero boundary condition and henceforth $F - F_0 \equiv 0$. This implies $F = F_0$.

Version 2: Suppose F is a solution of (1.10). Let the random walker start at x . We shall prove that

$$\mathbb{E}[F(S_{n \wedge T})] = F(x), \quad n \in \mathbb{N}_0, x \in \{0, 1, \dots, N\}.$$

We prove this via induction. If $n = 0$ we have $F(S_0) = F(x)$, and hence $\mathbb{E}[F(S_0)] = F(x)$. We assume the claim holds for n and show the inductive step $n \mapsto n + 1$. We compute the expectation and get

$$\mathbb{E}[F(S_{(n+1) \wedge T})] = \sum_{y=0}^N \mathbb{P}(S_{n \wedge T} = y) \mathbb{E}[F(S_{n \wedge T}) | S_{n \wedge T} = y].$$

If $y = 0$ or $y = N$ and $S_{n \wedge T} = y$, then $S_{(n+1) \wedge T} = y$ and hence

$$\mathbb{E}[F(S_{(n+1) \wedge T}) | S_{n \wedge T} = y] = F(y).$$

If $0 < x < N$ and $S_{n \wedge T} = y$, then

$$\mathbb{E}[F(S_{(n+1) \wedge T}) | S_{n \wedge T} = y] = \frac{1}{2}F(y+1) + \frac{1}{2}F(y-1) = F(y).$$

Therefore we obtain

$$\mathbb{E}[F(S_{(n+1) \wedge T})] = \sum_{y=0}^N \mathbb{P}(S_{n \wedge T} = y)F(y) = \mathbb{E}[F(S_{n \wedge T})] = F(x),$$

where the last equality holding by inductive hypothesis and the next to the least equality is the computation of the expectation value. As the right hand side of our claim does not depend on the time n we can pass to the limit and obtain

$$\begin{aligned} F(x) &= \lim_{n \rightarrow \infty} \mathbb{E}[F(S_{n \wedge T})] = \lim_{n \rightarrow \infty} \sum_{y=0}^N \mathbb{P}(S_{n \wedge T} = y)F(y) \\ &= P(S_T = 0)F(0) + \mathbb{P}(S_T = N)F(N) \\ &= (1 - \mathbb{P}(S_T = N))F(0) + \mathbb{P}(S_T = N)F(N) = \mathbb{P}(S_T = N), \end{aligned}$$

where the last equality is obtained using the boundary conditions $F(0) = 0$ and $F(N) = 1$. Now, $\mathbb{P}(S_T = N) = \frac{x}{N}$ finishing the proof showing that

$$F(x) = F(0) + \frac{x}{N}(F(N) - F(0)).$$

Why we have $\mathbb{P}(S_T = N) = \frac{x}{N}$? We can show this using the optimal sampling theorem. Let $M_n := S_{n \wedge T}$. Then M_n is a bounded martingale and the optimal sampling theorem states that for $0 \leq x \leq N$ we have $\mathbb{E}_x[M_0] = \mathbb{E}_x[M_T]$ where the index x at the expectation means starting at x . Martingales are families of random variables, e.g., a fair game is a typically martingale as the expected win does not depend when the game is stopped. We have $x = \mathbb{E}_x[M_0]$ and we compute $\mathbb{E}_x[M_T] = 0\mathbb{P}(S_T = 0) + N\mathbb{P}(S_T = N)$ to get that $\mathbb{P}(S_T = N) = x/N$. \square

We give briefly the definition for martingales.

Definition 1.21 A sequence $(Y_n)_{n \in \mathbb{N}_0}$ of random variables is a martingale with respect to the sequence $(X_n)_{n \in \mathbb{N}_0}$ of random variables if, for all $n \in \mathbb{N}_0$,

$$(i) \mathbb{E}[|Y_n|] < \infty,$$

$$(ii) \mathbb{E}[Y_{n+1}|X_0, \dots, X_n] = Y_n.$$

As an example we consider the random walk in \mathbb{Z} with probability p going to the right. $S_n = X_1 + \dots + X_n$ and

$$\mathbb{E}[S_{n+1}|X_0, \dots, X_n] = Y_n.$$

Therefore $Y_n + S_n - n(p - q)$ is a martingale with respect to the random walk $(S_n)_{n \in \mathbb{N}_0}$. This follows immediately via

$$\mathbb{E}[S_{n+1} - (n + 1)(p - q)|X_0, \dots, X_n] = S_n - n(p - q) = Y_n.$$

We shall generalise our previous theorem to higher dimensions. We replace $\{1, \dots, N - 1\}$ with an arbitrary finite subset $A \subset \mathbb{Z}^d$. The (outer) boundary of A is

$$\partial A = \{z \in \mathbb{Z}^d \setminus A : \text{dist}(z, A) = 1\},$$

and we let $\bar{A} = A \cup \partial A$ be the closure of A .

Definition 1.22 *The linear operators Q and \mathcal{L} acting on functions $F: \mathbb{Z}^d \rightarrow \mathbb{R}$ are defined by*

$$QF(x) = \frac{1}{2d} \sum_{y \in \mathbb{Z}^d : |x-y|=1} F(y)$$

and

$$\mathcal{L}F(x) = (Q - \mathbb{1})F(x) = \frac{1}{2d} \sum_{y \in \mathbb{Z}^d : |x-y|=1} F(y) - F(x).$$

*The operator \mathcal{L} is called the **discrete Laplacian**.*

We easily see that

$$\mathcal{L}F(x) = \mathbb{E}[F(S_1) - F(S_0)|S_0 = x].$$

The name Laplacian is motivated by the continuous space variant. That is, for any function $f: \mathbb{R}^d \rightarrow \mathbb{R}$, the Laplacian is

$$\Delta f(x) = \sum_{i=1}^d \frac{\partial^2 f}{\partial x_i^2}(x).$$

For any $i = 1, \dots, d$ we denote by e_i the basis vector in \mathbb{Z}^d with 1 in the i th-component and all other components equal to zero. The finite difference operators are defined as

$$\begin{aligned}\nabla_i F(x) &= F(x + e_i) - F(x); \\ \nabla_i^* F(x) &= F(x - e_i) - F(x); \\ \nabla_i^2 F(x) &= \frac{1}{2}F(x + e_i) + \frac{1}{2}F(x - e_i) - F(x), \quad x \in \mathbb{Z}^d.\end{aligned}$$

Then

$$\mathcal{L}F(x) = \frac{1}{d} \sum_{i=1}^d \nabla_i^2 F(x) = - \sum_{i=1}^d \nabla_i^* \nabla_i F(x),$$

which justifies the name Laplacian for the linear operator \mathcal{L} .

Definition 1.23 (i) The function $F: \mathbb{Z}^d \rightarrow \mathbb{R}$ is (discrete) **harmonic** at x if $\mathcal{L}F(x) = 0$, and F is **harmonic** in A , $A \subset \mathbb{Z}^d$, if $\mathcal{L}F(x) = 0$ for all $x \in A$.

(ii) **Dirichlet problem for harmonic functions:** Given a set $A \subset \mathbb{Z}^d$ and a function $F: \partial A \rightarrow \mathbb{R}$ find an extension of F to \bar{A} such that F is harmonic in A , i.e., $\mathcal{L}F(x) = 0$ for all $x \in A$.

For the case $d = 1$ and $A = \{1, \dots, N-1\}$, it is easy to guess the solution. In higher dimensions this is no longer the case. However, we will show that our last proof of Theorem 1.20 has a straightforward extension to higher dimensions. We let $T_A = \min\{n \in \mathbb{N}_0: S_n \notin A\}$.

Theorem 1.24 If $A \subset \mathbb{Z}^d$ finite, then for every $F: \partial A \rightarrow \mathbb{R}$, there is a unique extension of F to \bar{A} that satisfies $\mathcal{L}F(x) = 0$ for all $x \in A$. The extension is given by

$$F_0(x) = \mathbb{E}[F(S_{T_A}) | S_0 = x] = \sum_{y \in \partial A} \mathbb{P}(S_{T_A} = y | S_0 = x) F(y).$$

Proof. We only give a brief sketch of the proof. We can easily show that F_0 is indeed a solution. This is left as an exercise to the reader. We are left to show uniqueness of the solution. Suppose F is harmonic on A , $S_0 = x \in \bar{A}$, and let $M_n = F(S_{n \wedge T_A})$. Then $\mathcal{L}F(x) = 0$ for all $x \in A$ can be rewritten as

$$\mathbb{E}[M_{n+1} | S_0, \dots, S_n] = F(S_{n \wedge T_A}) = M_n.$$

Recall that a process $(M_n)_{n \in \mathbb{N}_0}$ that satisfies $\mathbb{E}[M_{n+1} | S_0, \dots, S_n] = M_n$ is called a martingale with respect to the random walk. One can show that F

being harmonic in A is essentially equivalent to $F(S_{n \wedge T_A})$ being a martingale. The optimal sampling theorem gives that $\mathbb{E}[M_n] = \mathbb{E}[M_0]$, $S_0 = x$, and therefore

$$\sum_{y \in \partial A} \mathbb{P}(S_{n \wedge T_A} = y) F(y) = \mathbb{E}[M_n] = \mathbb{E}[M_0] = F(x).$$

As a next step one needs to show that with probability one $T_A < \infty$ (exercise for the reader). We can therefore take limits and obtain

$$F(x) = \lim_{n \rightarrow \infty} \sum_{y \in \partial A} \mathbb{P}(S_{n \wedge T_A} = y) F(y) = \sum_{y \in \partial A} \mathbb{P}(S_{T_A} = y) F(y).$$

□

1.5 Summary

The simple random walks on \mathbb{Z}^d (discrete time) are examples of Markov chains on \mathbb{Z}^d .

Definition 1.25 *Let I be a countable set, $\lambda \in \mathcal{M}_1(I)$ be a probability measure (vector) on I , and $P = (P(i, j))_{i, j \in I}$ be a transition function (stochastic matrix). A sequence $X = (X_n)_{n \in \mathbb{N}_0}$ of random variables X_n taking values in I is called a Markov chain with state space I and transition matrix P and initial distribution λ , if*

$$\begin{aligned} \mathbb{P}(X_{n+1} = i_{n+1} | X_0 = i_0, \dots, X_n = i_n) &= P(i_n, i_{n+1}) \text{ and} \\ \mathbb{P}(X_0 = i) &= \lambda(i), i \in I, \end{aligned}$$

for every $n \in \mathbb{N}_0$ and every $i_0, \dots, i_{n+1} \in I$ with $\mathbb{P}(X_0 = i_0, \dots, X_n = i_n) > 0$. We call the family $X = (X_n)_{n \in \mathbb{N}_0}$ a (λ, P) -Markov chain.

Note that for every $n \in \mathbb{N}_0, i_0, \dots, i_n \in I$, the probabilities are computed as

$$\mathbb{P}(X_0 = i_0, \dots, X_n = i_n) = \lambda(i_0) P(i_0, i_1) P(i_1, i_2) \cdots P(i_{n-1}, i_n).$$

A vector $\lambda = (\lambda(i))_{i \in I}$ is called a stationary distribution of the Markov chain if the following holds:

- (a) $\lambda(i) \geq 0$ for all $i \in I$, and $\sum_{i \in I} \lambda(i) = 1$.
- (b) $\lambda = \lambda P$, that is, $\lambda(j) = \sum_{i \in I} \lambda(i) P(i, j)$ for all $j \in I$.

Without proof we state the following result which will we prove later in the continuous time setting.

Theorem 1.26 *Let I be a finite set and $P: I \times I \rightarrow \mathbb{R}_+$ be a transition function (matrix). Suppose for some $i \in I$ that*

$$P_n(i, j) \rightarrow \lambda(j) \text{ as } n \rightarrow \infty \text{ for all } j \in I.$$

Then $\lambda = (\lambda(j))_{j \in I}$ is an invariant distribution.

2 Markov processes

In this chapter we introduce continuous-time Markov processes with a countable state space I . Throughout the chapter we assume that $X = (X_t)_{t \geq 0}$ is a family of I -valued random variables. The family $X = (X_t)_{t \geq 0}$ is called a *continuous-time random process*. We shall specify the probabilistic behaviour (or *law*) of $X = (X_t)_{t \geq 0}$. However, there are subtleties in this problem not present in the discrete-time case. They arise because the probability of a countable disjoint union is the sum of the single probabilities, whereas for a noncountable union there is no such rule. To avoid these subtleties we shall consider only continuous-time processes which are right continuous. This means that with probability one, for all $t \geq 0$, $\lim_{h \downarrow 0} X_{t+h} = X_t$. By a standard result of measure theory the probability of any event depending on a right-continuous process can be determined from its *finite-dimensional distributions*, that is, from the probabilities $\mathbb{P}(X_{t_0} = i_0, \dots, X_{t_n} = i_n)$ for $n \in \mathbb{N}_0, 0 \leq t_0 \leq \dots \leq t_n$ and $i_0, \dots, i_n \in I$. Throughout we are using both writings, X_t and $X(t)$ respectively.

Definition 2.1 *The process $X = (X_t)_{t \geq 0}$ is said to satisfy the Markov property if*

$$\mathbb{P}(X(t_n) = j | X(t_0) = i_0, \dots, X(t_{n-1}) = i_{n-1}) = \mathbb{P}(X(t_n) = j | X(t_{n-1}) = i_{n-1})$$

for all $j, i_0, \dots, i_{n-1} \in I$ and any sequence $t_0 < t_1 < \dots < t_n$ of times.

We studied in the first chapter the simplest discrete time Markov process (Markov chain) having independent, identically distributed increments (Bernoulli random variables). The simplest continuous time Markov processes are those whose increments are mutually independent and homogeneous in the sense that the distribution of an increment depends only on the length of the time interval over which the increment is taken. More precisely, we are dealing with stochastic processes $X = (X_t)_{t \geq 0}$ having the property that $\mathbb{P}(X_0 = x_0) = 1$ for some $X_0 \in I$ and

$$\mathbb{P}(X(t_1) - X(t_0) = i_1, \dots, X(t_n) - X(t_{n-1}) = i_n) = \prod_{m=1}^n \mathbb{P}(X(t_m) - X(t_{m-1}) = i_m)$$

for $n \in \mathbb{N}, i_1, \dots, i_n \in I$ and all times $t_0 < t_1 < \dots < t_n$.

We introduce in the first subsection the Poisson process on \mathbb{N} . Before that we shall collect some basic facts from probability theory.

Definition 2.2 (Exponential distribution) *A random variable T having values in $[0, \infty)$ has exponential distribution of parameter $\lambda \in [0, \infty)$ if $\mathbb{P}(T >$*

$t) = e^{-\lambda t}$ for all $t \geq 0$. The exponential distribution is the probability measure on $[0, \infty)$ having the (Lebesgue-) density function

$$f_T(t) = \lambda e^{-\lambda t} \mathbb{1}\{t \geq 0\}.$$

We write $T \sim E(\lambda)$ for short. The mean (expectation) of T is given by

$$\mathbb{E}(T) = \int_0^\infty \mathbb{P}(T > t) dt = \lambda^{-1}.$$

The other important distribution is the so-called Gamma distribution. We consider random time points in the interval $(0, \infty)$ (e.g. incoming claims in an insurance company or phone calls arriving at a telephone switchboard). The heuristic reasoning is that, for every $t > 0$, the number of points in $(0, t]$ is Poisson distributed with parameter λt , where $\lambda > 0$ represents the average number of points per time. We look for a model of the r -th random point. What is the probability measure P describing the distribution of the r -th random point?

$P((0, t])$ = probability that the r -th point arrives no later than t (i.e. at least r points/arrivals in $(0, t]$). Denote by $P_{\lambda t}$ the Poisson distribution with parameter λt . We get the probability in question using the complementary event as

$$\begin{aligned} P((0, t]) &= 1 - P_{\lambda t}(\{0, \dots, r-1\}) \\ &= 1 - e^{-\lambda t} \sum_{k=0}^{r-1} \frac{(\lambda t)^k}{k!} = \int_0^t \frac{\lambda^r}{(r-1)!} x^{r-1} e^{-\lambda x} dx. \end{aligned}$$

The last equality can be checked when differentiating with respect to t . Recall the definition of Euler's Gamma function, $\Gamma(r) = \int_0^\infty y^{r-1} e^{-y} dy$, $r > 0$, and $\Gamma(r) = (r-1)!$ for all $r \in \mathbb{N}$.

Definition 2.3 (Gamma distribution) For every $\lambda, r > 0$, the probability measure $\Gamma_{\lambda, r}$ on $[0, \infty)$ with (Lebesgue-) density function

$$\gamma_{\lambda, r}(x) = \frac{\lambda^r}{\Gamma(r)} x^{r-1} e^{-\lambda x}, x \geq 0,$$

is called the Gamma distribution with scale parameter λ and shape parameter r . Note that $\Gamma_{\lambda, 1}$ is the exponential distribution with parameter λ .

Lemma 2.4 (Sum of exponential random variables) If $X_i \sim E(\lambda)$, $i = 1, \dots, n$, independently, and $Z = X_1 + \dots + X_n$ then Z is $\Gamma_{\lambda, n}$ distributed.

Proof. Exercise of example sheet 2. □

2.1 Poisson process

In this Subsection we will introduce a basic intuitive construction of the Poisson process. The Poisson process is the backbone of the theory of Markov processes in continuous time having values in a countable state space. We will study later more general settings. Pick a parameter $\lambda > 0$ and let $(E_i)_{i \in \mathbb{N}}$ be a sequence of i.i.d. (independent identically distributed) random variables (having values in \mathbb{R}_+) that are exponentially distributed with parameter λ (existence of such a sequence is guaranteed - see measure theory). Now, E_i is the time gap (waiting or holding time) between the $(i - 1)$ -th (time) point and the i -th point. Then the sum

$$J_k = \sum_{i=1}^k E_i$$

is the k -th random point in time (see figure). Furthermore, let

$$N_t = \sum_{k \in \mathbb{N}} \mathbb{1}_{(0,t]}(J_k)$$

be the number of points in the interval $(0, t]$. Thus, for $s < t$, $N_t - N_s$ is the number of points in $(s, t]$. Clearly, for $t \in [J_k, J_{k+1})$ one has $N_t = k$.

Theorem 2.5 (Construction of the Poisson process) *The $N_t, t \geq 0$, are random variables having values in \mathbb{N}_0 , and, for $0 = t_0 < t_1 < \dots < t_n$, the increments $N_{t_i} - N_{t_{i-1}}$ are independent and Poisson distributed with parameter $\lambda(t_i - t_{i-1})$, $1 \leq i \leq n$.*

Definition 2.6 *A family $(N_t)_{t \geq 0}$ of \mathbb{N}_0 -valued random variables satisfying the properties of Theorem 2.5 with $N_0 = N(0) = 0$ is called a **Poisson process** with **intensity** $\lambda > 0$.*

We can also write $J_k = \inf\{t > 0: N_t \geq k\}$, $k \geq 1$, in other words, J_k is the k -th time point at which the **sample path** $t \mapsto N_t$ of the Poisson process performs a jump of size 1. These times are therefore called **jump times** of the Poisson process, and $(N_t)_{t \geq 0}$ and $(J_k)_{k \in \mathbb{N}}$ are two manifestations of the same mathematical object.

Proof of Theorem 2.5. First note that

$$\{N_t = k\} = \{J_k \leq t < J_{k+1}\}. \quad (2.11)$$

We consider here $n = 2$ to keep the notation simple. The general case follows analogously. Pick $0 < s < t$ and $k, l \in \mathbb{N}$. It suffices to show that

$$\mathbb{P}(N_s = k, N_{t-s} = l) = \left(e^{-\lambda s} \frac{(\lambda s)^k}{k!}\right) \left(e^{-\lambda(t-s)} \frac{(\lambda(t-s))^l}{l!}\right). \quad (2.12)$$

Having (2.12), summing over l and k , respectively, we conclude that N_s and N_{t-s} are Poisson distributed (and are independent, see right hand side of (2.12)). The joint distribution of the (holding) times $(E_j)_{1 \leq j \leq k+l+1}$ has the product density

$$f(x_1, \dots, x_{k+l+1}) = \lambda^{k+l+1} e^{-\lambda \tau_{k+l+1}(x)},$$

where for convenience we write $\tau_{k+l+1}(x) = x_1 + \dots + x_{k+l+1}$. Using the equality of the events in (2.11), the left hand side of (2.12) reads as

$$\begin{aligned} \mathbb{P}(N_s = k, N_{t-s} - N_s = l) &= \mathbb{P}(J_k \leq s < J_{k+1} \leq J_{k+l} \leq t < J_{k+l+1}) \\ &= \int_0^\infty \dots \int_0^\infty dx_1 \dots dx_{k+l+1} \lambda^{k+l+1} e^{-\lambda \tau_{k+l+1}(x)} \\ &\quad \times \mathbb{1}\{\tau_k(x) \leq s < \tau_{k+1}(x) \leq t < \tau_{k+l+1}(x)\}. \end{aligned}$$

We integrate step by step starting from the innermost integral and moving outwards. Fix x_1, \dots, x_{k+l} and set $z = \tau_{k+l+1}(x)$,

$$\int_0^\infty dx_{k+l+1} \lambda e^{-\lambda \tau_{k+l+1}(x)} \mathbb{1}\{\tau_{k+l+1}(x) > t\} = \int_t^\infty dz \lambda e^{-\lambda z} = e^{-\lambda t}.$$

Fix x_1, \dots, x_k and make the substitution $y_1 = \tau_{k+1}(x) - s, y_2 = x_{k+2}, \dots, y_l = x_{k+l}$ to obtain

$$\begin{aligned} &\int_0^\infty \dots \int_0^\infty dx_{k+1} \dots dx_{k+l} \mathbb{1}\{s < \tau_{k+1}(x) \leq \tau_{k+l}(x) \leq t\} \\ &= \int_0^\infty \dots \int_0^\infty dy_1 \dots dy_l \mathbb{1}\{y_1 + \dots + y_l \leq t - s\} = \frac{(t-s)^l}{l!}, \end{aligned}$$

which can be proved via induction on l . In a similar way one gets

$$\int_0^\infty \dots \int_0^\infty dx_1 \dots dx_k \mathbb{1}\{\tau_k(x) \leq s\} = \frac{s^k}{k!}.$$

Combing all our steps above, we obtain finally

$$\mathbb{P}(N_s = k, N_{t-s} = l) = e^{-\lambda t} \lambda^{k+l} \frac{s^k}{k!} \frac{(t-s)^l}{l!}.$$

□

The following statement shows that the Poisson process satisfies the Markov property.

Theorem 2.7 *Let $N = (N_t)_{t \geq 0}$ be a Poisson process with intensity $\lambda > 0$, then*

$$\mathbb{P}(N_{s+t} - N_s = k | N_\tau, \tau \in [0, s]) = \mathbb{P}(N_t = k), k \in \mathbb{N}.$$

That is for all $s > 0$, the past $(N_\tau)_{\tau \in [0, s]}$ is independent of the future $(N_{s+t} - N_s)_{t \geq 0}$. In other words, for all $s > 0$ the process after time s and counted from the level N_s remains a Poisson process with intensity λ independent of its past $(N_\tau)_{\tau \in [0, s]}$.

2.2 Compound Poisson process on \mathbb{Z}^d

We can easily construct a rich class of processes which are the continuous time analogs of the random walks on \mathbb{Z}^d in Section 1.

Pick a probability vector (probability measure) $\mu = (\mu_k)_{k \in \mathbb{Z}^d} \in \mathcal{M}_1(\mathbb{Z}^d)$ such that $\mu_0 = 0$, i.e., $\mu_k \in [0, 1] \forall k \in \mathbb{Z}^d$ and $\sum_{k \in \mathbb{Z}^d} \mu_k = 1$. The compound Poisson process on \mathbb{Z}^d with jump distribution μ and rate $\lambda \in (0, \infty)$ is the stochastic process $(X_t)_{t \geq 0}$ which starts at the origin, sits there for an exponential holding time having mean value λ^{-1} , at which time it jumps by the amount $k \in \mathbb{Z}^d$ with probability μ_k , sits where it lands for another, independent holding time with mean λ^{-1} , jumps again and so on.

If $d = 1, \lambda = 1$, and $\mu_1 = 1$ we say $(X_t)_{t \geq 0}$ is the simple Poisson process, which, once restricted to the state space \mathbb{N}_0 , is the Poisson process from the previous section. The jump distribution allows only jumps by $+1$, i.e., only jumps to the right, because $\mu_k = 0$ for all $k \neq 0$.

Construction of the compound Poisson process:

Choose a family $(B_n)_{n \in \mathbb{N}}$ of mutually independent \mathbb{Z}^d -valued random variables with distribution $\mu \in \mathcal{M}_1(\mathbb{Z}^d)$ with $\mu_0 = 0$. This determines a random walk $(Y_n)_{n \in \mathbb{N}_0}$ (in discrete time) on \mathbb{Z}^d .

$$Y_0 = 0 \quad \text{and} \quad Y_n = \sum_{m=1}^n B_m, n \geq 1.$$

For any rate $\lambda \in (0, \infty)$, a family $(X_t)_{t \geq 0}$ of \mathbb{Z}^d -valued random variables is defined by

$$X_t := Y_{N(\lambda t)}, t \geq 0,$$

where $(N_t)_{t \geq 0}$ is a simple Poisson process which is independent of the random variables B_m (simple means intensity one). The following facts are easily seen from the construction.

$X_0 = 0$ and $[0, \infty) \ni t \mapsto X_t$ is a piecewise constant, right continuous \mathbb{Z}^d -valued path. The number of jumps during a time interval $(s, t]$ is precisely

$N(\lambda t) - N(\lambda s)$ and $B_n = Y_n - Y_{n-1}$ is the amount of the n -th jump. We let $J_0 = 0$ and $J_n, n \geq 1$, denote the time of the n -th jump. Then

$$N(\lambda t) = n \Leftrightarrow J_n \leq \lambda t < J_{n+1}$$

and $X_{J_n} - X_{J_{n-1}} = B_n$. If $(E_i)_{i \in \mathbb{N}}$ is the family of unit exponential holding times (i.e. $E_i \sim E(1)$) of the simple Poisson process $(N_t)_{t \geq 0}$, then the holding times of the process $(X_t)_{t \geq 0}$ are given via the jump times as

$$J_n - J_{n-1} = \frac{E_n}{\lambda}; \quad X(t) - X(t-) = 0 \text{ for } t \in (J_{n-1}, J_n).$$

We call $(X_t)_{t \geq 0}$ the **compound Poisson process** with jump distribution μ and rate λ . In the next lemma we shall show that a compound process moves along in homogeneous, mutually independent increments.

Lemma 2.8

$$\mathbb{P}(X(s+t) - X(s) = k | X(\tau), \tau \in [0, s]) = \mathbb{P}(X(t) = k), \quad k \in \mathbb{Z}^d. \quad (2.13)$$

Proof. Given $A \in \sigma(\{X(\tau) : \tau \in [0, s]\})$ it suffices to show that

$$\mathbb{P}(\{X(s+t) - X(s) = k\} \cap A) = \mathbb{P}(\{X(s+t) - X(s) = k\})\mathbb{P}(A).$$

W.l.o.g. we assume that, for some $m \in \mathbb{N}$, $N(\lambda s) = m$ on A . Then the event A is independent of $\sigma(\{Y_{m+n} - Y_m : n \geq 0\} \cup \{N(\lambda(s+t)) - N(\lambda s)\})$, and so

$$\begin{aligned} & \mathbb{P}(\{X(s+t) - X(s) = k\} \cap A) \\ &= \sum_{n=0}^{\infty} \mathbb{P}(\{X(s+t) - X(s) = k; N(\lambda(s+t)) - N(\lambda s) = n\} \cap A) \\ &= \sum_{n=0}^{\infty} \mathbb{P}(\{Y_{m+n} - Y_m = k; N(\lambda(s+t)) - N(\lambda s) = n\} \cap A) \\ &= \sum_{n=0}^{\infty} \mathbb{P}(Y_n = k; N(\lambda t) = n)\mathbb{P}(A) = \mathbb{P}(X(t) = k)\mathbb{P}(A). \end{aligned}$$

□

Finally, we shall compute the distribution of the compound Poisson process $(X_t)_{t \geq 0}$. Recall that the distribution of the sum of k independent, identically distributed random variables is the n -fold convolution of their distribution.

Definition 2.9 (Convolution) If $\mu, \nu \in \mathcal{M}_1(\mathbb{Z}^d)$ are two probability vectors, the convolution $\mu * \nu \in \mathcal{M}_1(\mathbb{Z}^d)$ of μ and ν is defined by

$$\mu * \nu(m) = \sum_{k \in \mathbb{Z}^d} \mu_k \nu_{m-k}, \quad m \in \mathbb{Z}^d.$$

The convolution of $\mu \in \mathcal{M}_1(\mathbb{Z}^d)$ with itself is defined as

$$\begin{aligned} (\mu^{(*0)})_k &= \delta_{0,k}, \\ (\mu^{(*n)})_k &= \sum_{j \in \mathbb{Z}^d} (\mu^{(*(n-1))})_{k-j} \mu_j, \quad n \geq 1. \end{aligned}$$

Clearly, we have

$$\mathbb{P}(Y_n = k) = \mu_k^{(*n)}.$$

Henceforth we obtain the following,

$$\mathbb{P}(X(t) = k) = \sum_{n=0}^{\infty} \mathbb{P}(Y_n = k, N(\lambda t) = n) = e^{-\lambda t} \sum_{n=0}^{\infty} \frac{(\lambda t)^n}{n!} (\mu^{(*n)})_k.$$

Now with Lemma 2.8 we compute for an event $A \in \sigma(N(\tau): \tau \in [0, s])$.

$$\begin{aligned} \mathbb{P}(\{X(s+t) = k\} \cap A) &= \sum_{j \in \mathbb{Z}^d} \mathbb{P}(\{X(s+t) = k\} \cap A \cap \{X(s) = j\}) \\ &= \sum_{j \in \mathbb{Z}^d} \mathbb{P}(\{X(s+t) - X(s) = k - j\} \cap A \cap \{X(s) = j\}) \\ &=: \sum_{j \in \mathbb{Z}^d} P_t(j, k) \mathbb{P}(A \cap \{X(s) = j\}) = \mathbb{E}(P_t(X(s), k) \mathbb{1}\{A\}), \end{aligned}$$

where

$$P_t(k, l) = e^{-\lambda t} \sum_{m=0}^{\infty} \frac{(\lambda t)^m}{m!} (\mu^{(*m)})_{k-l}, \quad l, k \in \mathbb{Z}^d.$$

We have thus proved that $(X_t)_{t \geq 0}$ is a continuous time Markov process with transition probability P_t in the sense that

$$\mathbb{P}(X(s+t) = k | X(\tau), \tau \in [0, s]) = P_t(X(s), k).$$

As a consequence of the last equation, we find that $(P_t)_{t \geq 0}$ is a semigroup. That is, it satisfies the *Chapman-Kolmogorov equation*

$$P_{s+t} = P_s P_t, \quad s, t \in [0, \infty). \quad (2.14)$$

This can be seen as follows,

$$\begin{aligned} P_{s+t}(0, k) &= \sum_{j \in \mathbb{Z}^d} \mathbb{P}(X(s+t) = k; X(s) = j) = \sum_{j \in \mathbb{Z}^d} P_t(j, k) P_s(0, j) \\ &= \sum_{j \in \mathbb{Z}^d} P_s(0, j) P_t(j, k) = (P_s P_t)_{0, k}, \end{aligned}$$

where we used that $P_t(k, l) = P_t(0, l - k)$.

2.3 Markov processes with bounded rates

There are two possible directions in which one can generalise the previous construction of the Poisson respectively the compound Poisson process:

- jump distribution depends on where the process is at the time of the jump.
- holding time depends on the particular state the process occupies.

Assumptions: I countable state space and $\Pi = (\pi(x, y))_{x, y \in I}$ a transition probability matrix such that $\pi(x, x) = 0$ for all $x \in I$.

$$\Lambda = \{\lambda(i) \equiv \lambda_i : i \in I\} \subset (0, \infty)$$

a family of bounded rates such that $\sup_{i \in I} \{\lambda_i\} < \infty$.

Proposition 2.10 *With the above assumptions, a continuous time Markov process on I with rates Λ and transition probability matrix Π is an I -valued family $(X_t)_{t \geq 0}$ of random variables having the properties that*

(a) $t \mapsto X(t)$ is piecewise constant and right continuous,

(b) If $J_0 = 0$ and, for $n \geq 1$, J_n is the time of the n -th jump, then

$$\mathbb{P}(J_n > J_{n-1} + t; X(J_n) = j | X(\tau), \tau \in [0, J_n]) = e^{-t\lambda(X(J_{n-1}))} \pi(X(J_{n-1}), j) \quad (2.15)$$

on $\{J_{n-1} < \infty\}$.

Proof. We have to show two things. First (see step 1 below) we have to show that Proposition 2.10 together with an initial distribution uniquely determines the distribution of the family $(X_t)_{t \geq 0}$. Secondly (see step 2 below), we have to show that the family $(X_t)_{t \geq 0}$ possesses the Markov property.

Step 1: The assumption on the rates ensures that $\mathbb{P}(J_n < \infty) = 1$ for all $n \in \mathbb{N}_0$, henceforth we assume that $J_n < \infty$ for all $n \in \mathbb{N}_0$. We now set $Y_n = X(J_n)$ and $E_n = \frac{J_n - J_{n-1}}{\lambda(Y_{n-1})}$ for $n \in \mathbb{N}$. Then (2.15) shows that

$$\mathbb{P}(E_n > t, Y_n = j | \{E_1, \dots, E_{n-1}\} \cup \{Y_0, \dots, Y_{n-1}\}) = e^{-t} \pi(Y_{n-1}, j).$$

Hence, $(Y_n)_{n \in \mathbb{N}_0}$ is a Markov chain with transition probability matrix Π and the same initial distribution as $(X_t)_{t \geq 0}$. Furthermore, $(E_n)_{n \in \mathbb{N}}$ is a family of mutually independent, unit exponential random variables, and $\sigma(\{Y_n : n \in \mathbb{N}_0\})$ is independent of $\sigma(\{E_n : n \in \mathbb{N}\})$. Thus, the joint distribution of $\{Y_n : n \in \mathbb{N}_0\}$ and $\{E_n : n \in \mathbb{N}\}$ is uniquely determined. We can recover the process $(X_t)_{t \geq 0}$ from the Markov chain $(Y_n)_{n \in \mathbb{N}_0}$ and the family $(E_n)_{n \in \mathbb{N}}$ in the following way. Given $(e_1, e_2, \dots) \in (0, \infty)^\mathbb{N}$ and $(j_0, j_1, \dots) \in I^\mathbb{N}$, define

$$\Phi^{(\Lambda, \Pi)}(t; (e_1, e_2, \dots), (j_0, j_1, \dots)) = j_n \quad \text{for } \xi_n \leq t < \xi_{n+1},$$

where we put $\xi_0 = 0$ and $\xi_n = \sum_{m=1}^n \lambda_{j_{m-1}} e_m$. Then

$$X(t) = \Phi^{(\Lambda, \Pi)}(t; (E_1, \dots), (Y_0, Y_1, \dots)) \quad \text{for } 0 \leq t \leq \sum_{m=1}^{\infty} \lambda_{j_{m-1}}^{-1} E_m.$$

Now, the distribution of $(X_t)_{t \geq 0}$ is uniquely determined once we check that $\sum_{m=1}^{\infty} \lambda^{-1}(j_{m-1}) E_m = \infty$ with probability one. At this stage our assumptions on the rates come into play. Namely, by the Strong Law of Large Numbers we know that $\sum_{m=1}^{\infty} E_m = \infty$ with probability one.

Step 2: We show that the family $(X_t)_{t \geq 0}$ possesses the Markov property:

$$\mathbb{P}(X(s+t) = j | X(\tau), \tau \in [0, s]) = P(t)_{X(s), j}, \quad (2.16)$$

where $P_t(i, j) := \mathbb{P}(X(t) = j | X(0) = i)$. We use the Markov chain $(Y_n)_{n \in \mathbb{N}_0}$ again. For that we consider the $\Phi^{(\Lambda, \Pi)}$ defined above. Recall from the definition that $\xi_{n+m} \leq t+s < \xi_{n+m+1}$ corresponds to the state j_{n+m} of the process at time t . If we are ahead of m time steps (for the Markov chain), that is $\tilde{\xi}_n = \sum_{l=1}^n \lambda(j_{m+l-1}) e_{m+l} - s + \xi_m = -s + \xi_{n+m}$, we observe that $\tilde{\xi}_n \leq t < \tilde{\xi}_{n+1}$ corresponds to the state j_{n+m} as well because of $-s + \xi_{n+m+1} \geq t \geq -s + \xi_{n+m}$. This leads us to the following observation for $\xi_m \leq t < \xi_{m+1}$,

$$\begin{aligned} & \Phi^{(\Lambda, \Pi)}(s+t; (e_1, \dots), (j_0, \dots)) \\ &= \Phi^{(\Lambda, \Pi)}(t; (e_{m+1} - \lambda_{j_m}(s - \xi_m), e_{m+2}, \dots), (j_m, \dots)). \end{aligned} \quad (2.17)$$

Pick an event $A \in \sigma(\{X(\tau) : \tau \in [0, s]\})$ and assume that $X(s) = j$ on A . To prove (2.16) it suffices to show that

$$\mathbb{P}(\{X(s+t) = j\} \cap A) = P_t(i, j) \mathbb{P}(A).$$

To see this, put $A_m = A \cap \{X(s) = m\} = \{E_{m+1} > \lambda(i)(s - J_m)\} \cap B_m$ where B_m is an event depending on $\{E_1, \dots, E_m\} \cup \{Y_0, \dots, Y_m\}$. Clearly, $B_m \subset \{J_m \leq s\}$. We get

$$\begin{aligned} \mathbb{P}(\{X(s+t) = j\} \cap A) &= \sum_{m=0}^{\infty} \mathbb{P}(\{X(s+t) = j\} \cap A_m) \\ &= \sum_{m=0}^{\infty} \mathbb{P}(\{X(s+t) = j; E_{m+1} > \lambda_i(s - J_m)\} \cap B_m). \end{aligned}$$

By the memoryless property, (2.15), and our observation (2.17) we get

$$\begin{aligned} &\sum_{m=0}^{\infty} \mathbb{P}(\{X(s+t) = j; E_{m+1} > \lambda_i(s - J_m)\} \cap B_m) \\ &= \mathbb{P}(\{\Phi^{(\Lambda, \Pi)}(t; (E_{m+1} - \lambda_i(s - J_m), E_{m+2}, \dots, E_{m+n}, \dots), \\ &\quad (i, Y_{m+1}, \dots, Y_{m+n}, \dots)) = j\} \cap \{E_{m+1} > \lambda_i(s - J_m)\} \cap B_m) \\ &= \mathbb{P}(X(t) = j | X(0) = i) \mathbb{E}(e^{-\lambda_i(s - J_m)}, B_m) = P_t(i, j) \mathbb{P}(A_m), \end{aligned}$$

from which we finally get the Markov property. \square

The Markov property immediately shows that the family $(P_t)_{t \geq 0}$ is a semi-group because of

$$\begin{aligned} P_{t+s}(i, j) &= \sum_{k \in I} \mathbb{P}(X(s+t) = j; X(s) = k | X(0) = i) \\ &= \sum_{k \in I} P_t(k, j) \mathbb{P}(X(s) = k) = \sum_{k \in I} P_t(k, j) P_s(i, k) = (P_s P_t)_{i, j}. \end{aligned}$$

2.4 The Q -matrix and Kolmogorov's backward equations

In this Subsection we learn how to construct a process $X = (X_t)_{t \geq 0}$ taking values in some countable state space I satisfying the Markov property in Definition 2.1. We will do this in several steps. First, we proceed like for Markov chains (discrete time, countable state space). In continuous time we do not have a unit length of time and hence no exact analogue of the transition function $P: I \times I \rightarrow [0, 1]$.

Notation 2.11 (Transition probability) *Let $X = (X_t)_{t \geq 0}$ be a Markov process on a countable state space I .*

(a) The **transition probability** $P_{s,t}(i, j)$ of the Markov process X is defined as

$$P_{s,t}(i, j) = \mathbb{P}(X_t = j | X_s = i) \quad \text{for } s \leq t; i, j \in I.$$

(b) The Markov process X is called **(time-) homogeneous** if

$$P_{s,t}(i, j) = P_{0,t-s}(i, j) \quad \text{for all } i, j \in I; t \geq s \geq 0.$$

We consider homogeneous Markov processes only in the following, hence we write P_t for $P_{0,t}$. We write P_t for the $|I| \times |I|$ -matrix. The family $P = (P_t)_{t \geq 0}$ is called **transition semigroup** of the Markov process. For continuous time processes it can happen that rows of the transition matrix P_t do not sum up to one. This motivates the following definition for families of matrices on the state space I .

Definition 2.12 ((Sub-) stochastic semigroup) A family $P = (P_t)_{t \geq 0}$ of matrices on the countable set I is called (Sub-) stochastic semigroup on I if the following conditions hold.

(a) $P_t(i, j) \geq 0$ for all $i, j \in I$.

(b) $\sum_{j \in I} P_t(i, j) = 1$ (respectively $\sum_{j \in I} P_t(i, j) \leq 1$).

(c) **Chapman-Kolmogorov equations**

$$P_{t+s}(i, j) = \sum_{k \in I} P_t(i, k) P_s(k, j), \quad t, s \geq 0.$$

We call the family $P = (P_t)_{t \geq 0}$ **standard** if in addition to (a)-(c)

$$\lim_{t \downarrow 0} P_t(i, j) = \delta_{i,j} \quad \text{for all } i, j \in I$$

holds.

As we have seen in the previous section, apart from its initial distribution, the distribution of a Markov process is completely determined by the semigroup $(P_t)_{t \geq 0}$. Thus, it is important to develop methods for calculating the transition probabilities $P_t(j, k)$, $j, k \in I$, directly from the data contained in the rates Λ and the transition probability matrix Π . The Chapman-Kolmogorov equations (semigroup property) leads one to suspect that P_t can be written as e^{tQ} for some Q . In fact, Q should be derived by differentiation of the semigroup at $t = 0$. To prove these speculations, we shall first show that

$$P_t(i, j) = \delta_{i,j}e^{-t\lambda_i} + \lambda_i \int_0^t e^{-s\lambda_i} (\Pi P_{t-s})_{i,j} ds. \quad (2.18)$$

To prove (2.18) note that conditional on $X_0 = i$ we have $J_1 \sim E(\lambda_i)$ and $X_{J_1} \sim (\pi(i, k) : k \in I)$. Condition on the first jump time $J_1 = s$ and on the event $X_{J_1} = k$ we get that

$$\mathbb{P}_i(X_t = j, t < J_1) = \mathbb{P}(X_t = j, t < J_1 | X(0) = i) = e^{-\lambda_i t} \delta_{i,j}$$

and

$$\mathbb{P}_i(J_1 \leq t, X_{J_1} = k, X_t = j) = \int_0^t \lambda_i e^{-\lambda_i s} \pi(i, k) P_{t-s}(k, j) ds,$$

for some state $k \in I, k \neq i$. Summing over all possible intermediate states $k \neq i$ for the latter probability we obtain

$$\begin{aligned} P_t(i, j) &= \mathbb{P}_i(X_t = j, t < J_1) + \sum_{k \in I \setminus \{i\}} \mathbb{P}_i(J_1 \leq t, X_{J_1} = k, X_t = j) \\ &= e^{-\lambda_i t} \delta_{i,j} + \sum_{k \in I \setminus \{i\}} \int_0^t \lambda_i e^{-\lambda_i s} \pi(i, k) P_{t-s}(k, j) ds. \end{aligned}$$

Interchange sum and integral by monotone convergence to get

$$\mathbb{P}(E_1 \leq t\lambda_i; X(t) = j | X(0) = i) = \lambda_i \int_0^t e^{-\lambda_i s} \sum_{k \in I} \pi_{i,k} P_{t-s}(k, j) ds.$$

Thus we have proved (2.18).

Make a change of variable $u = t - s$ in each of the the integrals, and multiply by $e^{\lambda_i t}$ to obtain

$$e^{\lambda_i t} P_t(i, j) = \delta_{i,j} + \int_0^t \sum_{k \in I \setminus \{i\}} \lambda_i e^{\lambda_i u} \pi(i, k) P_u(k, j) du. \quad (2.19)$$

This equation shows, firstly, that $P_t(i, j)$ is continuous in t for all $i, j \in I$. Secondly, the integrand is then a uniformly converging sum of continuous functions, hence continuous, and hence $P_t(i, j)$ is differentiable in t and satisfies

$$e^{\lambda_i t} (\lambda_i P_t(i, j) + \dot{P}_t(i, j)) = \sum_{k \in I \setminus \{i\}} \lambda_i e^{\lambda_i t} \pi(i, k) P_t(k, j).$$

We now put $\lambda_i =: -q_{i,j}$ and $\lambda_i \pi(i, k) =: q_{i,k}$ for $k \neq i$. That is define the matrix

$$Q = \Lambda(\Pi - \mathbb{1}),$$

where $\mathbf{\Lambda}$ is the diagonal matrix whose i th entry is λ_i . We therefore get

$$\frac{d}{dt}P_t(i, j) = -\lambda_i P_t(i, j) + \lambda_i (\Pi P_t)_{i, j}. \quad (2.20)$$

We can rewrite this equation in matrix notation as

$$\frac{d}{dt}P_t = Q P_t \quad \text{with } P_0 = \mathbf{1} \text{ and } Q = \mathbf{\Lambda}(\Pi - \mathbf{1}). \quad (2.21)$$

Equation (2.21) is called **Kolmogorov's backward equation**. The reason for the adjective 'backward' is that Kolmogorov's backward equation (KBE) describes the evolution of $t \mapsto P_t(i, j)$ in terms of its backward variable i (i.e., as a function of the rates at state i from which the process is jumping to j). One can derive in a similar but more elaborative way the corresponding **Kolmogorov's forward equation** (KFE),

$$\frac{d}{dt}P_t = P_t Q \quad \text{with } P_0 = \mathbf{1} \text{ when } Q = \mathbf{\Lambda}(\Pi - \mathbf{1}). \quad (2.22)$$

Our construction and derivations of KBE motivates the following definition.

Definition 2.13 A **Q -matrix** or **generator** on a countable state space I is a matrix $Q = (q_{i, j})_{i, j \in I}$ satisfying the following conditions:

- (a) $0 \leq -q_{i, i} < \infty$ for all $i \in I$.
- (b) $q_{i, j} \geq 0$ for all $i \neq j, i, j \in I$.
- (c) $\sum_{j \in I} q_{i, j} = 0$ for all $i \in I$.

The positive entries $q_{i, j}$ are called **transition rates** if $i \neq j$, and $q_i = -q_{i, i}$ is called the rate leaving state i . A Q -matrix is also called generator because it provides a continuous time parameter semigroup of stochastic matrices. In this way a Q -matrix or generator is the most convenient way to define a Markov process in particular as the non-diagonal entries are interpreted as transition rates. Unfortunately, there is some technical difficulty in defining this connection properly when the state space is infinite. However, if the state space is finite we get the following results. Before that recall the definition of an exponential of a finite dimensional matrix.

Theorem 2.14 Let I be a finite state space and $Q = (q_{i, j})_{i, j \in I}$ a generator or Q -matrix. Define $P_t := e^{tQ}$ for all $t \geq 0$. Then the following holds:

- (a) $P_{s+t} = P_s P_t$ for all $s, t \geq 0$.

(b) $(P_t)_{t \geq 0}$ is the unique solution to the **forward equation**

$$\frac{d}{dt}P_t = P_tQ \text{ and } P_0 = \mathbb{1}.$$

(c) $(P_t)_{t \geq 0}$ is the unique solution to the **backward equation**

$$\frac{d}{dt}P_t = QP_t \text{ and } P_0 = \mathbb{1}.$$

(d) For $k \in \mathbb{N}_0$

$$\left. \frac{d^k}{dt^k} P_t \right|_{t=0} = Q^k.$$

Proof. We only give a sketch of the proof as it basically amounts to well-known basic matrix algebra. For all $s, t \in \mathbb{R}_+$, the matrices sQ and tQ commute, hence $e^{sQ}e^{tQ} = e^{(s+t)Q}$, proving the semigroup property. The matrix-valued power series

$$P_t = \sum_{k=0}^{\infty} \frac{(tQ)^k}{k!}$$

has a radius of convergence which is infinite. Hence, one can justify a term by term differentiation (we skip that) to get

$$P_t' = \sum_{k=1}^{\infty} \frac{t^{k-1}Q^k}{(k-1)!} = P_tQ = QP_t.$$

We are left to show that the solution to both the forward and backward equation are unique. For that let $(M(t))_{t \geq 0}$ satisfy the forward equations (case for backward equations follows similar).

$$\begin{aligned} \frac{d}{dt} \left(M(t)e^{-tQ} \right) &= \left(\frac{d}{dt} M(t) \right) e^{-tQ} + M(t) \left(\frac{d}{dt} e^{-tQ} \right) = M(t)Qe^{-tQ} \\ &\quad + M(t)(-Q)e^{-tQ} = 0, \end{aligned}$$

henceforth $M(t)e^{-tQ}$ is constant and so $M(t) = P_t$. □

Proposition 2.15 *Let $Q = (q_{i,j})_{i,j \in I}$ be a matrix on a finite set I . Then the following equivalence holds.*

$$Q \text{ is a } Q\text{-matrix} \Leftrightarrow P_t = e^{tQ} \text{ is a stochastic matrix for all } t \geq 0.$$

Proof. Let Q be a Q -matrix. As $t \downarrow 0$ we have $P_t = \mathbb{1} + tQ + O(t^2)$. Hence, for sufficiently small times t the positivity of $P_t(i, j), i \neq j$, follows from the positivity of $q_{i,j} \geq 0$. For larger times t we can easily use that $P_t = P_{\frac{t}{n}}^n$ for any $n \in \mathbb{N}$, and henceforth

$$q_{i,j} \geq 0, i \neq j \Leftrightarrow P_t(i, j) \geq 0, i \neq j \text{ for all } t \geq 0.$$

Furthermore, if Q has zero row sums then so does $Q^n = (q_{i,j}^{(n)})_{i,j \in I}$ for every $n \in \mathbb{N}$,

$$\sum_{k \in I} q_{i,j}^{(n)} = \sum_{k \in I} \sum_{j \in I} q_{i,j}^{(n-1)} q_{j,k} = \sum_{j \in I} q_{i,j}^{(n-1)} \sum_{k \in I} q_{j,k} = 0.$$

Thus

$$\sum_{j \in I} P_t(i, j) = 1 + \sum_{n=1}^{\infty} \frac{t^n}{n!} \sum_{j \in I} q_{i,j}^{(n)} = 1,$$

and henceforth P_t is a stochastic matrix for all $t \geq 0$. Conversely, assuming that $\sum_{j \in I} P_t(i, j) = 1$ for all $t \geq 0$ gives that

$$\sum_{j \in I} q_{i,j} = \left. \frac{d}{dt} \right|_{t=0} \sum_{j \in I} P_t(i, j) = 0.$$

□

Example 2.16 Consider $I = \{1, \dots, N\}$, $\lambda > 0$, and the following Q -matrix $Q = (q_{i,j})_{i,j \in I}$ with $q_{i,i+1} = \lambda$ and $q_{i,i} = -\lambda$ for $i \in \{1, \dots, N-1\}$ and all other entries being zero. That is, $q_{N,i} = 0$ for all $i \in I$.

$$Q = \begin{pmatrix} -\lambda & \lambda & 0 & 0 & \cdots & \cdots & 0 \\ 0 & -\lambda & \lambda & 0 & \cdots & \cdots & 0 \\ 0 & 0 & -\lambda & \lambda & \cdots & \cdots & 0 \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & 0 \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & 0 \\ \cdots & \cdots & \cdots & \cdots & \cdots & -\lambda & \lambda \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}.$$

Clearly, Q is an upper-triangular matrix and so any power Q^k is upper triangular as well. Hence, so is e^{tQ} . There are no jumps $j \rightarrow j-1$. That is, $P_t(i, j) = 0$ for $i > j$ and $t \geq 0$. The forward equation $P'_t = P_t Q$ reads as

$$\begin{aligned} P'_t(i, i) &= -\lambda P_t(i, i); P_0(i, i) = 1, i \in \{1, \dots, N-1\} \\ P'_t(i, j) &= -\lambda P_t(i, j) + \lambda P_t(i, j-1); P_0(i, j) = 0, 1 \leq i < j < N, \\ P'_t(i, N) &= \lambda P_t(i, N-1); P_0(i, N) = 0, 1 \leq i < N, \\ P'_t(N, N) &= 0; P_0(N, N) = 1. \end{aligned}$$

Because of $P_t(i, j) = 0$ for all $i > j$, the equations admit the following recursive solution.

$$\begin{aligned}\dot{P}_t(i, i) &= -\lambda P_t(i, i): P_t(i, i) = e^{-\lambda t}, 1 \leq i < N; \\ \dot{P}_t(i, i+1) &= -\lambda P_t(i, i+1) + \lambda e^{-\lambda t}: P_t(i, i+1) = \lambda t e^{-\lambda t}, 1 \leq i < N, \\ \dot{P}_t(i, i+2) &= -\lambda P_t(i, i+2) + \lambda^2 t e^{-\lambda t}: P_t(i, i+2) = \frac{(\lambda t)^2}{2} e^{-\lambda t}, 1 \leq i < N-1;\end{aligned}$$

and so on. In general,

$$P_t(i, j) = \left(\frac{(\lambda t)^{j-1}}{(j-1)!} \right) e^{-\lambda t}, 1 \leq i \leq j < N-1,$$

and

$$P_t(i, N) = 1 - \sum_{\ell=0}^{N-i-1} \frac{(\lambda t)^\ell}{\ell!} e^{-\lambda t}, 1 \leq i < N,$$

and finally $P_t(N, N) = 1$. In matrix form

$$P_t = e^{tQ} = \begin{pmatrix} e^{-\lambda t} & (\lambda t)e^{-\lambda t} & (\lambda t)^2 e^{-\lambda t}/2! & \cdots & \sum_{\ell \geq N-1} (\lambda t)^\ell e^{-\lambda t}/\ell! \\ 0 & e^{-\lambda t} & (\lambda t)e^{-\lambda t} & \cdots & \sum_{\ell \geq N-2} (\lambda t)^\ell e^{-\lambda t}/\ell! \\ \cdots & \ddots & \cdots & \cdots & \cdots \\ \cdots & \ddots & \cdots & \cdots & \cdots \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}.$$

We now see that, as $t \rightarrow \infty$, $P_t(i, j) \rightarrow 0$ for all $1 \leq i \leq j < N$ and $P_t(i, N) \rightarrow 1$ for all $1 \leq i < N$. That is,

$$\lim_{t \rightarrow \infty} P_t(i, j) = \delta_{i, N}, \quad \text{for all } j \in I.$$

◇

Example 2.17 (Modification of example 2.16) Consider the following modification of the previous example 2.16, that is, consider now the Q -matrix

$$Q = \begin{pmatrix} -\lambda & \lambda & 0 & 0 & \cdots & \cdots & 0 \\ 0 & -\lambda & \lambda & 0 & \cdots & \cdots & 0 \\ 0 & 0 & -\lambda & \lambda & \cdots & \cdots & 0 \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & 0 \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & 0 \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & 0 \\ \lambda & 0 & 0 & 0 & 0 & 0 & -\lambda \end{pmatrix}.$$

Here, the matrix $P_t = e^{tQ}$ will exhibit a cyclic structure; for all i, j, ℓ we have

$$P_t(i, j) = P_t(i + \ell, j + \ell) \quad \text{addition mod } N.$$

Henceforth,

$$P_t(i, j) = P_t(1, j - i + 1) = e^{-\lambda t} \sum_{\ell \geq 0} \frac{(\lambda t)^{j-i+\ell N}}{(j-i+\ell N)!}, \quad 1 \leq i \leq j \leq N,$$

and

$$P_t(i, j) = P_t(1, N + j - i + 1), \quad 1 \leq i \leq j \leq N.$$

As $t \rightarrow \infty$, $P_t(i, j) \rightarrow \frac{1}{N}$, giving the uniform distribution. This can be seen easily by writing $e^{\lambda t}$ as a sum of N power series; e.g., for $N = 2$,

$$e^{\lambda t} = \sum_{\ell=0}^{\infty} \frac{(\lambda t)^{2\ell}}{(2\ell)!} + \sum_{\ell=0}^{\infty} \frac{(\lambda t)^{2\ell+1}}{(2\ell+1)!}.$$

◇

Example 2.18 A virus exists in $N+1$ strains $\in I = \{0, 1, \dots, N\}$. It keeps its strain for a random time which is exponential distributed with parameter $\lambda > 0$, then mutates to one of the remaining strains with equal probability. Find the probability that the strain at time t is the same as the initial strain., i.e.,

$$\mathbb{P}(\text{at time } t \text{ same strain as at time } 0).$$

Due to symmetry, $q_i = -q_{i,i} = \lambda$ and $q_{i,j} = \frac{\lambda}{N}$ for $1 \leq i, j \leq N+1, i \neq j$. We shall compute $P_t(i, i) = (e^{tQ})_{i,i}$. Clearly, $P_t(i, i) = P_t(1, 1)$ for all $i \in \{0, 1, \dots, N\}, t \geq 0$, again by symmetry. As jumping to one of the N strains is leaving the current strain with rate λ is the same random mechanism as leaving the current strain to only one possible strain with rate λ/N . Therefore we consider the reduced state space $\tilde{I} = \{0, 1\}$ (success respectively failure for the event in question). The corresponding reduced (2×2) - jump matrix, over states 0 and 1, is

$$\tilde{Q} = \begin{pmatrix} -\lambda & \lambda \\ \lambda/N & -\lambda/N \end{pmatrix}.$$

The matrix \tilde{Q} has eigenvalues 0 and $\mu = -\lambda(N+1)/N$ with its row eigenvectors being $(1, 1)$ and $(N, -1)$. Hence, we make the following ansatz

$$P_t(1, 1) = A + Be^{-\frac{\lambda(N+1)}{N}t}.$$

We seek solutions of the form $A + Be^{\mu t}$, and we obtain $A = 1/(N + 1)$ and $B = n/(N + 1)$ and

$$P_t(1, 1) = \frac{1}{N + 1} + \left(\frac{N}{N + 1}\right)e^{-\frac{\lambda(N+1)}{N}t} = P_t(i, i).$$

By symmetry,

$$P_t(i, j) = \frac{1}{N + 1} - \left(\frac{1}{N + 1}\right)e^{-\frac{\lambda(N+1)}{N}t}, \quad i \neq j,$$

and we conclude

$$P_t(i, j) \rightarrow \frac{1}{N + 1} \quad \text{as } t \rightarrow \infty.$$

◇

Recall the definition of the Poisson process and in particular the characterisation in Theorem 2.5. A right continuous process $(N_t)_{t \geq 0}$ with values in \mathbb{N}_0 is a Poisson process of rate $\lambda \in (0, \infty)$ if its holding times E_1, E_2, \dots are independent exponential random variables of parameter λ , its increments $N_{t_i} - N_{t_{i-1}}$ are independent and Poisson distributed with parameter $\lambda(t_i - t_{i-1})$, and its jump chain is given by $Y_n = X_{J_n}, n \in \mathbb{N}_0$. To obtain the corresponding Q -matrix we recall that the off-diagonal entries are the jump rates. Jump rates are jumps/per unit time. We 'wait' an expected time $\frac{1}{\lambda}$, then we jump by one, hence the jump rate is $\frac{1}{\frac{1}{\lambda}} = \lambda$ and the Q -matrix

$$Q = \begin{pmatrix} -\lambda & \lambda & 0 & 0 & 0 & \dots & \dots \\ 0 & -\lambda & \lambda & 0 & 0 & \dots & \dots \\ 0 & 0 & -\lambda & \lambda & 0 & \dots & \dots \\ 0 & \dots & \dots & -\lambda & \lambda & \dots & \dots \\ \dots & \dots & \dots & \dots & -\lambda & \lambda & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots \end{pmatrix}.$$

The following Theorem gives a complete characterisation of the Poisson process.

Theorem 2.19 (Poisson process) *The Poisson process for parameter (intensity) $\lambda \in (0, \infty)$ can be characterised in three equivalent ways: a process $(N_t)_{t \geq 0}$ (right continuous) taking values in \mathbb{N}_0 with $N_0 = 0$ and:*

(a) *and for all $0 < t_1 < t_2 < \dots < t_n, n \in \mathbb{N}$, and $i_1, \dots, i_n \in \mathbb{N}_0$*

$$\mathbb{P}(N_{t_1} = i_1, \dots, N_{t_n} = i_n) = P_{t_1}(0, i_1)P_{t_2-t_1}(i_1, i_2) \cdots P_{t_n-t_{n-1}}(i_{n-1}, i_n),$$

where the matrix P_t is defined as $P_t = e^{tQ}$ (to be justified as the state space is not finite).

(b) with independent increments $N(t_1) - N(t_0), \dots, N(t_n) - N(t_{n-1})$, for all $0 = t_0 < t_1 < \dots < t_n$, and the infinitesimal probabilities for all $t \geq 0$ as $h \downarrow 0$

$$\mathbb{P}(N(t+h) - N(t) = 0) = 1 - \lambda h + o(h)$$

$$\mathbb{P}(N(t+h) - N(t) = 1) = \lambda h + o(h)$$

$$\mathbb{P}(N(t+h) - N(t) \geq 2) = o(h),$$

where the terms $o(h)$ do not depend on t .

(c) spending a random time $E_k \sim E(\lambda)$ in each state $k \in \mathbb{N}_0$ independently, and then jumping to $k+1$.

Proof. We need to justify the operation $P_t = e^{tQ}$ as the state space \mathbb{N}_0 is not finite. We are using the fact that Q is upper triangular and so is Q^k for any $k \in \mathbb{N}$ and therefore P_t is upper triangular. In order to find the entries $P_t(i, i+\ell)$ for any $\ell \in \mathbb{N}_0$ we use the forward or backward equation both with initial condition $P_0 = \mathbf{1}$. This gives $\frac{d}{dt}P_t(i, i) = -\lambda P_t(i, i)$ and $P_0(i, i) = 1$ and thus $P_t(i, i) = e^{-\lambda t}$ for all $i \in \mathbb{N}_0$ and all $t \geq 0$. Put $\ell = 1$, that is consider one step above the main diagonal. Then

$$\text{(forward)} \quad \frac{d}{dt}P_t(i, i+1) = -\lambda P_t(i, i+1) + \lambda P_t(i, i),$$

$$\text{(backward)} \quad \frac{d}{dt}P_t(i, i+1) = -\lambda P_t(i, i+1) + \lambda P_t(i+1, i+1)$$

gives $P_t(i, i+1) = \lambda t e^{-\lambda t}$ for all $i \in \mathbb{N}_0$ and $t \geq 0$. The general case (i.e. $\ell \in \mathbb{N}_0$) follows in the same way and henceforth

$$P_t(i, i+\ell) = \frac{(\lambda t)^\ell}{\ell!} e^{-\lambda t}, \quad i \in \mathbb{N}_0, t \geq 0.$$

(a) \Rightarrow (b): We get for $\ell = 0, 1$

$$\mathbb{P}(N(t+h) - N(t) = \ell) = \frac{(\lambda h)^\ell}{\ell!} e^{-\lambda h} = \begin{cases} e^{-\lambda h} = 1 - \lambda h + o(h) & \text{if } \ell = 0 \\ \lambda h e^{-\lambda h} = \lambda h + o(h) & \text{if } \ell = 1, \end{cases}$$

and $\mathbb{P}(N(t+h) - N(t) \geq 2) = 1 - \mathbb{P}(N(t+h) - N(t) = 0 \text{ or } 1) = 1 - (1 - \lambda h + \lambda h + o(h)) = o(h)$.

(b) \Rightarrow (c): This step is more involved. We need to get around the infinitesimal probabilities, that is small times h . This is done as follows. We first check

that no double jumps exists, i.e.

$$\begin{aligned}
& \mathbb{P}(\text{no jumps of size } \geq 2 \text{ in } (0, t]) \\
&= \mathbb{P}\left(\text{no such jumps in } \left(\frac{k-1}{m}t, \frac{k}{m}t\right] \forall k = 1, \dots, m\right) \\
&= \prod_{k=1}^m \mathbb{P}\left(\text{no such jumps in } \left(\frac{k-1}{m}t, \frac{k}{m}t\right]\right) \\
&\geq \prod_{k=1}^m \mathbb{P}\left(\text{no jump at all or single jump of size one in } \left(\frac{k-1}{m}t, \frac{k}{m}t\right]\right) \\
&= \left(1 - \lambda \frac{t}{m} + \lambda \frac{t}{m} + o\left(\frac{t}{m}\right)\right)^m = \left(1 + o\left(\frac{t}{m}\right)\right)^m \rightarrow 1 \text{ as } m \rightarrow \infty.
\end{aligned}$$

This is true for all $t \geq 0$ and henceforth $\mathbb{P}(\text{no jumps of size } \geq 2 \text{ ever}) = 1$. Pick $t, s > 0$ and obtain

$$\begin{aligned}
& \mathbb{P}(N(t+s) - N(s) = 0) = \mathbb{P}(\text{no jumps in } (s, s+t]) \\
&= \mathbb{P}\left(\text{no jumps in } \left(s + \frac{k-1}{m}t, s + \frac{k}{m}t\right] \forall k = 1, \dots, m\right) \\
&= \prod_{k=1}^m \mathbb{P}\left(\text{no jumps in } \left(s + \frac{k-1}{m}t, s + \frac{k}{m}t\right]\right) \\
&= \left(1 - \lambda \frac{t}{m} + o\left(\frac{t}{m}\right)\right)^m \rightarrow e^{-\lambda t} \text{ as } m \rightarrow \infty.
\end{aligned}$$

With some slight abuse we introduce the holding times with index starting at zero (before we started here with one):

$$\begin{aligned}
E_0 &= \sup\{t \geq 0 : N(t) = 0\}, \\
E_1 &= \sup\{t \geq 0 : N(E_0 + t) = 1\}, \dots, E_n = \begin{cases} J_n - J_{n-1} & \text{if } J_{n-1} < \infty \\ \infty & \text{otherwise.} \end{cases}
\end{aligned}$$

Note that the jump time J_k is also the hitting time of the state $k \in \mathbb{N}_0$. We need to show that these holding times are independent and exponential distributed with parameter λ . In order to do so we compute the probability for some given time intervals and show that it is given as a product of the corresponding densities. Pick positive t_1, \dots, t_n and positive h_1, \dots, h_n such that $0 < t_1 < t_1 + h_1 < \dots < t_{n-1} + h_{n-1} < t_n$. We get

$$\begin{aligned}
& \mathbb{P}(t_1 < J_1 \leq t_1 + h_1, \dots, t_n < J_n \leq t_n + h_n) \\
&= \mathbb{P}(N(t_1) = 0; N(t_1 + h_1) - N(t_1) = 1; N(t_2) - N(t_1 + h_1) = 0; \dots; \\
& \quad N(t_n) - N(t_{n-1} + h_{n-1}) = 0; N(t_n + h_n) - N(t_n) = 1) \\
&= \mathbb{P}(N(t_1) = 0) \mathbb{P}(N(t_1 + h_1) - N(t_1) = 1) \dots \\
&= e^{-\lambda t_1} (\lambda h_1 + o(h_1)) e^{-\lambda(t_2 - t_1 - h_1)} \times \dots \times e^{-\lambda(t_n - t_{n-1} - h_{n-1})} (\lambda h_n + o(h_n)),
\end{aligned}$$

and dividing by the product $h_1 \times \cdots \times h_n$ and taking the limit $h_i \downarrow 0$, $i = 1, \dots, n$, gives that the left hand side is the joint probability density function of the n jump times and the right hand side is the product $(e^{-\lambda t_1} \lambda)(e^{-\lambda(t_2-t_1)} \lambda) \cdots (e^{-\lambda(t_n-t_{n-1})} \lambda)$. Thus the joint density function reads as

$$\begin{aligned} f_{J_1, \dots, J_n}(t_1, \dots, t_n) &= \prod_{k=1}^n (\lambda e^{-\lambda(t_k - t_{k-1})}) \mathbb{1}\{0 < t_1 < \cdots < t_n\} \\ &= \lambda^n e^{-\lambda t_n} \mathbb{1}\{0 < t_1 < \cdots < t_n\}. \end{aligned}$$

Recall $E_0 = J_0, E_1 = J_1 - J_0, \dots, E_n = J_n - J_{n-1}$, hence we make a change of variables (for the n times) $e_0 = t_1, e_1 = t_2 - t_1, e_2 = t_3 - t_2, \dots, e_{n-1} = t_n - t_{n-1}$. The determinant of the Jacobi matrix for this transformation is one and therefore

$$\begin{aligned} f_{E_0, \dots, E_{n-1}}(e_0, e_1, \dots, e_{n-1}) &= f_{J_1, \dots, J_n}(e_0, e_0 + e_1, \dots, e_0 + \cdots + e_{n-1}) \\ &= \prod_{k=0}^{n-1} (\lambda e^{-\lambda e_k} \mathbb{1}\{e_k > 0\}), \end{aligned}$$

and henceforth E_0, E_1, \dots are independent and exponential distributed with parameter λ .

(c) \Rightarrow (a): This is already proved in Theorem 2.5. \square

We finish our discussion of the Poisson process with a final result concerning the uniform distribution of a single jump in some time interval.

Proposition 2.20 *Let $(N_t)_{t \geq 0}$ be a Poisson process. Then, conditional on $(N_t)_{t \geq 0}$ having exactly one jump in the interval $[s, s+t]$, the time at which that jump occurs is uniformly distributed in $[s, s+t]$.*

Proof. Pick $0 \leq u \leq t$.

$$\begin{aligned} \mathbb{P}(J_1 \leq u | N_t = 1) &= \mathbb{P}(J_1 \leq u \text{ and } N_t = 1) / \mathbb{P}(N_t = 1) \\ &= \mathbb{P}(N_u = 1 \text{ and } N_t - N_u = 0) / \mathbb{P}(N_t = 1) \\ &= \lambda u e^{-\lambda u} e^{-\lambda(t-u)} / (\lambda t e^{-\lambda t}) = \frac{u}{t}. \end{aligned}$$

\square

2.5 Jump chain and holding times

We introduce the jump chain of a Markov process, the holding times given a Q -matrix and the explosion time. Given a Markov process $X = (X_t)_{t \geq 0}$ on a countable state space I one of the following cases occur:

(A) The process has infinitely many jumps but only finitely many in any interval $[0, t]$, $t \geq 0$.

(B) The process has only finitely many jumps, that is, there exists a $k \in \mathbb{N}$ such that the k -th waiting/holding time $E_k = \infty$.

(C) The process has infinitely many jumps in a finite time interval. After the explosion time ζ (to be defined later, see below) has passed the process starts up again.

J_0, J_1, \dots are called the **jump times** and $(E_k)_{k \in \mathbb{N}}$ are called the **holding/waiting times** of the Markov process $X = (X_t)_{t \geq 0}$.

$$J_0 := 0, J_{n+1} = \inf\{t \geq J_n : X_t \neq X_{J_n}\}, n \in \mathbb{N}_0,$$

where we put $\inf\{\emptyset\} = \infty$, and for $k \in \mathbb{N}$

$$E_k = \begin{cases} J_k - J_{k-1} & \text{if } J_{k-1} < \infty, \\ \infty & \text{otherwise.} \end{cases}$$

The (first) **explosion time** ζ is defined by

$$\zeta = \sup_{n \in \mathbb{N}_0} \{J_n\} = \sum_{k=1}^{\infty} E_k.$$

The discrete-time process $(Y_n)_{n \in \mathbb{N}_0}$ given by $Y_n = X_{J_n}$ is called the **jump process** or the **jump chain** of the Markov process.

Having a Q -matrix one can compute the transition matrix for the corresponding jump chain of the process.

Notation 2.21 (Jump matrix Π) *The jump matrix $\Pi = (\pi_{i,j})_{i,j \in I}$ of a Q -matrix $Q = (q_{i,j})_{i,j \in I}$ is given by*

$$\pi_{i,j} = \begin{cases} \frac{q_{i,j}}{q_i} & \text{if } q_i \neq 0 \\ 0 & \text{if } q_i = 0, \end{cases} \quad \text{if } i \neq j;$$

and

$$\pi_{i,i} = \begin{cases} 0 & \text{if } q_i \neq 0 \\ 1 & \text{if } q_i = 0. \end{cases}$$

Proposition 2.22 *Let $(E_k)_{k \in \mathbb{N}}$ be a sequence of independent random variables with $E_k \sim E(\lambda_k)$ and $0 < \lambda_k < \infty$ for all $k \in \mathbb{N}$.*

(a) *If $\sum_{k=1}^{\infty} \frac{1}{\lambda_k} < \infty$, then $\mathbb{P}(\zeta = \sum_{k=1}^{\infty} E_k < \infty) = 1$.*

(b) If $\sum_{k=1}^{\infty} \frac{1}{\lambda_k} = \infty$, then $\mathbb{P}(\zeta = \sum_{k=1}^{\infty} E_k = \infty) = 1$.

Proof. The proof follows easily using the Monotone Convergence Theorem and independence. \square

In a continuous time process it can happen that there are infinitely many jumps in a finite time interval. This phenomenon is called **explosion**. If explosion occurs one cannot bookmark properly the states the process visits, somehow the process is stuck. A convenient mathematical way is to add a special state, called cemetery, written as ∂ , to the given state space I , i.e. to consider a new state space $I \cup \{\partial\}$. Whenever a Markov process is satisfying that $X_t = \partial$ if $t \geq \zeta$ we call this process (realisation) **minimal**.

When explosion occurs the transition probability forms now a sub-stochastic semigroup, see Definition 2.12. Recall that if $X = (X_t)_{t \geq 0}$ is a Markov process with initial distribution ν , where ν is a probability measure on the state space I , and semigroup $(P_t)_{t \geq 0}$, the probability for cylinder events (finite dimensional distribution) at times $0 = t_0 < t_1 < \dots < t_n$ and states $i_0, \dots, i_n \in I$ is given as

$$\mathbb{P}(X(t_0) = i_0, \dots, X(t_n) = i_n) = \nu(i_0)P_{t_1-t_0}(i_0, i_1) \cdots P_{t_n-t_{n-1}}(i_{n-1}, i_n).$$

Definition 2.23 (Markov process with explosion) Let $P = (P_t)_{t \geq 0}$ be a sub-stochastic semigroup on a countable state space I . Further let $\{\partial\} \notin I$ and let ν be a probability measure on the augmented state space $I \cup \{\partial\}$. A $I \cup \{\partial\}$ -valued family $X = (X_t)_{t \geq 0}$ is a Markov process with initial distribution ν and semigroup $(P_t)_{t \geq 0}$ if for $n \in \mathbb{N}$ and any $0 \leq t_1 < t_2 < \dots < t_n < t$ and states $i_1, \dots, i_n \in I$ the following holds:

(a) $\mathbb{P}(X(t) = i | X(t_1) = i_1, \dots, X(t_n) = i_n) = P_{t-t_n}(i_n | i)$ if the left hand side is defined.

(b) $\mathbb{P}(X_0 = i) = \nu(i)$ for all $i \in I \cup \{\partial\}$.

(c) $\mathbb{P}(X(t) = \partial | X(t_1) = i_1, \dots, X(t_{n-1}) = i_{n-1}, X(t_n) = \partial) = 1$.

Recall that q_i is the rate of leaving the state $i \in I$ and that $q_{i,j}$ is the rate of going from state i to state j . We get a criterion not having explosion of a process in terms of the q_i 's.

Proposition 2.24 (Explosion) Let $(X_t)_{t \geq 0}$ be a (λ, Q) -Markov process on some countable state space I . Then the process does not explode if any one of the following conditions holds:

(a) I is finite.

(b) $\sup_{i \in I} \{q_i\} < \infty$.

(c) $X_0 = i$ and the state i is recurrent for the jump chain (a state i is recurrent if $\mathbb{P}_i(Y_n = i \text{ for infinitely many } n) = 1$).

Proof. Put $T_n := q(Y_{n-1})E_n$, then $T_n \sim E(1)$ and $(T_n)_{n \in \mathbb{N}}$ is independent of $(Y_n)_{n \in \mathbb{N}_0}$. (a),(b): We have $q := \sup_{i \in I} \{q_i\} < \infty$, and hence

$$q\zeta = q \sum_{k=1}^{\infty} E_k \geq \sum_{n=1}^{\infty} T_n = \infty \quad \text{with probability 1.}$$

(c) If $(Y_n)_{n \in \mathbb{N}_0}$ visits the state i infinitely often at times N_1, N_2, \dots , then

$$q_i \zeta \geq \sum_{n=1}^{\infty} T_{N_n+1} = \infty \quad \text{with probability 1.}$$

□

We say a Q -matrix Q is **explosive** if $\mathbb{P}_i(\zeta < \infty) > 0$ for some state $i \in I$.

2.6 Summary - Markov processes

Let I be a countable state space. The basic data for a Markov process on I is given by the Q -matrix. A right continuous process $X = (X_t)_{t \geq 0}$ is a Markov process with initial distribution λ (probability measure on I) and Q -matrix (generator) if its jump chain $(Y_n)_{n \in \mathbb{N}_0}$ is a discrete time Markov chain with initial distribution λ and transition matrix Π (given in Notation (2.21)) and if for all $n \in \mathbb{N}$, conditional on Y_0, \dots, Y_{n-1} , its holding (waiting) times are independent exponential random variables of parameters $q(Y_0), \dots, q(Y_{n-1})$ respectively. How can we construct a Markov process given a discrete time Markov chain? Pick a Q -matrix respectively a jump matrix Π and consider the discrete time Markov chain $(Y_n)_{n \in \mathbb{N}_0}$ having initial distribution λ and transition matrix Π . Furthermore, let T_1, T_2, \dots be a family of independent random variables exponential distributed with parameter 1, independent of $(Y_n)_{n \in \mathbb{N}_0}$. Put

$$E_n = \frac{T_n}{q(Y_{n-1})} \text{ and } J_n = E_1 + \dots + E_n, n \in \mathbb{N},$$

$$X_t := \begin{cases} Y_n & \text{if } J_n \leq t < J_{n+1} \text{ for some } n, \\ \partial & \text{otherwise.} \end{cases}$$

Then $(X_t)_{t \geq 0}$ has the required properties of a Markov process.

If the state space is not finite we have the following characterisation of the semigroup of transition probabilities.

Proposition 2.25 (Backward/forward equation) *Let Q be a Q -matrix on a countable state space I .*

(a) *Then the backward equation*

$$P'_t = QP_t, \quad P_0 = \mathbb{1},$$

has a minimal non-negative solution $(P_t)_{t \geq 0}$. That is, for any other solution $(H_t)_{t \geq 0}$ of the backward equation we have $H_t \geq P_t$. The minimal solution forms a matrix semigroup $P_s P_t = P_{s+t}$ for all $s, t \geq 0$.

(b) *The minimal non-negative solution of the backward equation is also the minimal non-negative solution of the forward equation*

$$P'_t = P_t Q, \quad P_0 = \mathbb{1}.$$

Proof. The proof is rather long, and we skip it here. □

The following Theorem is our key result for Markov processes with infinite countable state space I .

Theorem 2.26 (Markov process, final characterisation) *Let $(X_t)_{t \geq 0}$ be a minimal right continuous process having values in a countable state space I . Furthermore, let Q be a Q -matrix on I with jump matrix Π and semigroup $(P_t)_{t \geq 0}$ being the minimal solution of KBE and KFE in Proposition 2.25. Then the following conditions are equivalent:*

(a) *Conditional on $X_0 = i$, the jump chain $(Y_n)_{n \in \mathbb{N}_0}$ of $(X_t)_{t \geq 0}$ is a discrete time Markov chain with initial distribution δ_i and transition matrix Π and for each $n \geq 1$, conditional on Y_0, \dots, Y_{n-1} , the holding (waiting) times E_1, \dots, E_n are independent exponential random variables of parameters $q(Y_0), \dots, q(Y_{n-1})$ respectively;*

(b) *for all $n \in \mathbb{N}_0$, all times $0 \leq t_0 \leq t_1 \leq \dots \leq t_{n+1}$ and all states $i_0, \dots, i_{n+1} \in I$*

$$\mathbb{P}(X_{t_n} = i_{n+1} | X_{t_0} = i_0, \dots, X_{t_n} = i_n) = P_{t_{n+1} - t_n}(i_n, i_{n+1}).$$

*If $(X_t)_{t \geq 0}$ satisfies any of these conditions then it is called a **Markov process** with **generator matrix** Q . If λ is the distribution of X_0 it is called the initial distribution of the Markov process.*

3 Examples, hitting times, and long-time behaviour

We study the birth-and-death process, introduce hitting times and probabilities, and discuss recurrence and transience. The last Subsection is devoted to a brief introduction to queueing models.

3.1 Birth-and-death process

Birth process: This is a Markov process $X = (X_t)_{t \geq 0}$ with state space $I = \mathbb{N}_0$ which models growth of populations. We provide two alternative definitions:

Definition via 'holding times': Let a sequence $(\lambda_j)_{j \in \mathbb{N}_0}$ of positive numbers be given. Conditional on $X(0) = j, j \in \mathbb{N}_0$, the successive holding times are independent exponential random variables with parameters $\lambda_j, \lambda_{j+1}, \dots$. The sequence $(\lambda_j)_{j \in \mathbb{N}_0}$ is thus the sequence of the **birth rates** of the process.

Definition via 'infinitesimal probabilities': Pick $s, t \geq 0, t > s$, conditional on $X(s)$, the increment $X(t) - X(s)$ is positive and independent of $(X(u))_{0 \leq u \leq s}$. Furthermore, as $h \downarrow 0$ uniformly in $t \geq 0$, it holds for $j, m \in \mathbb{N}_0$ that

$$\mathbb{P}(X(t+h) = j+m | X(t) = j) = \begin{cases} \lambda_j h + o(h) & \text{if } m = 1, \\ o(h) & \text{if } m > 1, \\ 1 - \lambda_j h + o(h) & \text{if } m = 0. \end{cases}$$

From this definition we get the difference of the transition probabilities

$$\begin{aligned} P_{t+h}(j, k) - P_t(j, k) &= P_t(j, k-1)\lambda_{k-1}h - P_t(j, k)\lambda_k h + o(h), \quad j \in \mathbb{N}_0, k \in \mathbb{N} \\ P_t(j, j-1) &= 0, \end{aligned}$$

hence the forward equations read as

$$P'_t(j, k) = \lambda_{k-1}P_t(j, k-1) - \lambda_k P_t(j, k), \quad j \in \mathbb{N}_0, k \in \mathbb{N}, k \geq j.$$

Alternatively, conditioning on the time of the first jump yields the following relation

$$P_t(j, k) = \delta_{j,k} e^{-\lambda_j t} + \int_0^t \lambda_j e^{-\lambda_j s} P_{t-s}(j+1, k) ds,$$

and the backward equations read

$$P'_t(j, k) = \lambda_j P_t(j+1, k) - \lambda_j P_t(j, k).$$

Theorem 3.1 (Birth process) (a) With the initial condition $P_0(j, k) = \delta_{j,k}$ the forward equation has a unique solution which satisfies the backward equation.

(b) If $(P_t)_{t \geq 0}$ is a unique solution to the forward equation and $(B_t)_{t \geq 0}$ any solution of the backward equation, then $P_t(j, k) \leq B_t(j, k)$ for all $j, k \in \mathbb{N}_0$.

Proof. We give only a brief sketch. We get easily from the definition

$$\begin{aligned} P_t(j, k) &= 0, \quad k < j, \\ P_t(j, j) &= e^{-\lambda_j t}, \\ P_t(j, j+1) &= e^{-\lambda_{j+1} t} \int_0^t \lambda_j e^{-(\lambda_j - \lambda_{j+1})s} ds \\ &= \frac{\lambda_j}{\lambda_j - \lambda_{j+1}} (e^{-\lambda_{j+1} t} - e^{-\lambda_j t}). \end{aligned}$$

□

Example 3.2 (a) Simple birth process where the birth rates are linear, i.e. $\lambda_j = \lambda j$, $\lambda > 0$, $j \in \mathbb{N}_0$.

(b) Simple birth process with immigration where $\lambda_j = \lambda j + \nu$, $\nu \in \mathbb{R}$. ◇

Birth-and-death process. Let two sequences $(\lambda_k)_{k \in \mathbb{N}_0}$ and $(\mu_k)_{k \in \mathbb{N}_0}$ of positive numbers be given. At state $k \in \mathbb{N}_0$ we have a birth rate λ_k and a **death rate** μ_k , and we only allow 1-step transitions, that is either one birth or one death. The Q -matrix reads as

$$Q = \begin{pmatrix} \lambda_0 & -\lambda_0 & 0 & 0 & 0 & 0 & 0 & \dots \\ \mu_1 & -(\lambda_1 + \mu_1) & \lambda_1 & 0 & 0 & 0 & 0 & \dots \\ 0 & \mu_2 & -(\lambda_2 + \mu_2) & \lambda_2 & 0 & 0 & 0 & \dots \\ 0 & 0 & \dots & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 \dots & \dots & \dots & \dots & \dots & \dots \end{pmatrix}.$$

We obtain the infinitesimal probabilities

$$\begin{aligned} \mathbb{P}(\text{exactly 1 birth in } (t, t+h] | X_t = k) &= \lambda_k h + o(h), \\ \mathbb{P}(\text{exactly 1 death in } (t, t+h] | X_t = k) &= \mu_k h + o(h), \\ \mathbb{P}(\text{no birth in } (t, t+h] | X_t = k) &= 1 - \lambda_k h + o(h), \\ \mathbb{P}(\text{no death in } (t, t+h] | X_t = k) &= 1 - \mu_k h + o(h). \end{aligned}$$

In the following figure (see blackboard in lecture) we have three potential transitions to the state k at time $t + h$, namely if we have at time t the state $k + 1$ we have one death, if we have $k - 1$ at time t we do have exactly one birth, and if at time t we have already state k then we do not have a birth or a death. This is expressed in the following relation for the transition probabilities.

$$\begin{aligned} P_{t+h}(0, k) &= P_t(0, k)P_h(k, k) + P_t(0, k - 1)P_h(k - 1, k) \\ &\quad + P_t(0, k + 1)P_h(k + 1, k) \\ P_{t+h}(0, 0) &= P_t(0, 0)P_h(0, 0) + P_t(0, 1)P_h(1, 0). \end{aligned}$$

Combining these facts yields

$$\begin{aligned} \frac{dP_t(0, k)}{dt} &= -(\lambda_k + \mu_k)P_t(0, k) + \lambda_{k-1}P_t(0, k - 1) + \mu_{k+1}P_t(0, k + 1) \\ \frac{dP_t(0, 0)}{dt} &= -\lambda_0P_t(0, 0) + \mu_1P_t(0, 1). \end{aligned}$$

This can be seen as a probability flow. Pick a state k , then the probability flow rate into state k is given as $\lambda_{k-1}P_t(0, k - 1) + \mu_{k+1}P_t(0, k + 1)$, whereas the probability flow rate out of the state k is given as $(\lambda_k + \mu_k)P_t(0, k)$, henceforth the probability flow rate is the difference of the flow into and out of a state.

3.2 Hitting times and probabilities. Recurrence and transience

In this section we study properties of the single states of a continuous time Markov process. Let a countable state space I and a Markov process $X = (X_t)_{t \geq 0}$ with state space I be given. If $i, j \in I$ we say that i **leads to** j and write $i \longrightarrow j$ if $\mathbb{P}_i(X_t = j \text{ for some } t \geq 0) > 0$. We say i **communicates with** j and write $i \longleftrightarrow j$ if both $i \longrightarrow j$ and $j \longrightarrow i$ hold.

Theorem 3.3 *Let $X = (X_t)_{t \geq 0}$ be a Markov process with state space I and Q -matrix $Q = (q_{i,j})_{i,j \in I}$ and jump matrix $\Pi = (\pi_{i,j})_{i,j \in I}$. The following statements for $i, j \in I, i \neq j$ are equivalent.*

- (a) $i \longrightarrow j$.
- (b) $i \longrightarrow j$ for the corresponding jump chain $(Y_n)_{n \in \mathbb{N}_0}$.
- (c) $q_{i_0, i_1} q_{i_1, i_2} \cdots q_{i_{n-1}, i_n} > 0$ for some states $i_0, \dots, i_n \in I$ with $i_0 = i$ and $i_n = j$.

(d) $P_t(i, j) > 0$ for all $t > 0$.

(e) $P_t(i, j) > 0$ for some $t > 0$.

Proof. All implications are clear, we only show (c) \Rightarrow (d). If $q_{i,j} > 0$, then

$$P_t(i, j) \geq \mathbb{P}_i(J_1 \leq t, Y_1 = j, E_2 > t) = (1 - e^{-q_{i,j}t})\pi_{i,j}e^{-q_{i,j}t} > 0,$$

because $q_{i,j} > 0$ implies $\pi_{i,j} > 0$. \square

Let a subset $A \subset I$ be given. The **hitting time** of the set A is the random variable D^A defined by

$$D^A = \inf\{t \geq 0: X_t \in A\}.$$

Note that this random time can be infinite. It is therefore of great interest if the probability of ever hitting the set A is strictly positive, that is the probability that D^A is finite. The **hitting probability** h_i^A of the set A for the Markov process $(X_t)_{t \geq 0}$ starting from state $i \in I$ is defined as

$$h_i^A := \mathbb{P}_i(D^A < \infty).$$

Before we state and prove general properties let us study the following example concerning the expectations of hitting probabilities. The average time, starting from state i , for the Markov process $(X_t)_{t \geq 0}$ to reach the set A is given by $k_i^A := \mathbb{E}_i(D^A)$.

Example 3.4 *Let be given four states 1, 2, 3, 4 with the following transition rates (see figure). $1 \rightarrow 2 = 1; 1 \rightarrow 3 = 1; 2 \rightarrow 1 = 2; 2 \rightarrow 3 = 2; 2 \rightarrow 4 = 2; 3 \rightarrow 1 = 3; 3 \rightarrow 2 = 3; 3 \rightarrow 4 = 3$. How long does it take to get from state 1 to state 4? Note that once the process arrives in state 4 he will be trapped. Write $k_i := \mathbb{E}_i(\text{time to get to state 4})$. Starting in state 1 we spend an average time $q_1^{-1} = \frac{1}{2}$ in state 1, then we jump with equal probability to state 2 or state 3, i.e.*

$$k_1 = \frac{1}{2} + \frac{1}{2}k_2 + \frac{1}{2}k_3,$$

and similarly

$$k_2 = \frac{1}{6} + \frac{1}{3}k_1 + \frac{1}{3}k_3,$$

$$k_3 = \frac{1}{9} + \frac{1}{3}k_1 + \frac{1}{3}k_2.$$

Solving these linear equations gives $k_1 = \frac{17}{12}$. \diamond

Proposition 3.5 Let $X = (X_t)_{t \geq 0}$ be a Markov process with state space I and Q -matrix $Q = (q_{i,j})_{i,j \in I}$ and $A \subset I$.

(a) The vector $h^A = (h_i^A)_{i \in I}$ is the minimal non-negative solution to the system of linear equations

$$\begin{cases} h_i^A = 1 & \text{if } i \in A, \\ \sum_{j \in I} q_{i,j} h_j^A = 0 & \text{if } i \notin A. \end{cases}$$

(b) Assume that $q_i > 0$ for all $i \notin A$. The vector $k^A = (k_i^A)_{i \in I}$ of the expected hitting times is the minimal non-negative solution to the system of linear equations

$$\begin{cases} k_i^A = 0 & \text{if } i \in A, \\ -\sum_{j \in I} q_{i,j} k_j^A = 1 & \text{if } i \notin A. \end{cases}$$

Proof. (a) is left as an exercise. (b) $X_0 = i \in A$ implies $D^A = 0$, so $k_i^A = 0$ for $i \in A$. If $X_0 = i \notin A$ we get that $D^A \geq J_1$. By the Markov property of the corresponding jump chain $(Y_n)_{n \in \mathbb{N}_0}$ it follows that

$$\mathbb{E}_i(D^A - J_1 | J_1 = j) = \mathbb{E}_j(D^A).$$

Using this we get

$$\begin{aligned} k_i^A &= \mathbb{E}_i(D^A) = \mathbb{E}_i(J_1) + \sum_{j \in I \setminus \{i\}} \mathbb{E}_i(D^A - J_1 | Y_1 = j) \mathbb{P}_i(Y_1 = j) \\ &= q_i^{-1} + \sum_{j \in I \setminus \{i\}} \pi_{i,j} k_j^A, \end{aligned}$$

and therefore $-\sum_{j \in I} q_{i,j} k_j^A = 1$. We skip the details for proving that this is the minimal non-negative solution. \square

Example 3.6 *Birth-and-death process:* Recall that a birth-and-death process with birth rates $(\lambda_k)_{k \in \mathbb{N}_0}$ and death rates $(\mu_k)_{k \in \mathbb{N}_0}$ with $\mu_0 = 0$ has the Q -matrix $Q = (q_{i,j})_{i,j \in \mathbb{N}_0}$ given by

$$q_{j,j+1} = \lambda_j, q_{j,j-1} = \mu_j, j > 0, q_j = \lambda_j + \mu_j.$$

Let $k_{j,j+1}$ be the expected time it takes to reach state $j+1$ when starting in state j . The holding (waiting) time in state $j > 0$ has mean (expectation) $\frac{1}{\lambda_j + \mu_j}$. Hence,

$$\mathbb{E}_j(D^{\{j+1\}}) = k_{j,j+1} = (\lambda_j + \mu_j)^{-1} + \frac{\mu_j}{\lambda_j + \mu_j} (k_{j-1,j} + k_{j,j+1}),$$

and therefore $k_{j,j+1} = \lambda_j^{-1} + \left(\frac{\mu_j}{\lambda_j}\right)k_{j-1,j}$ for $j \geq 1$ and $k_{0,1} = \lambda_0^{-1}$. The solution follows by iteration. \diamond

Let a Markov process $(X_t)_{t \geq 0}$ on a countable state space I be given. A state $i \in I$ is called **recurrent** if $\mathbb{P}_i(\{t \geq 0: X_t = i\} \text{ is unbounded}) = 1$, and the state $i \in I$ is called **transient** if $\mathbb{P}_i(\{t \geq 0: X_t = i\} \text{ is unbounded}) = 0$.

The Q -matrix of the process $(X_t)_{t \geq 0}$ is called **irreducible** if the whole state space I is a single class with respect to the \longleftrightarrow - equivalence relation defined above.

Theorem 3.7 *Let $(X_t)_{t \geq 0}$ be a MP on a countable state space I . Then the following holds.*

- (i) *If $i \in I$ is recurrent for the jump chain $(Y_n)_{n \geq \mathbb{N}_0}$, then i is recurrent for the MP $(X_t)_{t \geq 0}$.*
- (ii) *If $i \in I$ is transient for the jump chain $(Y_n)_{n \geq \mathbb{N}_0}$, then i is transient for the MP $(X_t)_{t \geq 0}$.*
- (iii) *Every state is either recurrent or transient; and recurrence and transience are class properties.*

Proof. (i) Suppose i is recurrent for $(Y_n)_{n \in \mathbb{N}_0}$. If $X_0 = i$ then $(X_t)_{t \geq 0}$ does not explode and J_n unbounded by Proposition 2.24. Also $X_{J_n} = Y_n = i$ infinitely often, so $\{t \geq 0: X_t = i\}$ is unbounded, with probability 1.

(ii) Suppose i is transient for $(Y_n)_{n \in \mathbb{N}_0}$. If $X_0 = i$ then

$$N := \sup\{n \in \mathbb{N}_0: Y_n = i\} < \infty,$$

so $\{t \geq 0: X_t = i\}$ is bounded by J_{N+1} , which is finite, with probability 1, because $(Y_n)_{n \in \mathbb{N}_0}$ cannot include an absorbing state.

(iii) These properties are inherited from the jump chain, and they hold for discrete time MCs. \square

We shall give conditions for recurrence and transience in the continuous time setting of MPs with countable state spaces. We denote by T_i the **first passage time** of $(X_t)_{t \geq 0}$ to the state i , defined by

$$T_i := \inf\{t \geq J_1: X_t = i\}.$$

Theorem 3.8 *Let $(X_t)_{t \geq 0}$ be a MP on a countable state space I with Q -matrix $Q = (q_{i,j})_{i,j \in I}$. The following dichotomy holds:*

- (i) If $q_i = 0$ or $\mathbb{P}_i(T_i < \infty) = 1$, then i is recurrent and $\int_0^\infty P_t(i, i) dt = \infty$.
- (ii) If $q_i > 0$ and $\mathbb{P}_i(T_i < \infty) < 1$, then i is transient and $\int_0^\infty P_t(i, i) dt < \infty$.

Proof. If $q_i = 0$, then $(X_t)_{t \geq 0}$ cannot leave i , so i is recurrent, $P_t(i, i) = 1$ for all t , and $\int_0^\infty P_t(i, i) dt = \infty$. Suppose $q_i > 0$. Let N_i denote the first passage time of the jump chain $(Y_n)_{n \in \mathbb{N}_0}$ to state i . Then

$$\mathbb{P}_i(N_i < \infty) = \mathbb{P}_i(T_i < \infty),$$

so i is recurrent if and only if $\mathbb{P}_i(T_i < \infty) = 1$, by the previous Theorem 3.7 and the corresponding result for the jump chain. Recall that we write $\pi_{i,j}^{(n)}$ for (i, j) entry in Π^n . We shall show that

$$\int P_t(i, i) dt = \frac{1}{q_i} \sum_{n=0}^{\infty} \pi_{i,i}^{(n)}. \quad (3.23)$$

Now (3.23) implies that i is recurrent if and only if $\int_0^\infty P_t(i, i) dt = \infty$, by Theorem 3.7 and the corresponding result for the jump chain. The case for transience follows immediately. We are left to show (3.23). Using Fubini's theorem, we obtain

$$\begin{aligned} \int_0^\infty P_t(i, i) dt &= \int_0^\infty \mathbb{E}_i[\mathbb{1}\{X_t = i\}] dt = \mathbb{E}_i\left[\int_0^\infty \mathbb{1}\{X_t = i\} dt\right] \\ &= \mathbb{E}_i\left[\sum_{n=0}^{\infty} E_{n+1} \mathbb{1}\{Y_n = i\}\right] \\ &= \sum_{n=0}^{\infty} \mathbb{E}_i[E_{n+1} | Y_n = i] \mathbb{P}_i(Y_n = i) = \frac{1}{q_i} \sum_{n=0}^{\infty} \pi_{i,i}^{(n)}. \end{aligned}$$

□

Notation 3.9 (Invariant distribution) Let $(X_t)_{t \geq 0}$ be a Markov process on a countable state space I .

- (a) A vector $\lambda = (\lambda_j)_{j \in I}$, $\lambda \in \mathcal{M}_1(I)$ (set of probability measures on I), is called an **invariant** distribution, or a **stationary**, or an **equilibrium probability measure** if for all $t \geq 0$ and for all states $j \in I$ it holds that

$$\mathbb{P}(X_t = j) = \lambda_j, \text{ i.e. } \lambda P_t = \lambda.$$

- (b) A vector $(\lambda_j)_{j \in I}$ with $\lambda_j \geq 0$, $\sum_{j \in I} \lambda_j \neq 1$, and $\lambda P_t = \lambda$ for all $t \geq 0$ is called an **invariant measure**. If in addition $\sum_{j \in I} \lambda_j < \infty$ holds, an invariant distribution (equilibrium probability measure) is given via

$$\tilde{\lambda}_j = \lambda_j \left(\sum_{i \in I} \lambda_i \right)^{-1}.$$

Proposition 3.10 Assume that $(X_t)_{t \geq 0}$ is a non-explosive Markov process on a countable state space I with Q -matrix $Q = (q_{i,j})_{i,j \in I}$.

- (a) Then $\lambda = (\lambda_i)_{i \in I}$ is an invariant measure for the process $(X_t)_{t \geq 0}$ if and only if for all states $j \in I$

$$\sum_{i \in I} \lambda_i q_{i,j} = 0, \quad \text{i.e.} \quad \lambda Q = 0.$$

- (b) Assume in addition that $q_i > 0$ for all $i \in I$ and let Π be the transition matrix of the jump chain $(Y_n)_{n \in \mathbb{N}_0}$ and $\lambda = (\lambda_i)_{i \in I}$. Then

$$\lambda \text{ invariant measure for } (X_t)_{t \geq 0} \Leftrightarrow \mu \Pi = \mu \text{ with } \mu_i = \lambda_i q_i, i \in I.$$

Proof. (a) λ is an invariant measure if $\mathbb{P}(X_t = j) = \lambda_j$ for all $t \geq 0$ and all $j \in I$, i.e. $\lambda P_t = \lambda$. Thus the row vector λ is annihilated by the matrix Q :

$$\begin{aligned} 0 &= \frac{d}{dt} \lambda P_t = \lambda \frac{d}{dt} P_t = \lambda P_t Q, \\ 0 &= \lambda P_t Q \Big|_{t=0} = \lambda Q. \end{aligned}$$

This argument cannot work for an explosive chain as in this case one cannot guarantee that $\frac{d}{dt}(\lambda P_t) = 0$.

- (b) Write $\mu \Pi = \mu$ as $\mu \Pi - \mu \mathbb{1} = 0$, or

$$\begin{aligned} (\mu \Pi - \mu \mathbb{1})_j &= \sum_{i \in I \setminus \{j\}} \mu_i \frac{q_{i,j}}{q_i} - \mu_j = \sum_{i \in I} \mu_i \left((1 - \delta_{i,j}) \frac{q_{i,j}}{q_i} - \delta_{i,j} \right) \\ &= \sum_{i \in I} \mu_i \left(\frac{q_{i,j}}{q_i} - \delta_{i,j} \left(1 + \frac{q_{i,j}}{q_i} \right) \right) = \sum_{i \in I} \lambda_i q_{i,j} = (\lambda Q)_j. \end{aligned}$$

Now the LHS is zero if and only if the RHS is zero. □

Example 3.11 *Birth-and-death process:* Assume that $\lambda_n > 0$ for all $n \in \mathbb{N}_0$ and $\mu_n > 0$ for all $n \in \mathbb{N}, \mu_0 = 0$, that is all states communicate. The corresponding jump chain $(Y_n)_{n \in \mathbb{N}_0}$ has transition matrix Π defined as

$$\pi_{n,n-1} = \frac{\mu_n}{\lambda_n + \mu_n}, \quad \pi_{n,n+1} = \frac{\lambda_n}{\lambda_n + \mu_n}.$$

It is easy to show that the following equivalence holds:

$$(X_t)_{t \geq 0} \text{ recurrent} \Leftrightarrow (Y_n)_{n \in \mathbb{N}_0} \text{ recurrent.}$$

◇

We consider now an irreducible Birth-and-death process (BDP): Assume that $\lambda_n > 0$ for all $n \in \mathbb{N}_0$ and $\mu_n > 0$ for all $n \in \mathbb{N}, \mu_0 = 0$, that is all states communicate, i.e. the Q -matrix is irreducible. The corresponding jump chain $(Y_n)_{n \in \mathbb{N}_0}$ has transition matrix Π defined as

$$\pi_{n,n-1} = \frac{\mu_n}{\lambda_n + \mu_n}, \quad \pi_{n,n+1} = \frac{\lambda_n}{\lambda_n + \mu_n}.$$

If the jump chain $(Y_n)_{n \in \mathbb{N}_0}$ is transient then

$$p(n) = \mathbb{P}_n(\text{chain ever reaches } 0) \rightarrow 0 \text{ as } n \rightarrow \infty.$$

Clearly,

$$\begin{aligned} p(0) &= 1, \\ p(n)(\mu_n + \lambda_n) &= p(n-1)\mu_n + p(n+1)\lambda_n. \end{aligned}$$

We shall find the function $p(n)$. We get by iteration

$$\begin{aligned} p(n) - p(n+1) &= \frac{\mu_n}{\lambda_n} (p(n-1) - p(n)), \quad n \geq 1, \\ p(n) - p(n+1) &= \frac{\mu_1 \cdots \mu_n}{\lambda_1 \cdots \lambda_n} (p(0) - p(1)), \end{aligned}$$

and thus

$$\begin{aligned} p(n+1) &= (p(n+1) - p(0)) + p(0) \\ &= \sum_{j=0}^n (p(j+1) - p(j)) + 1 = (p(1) - 1) \sum_{j=0}^n \frac{\mu_1 \cdots \mu_j}{\lambda_1 \cdots \lambda_j} + 1, \end{aligned}$$

where by convention the term for $j = 0$ is equal to one. We can find a nontrivial solution for the function $p(n)$ if the sum converges. Hence, we can derive the following fact:

Fact I: BDP is transient $\Leftrightarrow \sum_{n=1}^{\infty} \frac{\mu_1 \cdots \mu_n}{\lambda_1 \cdots \lambda_n} < \infty$. \diamond

Recall

$$T_i = \inf\{t \geq J_1 : X_t = i, X_0 = i\}, \quad i \in I,$$

and that a state $i \in I$ is recurrent if $\mathbb{P}_i(T_i < \infty) = 1$, so this state is visited for indefinitely large times. As in the previous example consider a Markov chain $(Y_n)_{n \in \mathbb{N}_0}$ on a countable state space I such that a limiting probability measure $\nu \in \mathcal{M}_1(I)$ exists, that is

$$\lim_{n \rightarrow \infty} P_n(x, y) = \nu(x) \quad \text{for all } x, y \in I,$$

where P_n is the n -step transition function (entry of the n -th power of the transition matrix Π). However, if the chain $(Y_n)_{n \in \mathbb{N}_0}$ is transient then we have seen that $\lim_{n \rightarrow \infty} P_n(x, y) = 0$ for all $x, y \in I$. Hence, in this case no limiting probability measure exists. However, $\lim_{n \rightarrow \infty} P_n(x, y) = 0$ can hold for a recurrent chain. This shows the example of the simple random walk for which we proved that $P_{2n}(0, 0) \rightarrow 0$ as $n \rightarrow \infty$. This motivates to define two types of recurrence:

null-recurrent is recurrent but $\lim_{n \rightarrow \infty} P_n(x, y) = 0$ for all $x, y \in I$, otherwise **positive recurrent**.

Definition 3.12 A state $i \in I$ is called **positive recurrent (PR)** if $m_i := \mathbb{E}_i(T_i) < \infty$, and it is called **null-recurrent (NR)** if $\mathbb{P}_i(T_i < \infty) = 1$ but $m_i = \infty$.

It turns out that positive recurrent processes behave very similar to Markov chains with finite state spaces. The following theorem gives a connection between the mean return time m_i and an invariant distribution.

Theorem 3.13 Let $(X_t)_{t \geq 0}$ be an irreducible and recurrent Markov process on a countable state space I and Q -matrix $Q = (q_{i,j})_{i,j \in I}$. Then:

- (a) either every state $i \in I$ is PR or every state $i \in I$ is NR;
- (b) or Q is PR if and only if it has a (unique) invariant distribution $\pi = (\pi_i)_{i \in I}$, in which case

$$\pi_i > 0 \text{ and } m_i = \frac{1}{\pi_i q_i} \text{ for all } i \in I.$$

Proof. We give a brief sketch.

$$\begin{aligned} m_i &= \text{mean return time to } i \\ &= \text{mean holding time at } i + \sum_{j \in I \setminus \{i\}} (\text{mean time spent at } j \text{ before return to } i). \end{aligned}$$

The first term on the right hand side is clearly $q_i^{-1} =: \gamma_i^{(i)}$ and for $j \neq i$ we write

$$\begin{aligned} \gamma_j^{(i)} &= \mathbb{E}_i(\text{mean time spent at } j \text{ before return to } i) \\ &= \mathbb{E}_i\left(\int_{J_1}^{T_i} \mathbb{1}\{X_t = j\} dt\right) \\ &= \int_0^\infty \mathbb{E}_i\left(\mathbb{1}\{X_t = j, J_1 < t < T_i\}\right) dt. \end{aligned}$$

Then

$$m_i = \sum_{j \in I} \gamma_j^{(i)} = \frac{1}{q_i} + \sum_{j \in I \setminus \{i\}} \gamma_j^{(i)} \begin{cases} < \infty & \text{if state } i \text{ is PR,} \\ = \infty & \text{if state } i \text{ is NR.} \end{cases}$$

This defines the vector $\gamma^{(i)} = (\gamma_j^{(i)})_{j \in I}$ where we put the index to stress the dependence on the state $i \in I$. If T_i^Y is the return time to state i of the jump chain $(Y_n)_{n \in \mathbb{N}_0}$ then we get

$$\begin{aligned} \gamma_j^{(i)} &= \mathbb{E}_i\left(\sum_{n \in \mathbb{N}_0} (J_{n+1} - J_n) \mathbb{1}\{Y_n = j, n < T_i^Y\}\right) \\ &= \sum_{n \in \mathbb{N}_0} \mathbb{E}_i\left((J_{n+1} - J_n) | Y_n = j\right) \mathbb{P}_i(Y_n = j, 1 \leq n < T_i^Y) \\ &= \frac{1}{q_j} \mathbb{E}_i\left(\sum_{n=1}^{T_i^Y-1} \mathbb{1}\{Y_n = j\}\right) =: \frac{\tilde{\gamma}_j^{(i)}}{q_j}, \end{aligned}$$

where we set $\tilde{\gamma}_i^{(i)} = 1$, and for $j \neq i$,

$$\begin{aligned} \tilde{\gamma}_i^{(i)} &= \mathbb{E}_i\left(\sum_{n=1}^{T_i^Y-1} \mathbb{1}\{Y_n = j\}\right) \\ &= \mathbb{E}_i\left(\text{time spent at } j \text{ in } (Y_n)_{n \in \mathbb{N}_Y} \text{ before returning to } i\right) \\ &= \mathbb{E}_i\left(\text{number of visits to } j \text{ before returning to } i\right). \end{aligned}$$

If the process $(X_t)_{t \geq 0}$ is recurrent then so is the jump chain $(Y_n)_{n \in \mathbb{N}_0}$. Then the vector $\tilde{\gamma}^{(i)}$ gives an invariant measure with $\tilde{\gamma}_j^{(i)} < \infty$, and all invariant

measures are proportional to $\tilde{\gamma}^{(i)}$. Then the vector $\gamma^{(i)}$ with $\gamma_j^{(i)} = \frac{1}{q_j} \tilde{\gamma}_j^{(i)}$ gives an invariant measure for the process $(X_t)_{t \geq 0}$. Furthermore, all invariant measures are proportional to $\gamma^{(i)}$. If the state i is positive recurrent, then

$$m_i = \sum_{j \in I} \gamma_j^{(j)} < \infty.$$

But then $m_k = \sum_{j \in I} \gamma_j^{(k)} < \infty$, for all k , i.e. all states are positive recurrent. Similarly, if i is null-recurrent, then this applies to all states as well. Hence we obtain (a). If Q is PR, then

$$\pi_j = \frac{\gamma_j^{(i)}}{\sum_{j \in I} \gamma_j^{(i)}} = \frac{1}{q_i m_i}, \quad j \in I,$$

yields a (unique) invariant distribution π . Clearly, $\pi_i > 0$ and

$$\mathbb{E}_k(\text{time spent at } j \text{ before returning to } k) = \frac{\pi_j}{\pi_k q_k}.$$

Conversely, if $(X_t)_{t \geq 0}$ has an invariant distribution π then all invariant measures have finite sum. This implies that $m_i = \sum_{j \in I} \gamma_j^{(i)} < \infty$, henceforth i is positive recurrent. \square

Let us summarise our considerations above:

- (I) Irreducible Markov processes $(X_t)_{t \geq 0}$ with $|I| > 1$ have rates $q_i > 0$ for all $i \in I$.
- (II) Non-explosive Markov processes can be transient or recurrent.
- (III) Irreducible Markov processes can be
 - (a) null-recurrent, i.e. $m_i = \infty$, no invariant measure λ with $\sum_{i \in I} \lambda_i < \infty$ exists.
 - (b) positive recurrent, i.e. $m_i < \infty$, unique invariant distribution $\lambda = (\lambda_i)_{i \in I}$ with $\mathbb{E}_i(T_i) = \frac{1}{\lambda_i q_i}$.
- (IV) Explosive Markov processes are always transient.

We state the following large time results without proof. It is, however, important to realise how this is linked to invariant distributions.

Theorem 3.14 *Let $(X_t)_{t \geq 0}$ be a Markov process on a countable state space I with initial distribution $\lambda \in \mathcal{M}_1(I)$ and Q -matrix $Q = (q_{i,j})_{i,j \in I}$ and with invariant distribution $\pi = (\pi_i)_{i \in I}$. Then for all states $i \in I$ we get, as $t \rightarrow \infty$,*

$$(I) \quad \frac{1}{t} \int_0^t \mathbb{1}\{X_s = i\} ds = \text{fraction of time at } i \text{ in } (0, t) \longrightarrow \pi_i$$

$$= \frac{1}{m_i q_i} = \frac{\text{mean holding time at } i}{\text{mean return time to } i}.$$

$$(II) \quad \frac{1}{t} \mathbb{E} \left(\int_0^t \mathbb{1}\{X_s = i\} ds \right) = \frac{1}{t} \int_0^t \mathbb{P}(X_s = i) ds \longrightarrow \pi_i.$$

Proposition 3.15 (Convergence to equilibrium) *Let Q be an irreducible and non-explosive Q -matrix with semigroup $(P_t)_{t \geq 0}$ and invariant distribution $\pi = (\pi_i)_{i \in I}$. Then for all $i, j \in I$*

$$P_t(i, j) \longrightarrow \pi_j \text{ as } t \rightarrow \infty.$$

Example 3.16 (Recurrent BDP) *Assume that $\lambda_n > 0$ for all $n \in \mathbb{N}_0$ and $\mu_n > 0$ for all $n \in \mathbb{N}$, $\mu_0 = 0$, i.e., all states communicate. Positive recurrence of the BDP implies that $\lim_{t \rightarrow \infty} \mathbb{P}(X_t = n | X_0 = m) = \pi_n$ for all $m \in \mathbb{N}_0$ (otherwise a recurrent process is called null recurrent). If the process is in the limiting probability, i.e., if $\mathbb{P}(X_t = n) = \pi_n$, then $\dot{P}_t(n) = 0$. Recall that $P_t(n) := \mathbb{P}(X_t = n)$ and that we can obtain the following system of equations*

$$\dot{P}_t(n) = \mu_{n+1} P_t(n+1) + \lambda_{n-1} P_t(n-1) - (\mu_n + \lambda_n) P_t(n). \quad (3.24)$$

To compute the transition probabilities

$$P_t(m, n) = \mathbb{P}(X_t = n | X_0 = m)$$

we need to solve the system (3.24) with initial conditions $P_0(m) = 1$ and $P_0(n) = 0$ for $n \neq m$.

Then the limiting probability $\pi = (\pi_n)_{n \in \mathbb{N}_0}$ should satisfy

$$0 = \lambda_{n-1} \pi_{n-1} + \mu_{n+1} \pi_{n+1} - (\lambda_n + \mu_n) \pi_n. \quad (3.25)$$

If we can find a distribution that satisfies (3.25), then the Markov process is positive recurrent and the obtained distribution is the unique equilibrium distribution. We solve (3.25) directly: $n = 0$ gives $\pi_1 = \frac{\lambda_0}{\mu_1} \pi_0$ and for $n \geq 1$ we get

$$\mu_{n+1} \pi_{n+1} - \lambda_n \pi_n = \mu_n \pi_n - \lambda_{n-1} \pi_{n-1}.$$

Iterating this yields

$$\mu_{n+1}\pi_{n+1} - \lambda_n\pi_n = \mu_1\pi_1 - \lambda_0\pi_0 = 0.$$

Hence, $\pi_{n+1} = \left(\frac{\lambda_n}{\mu_{n+1}}\right)\pi_n$, and by iterating we get the solution

$$\pi_n = \frac{\lambda_0 \cdots \lambda_{n-1}}{\mu_1 \cdots \mu_n} \pi_0.$$

We now impose the condition that π be a probability measure. We can arrange this if $\sum_{n=0}^{\infty} \pi_n < \infty$. \diamond

Example 3.16 establishes the following.

Fact II: BDP

$$\text{positive recurrent} \Leftrightarrow q := \sum_{n=0}^{\infty} \frac{\lambda_0 \cdots \lambda_{n-1}}{\mu_1 \cdots \mu_n} < \infty,$$

in which case $\pi_n = \frac{\lambda_0 \cdots \lambda_{n-1}}{\mu_1 \cdots \mu_n} q^{-1}$.

Definition 3.17 (Reversible process) A non-explosive Markov process $(X_t)_{t \geq 0}$ with state space I and Q -matrix Q is called **reversible** if for all $i_0, \dots, i_n \in I, n \in \mathbb{N}$, and times $0 = t_0 < t_1 < \dots < t_n = T, T > 0$,

$$\mathbb{P}(X_0 = i_0, \dots, X_T = i_n) = \mathbb{P}(X_0 = i_n, \dots, X_{T-t_1} = i_1, X_T = i_0).$$

Equivalently,

$$(X_t: 0 \leq t \leq T) \sim (X_{T-t}: 0 \leq t \leq T) \quad \text{for all } T > 0,$$

where \sim stands for equal in distribution. Note that in order to define the reversed process one has to fix a time $T > 0$.

Theorem 3.18 (Detailed balance equations) A non-explosive Markov process $(X_t)_{t \geq 0}$ with state space I and Q -matrix $Q = (q_{i,j})_{i,j \in I}$ and initial distribution $\lambda = (\lambda_i)_{i \in I}$ is reversible if and only if the **detailed balance equations (DBEs)**

$$\lambda_i q_{i,j} = \lambda_j q_{j,i} \quad \text{for all } i, j \in I, i \neq j,$$

hold.

Proof. Suppose the detailed balance equations hold. Hence,

$$(\lambda Q)_j = \sum_{i \in I} \lambda_i q_{i,j} = \sum_{i \in I} \lambda_j q_{j,i} = 0.$$

By induction, the DBEs hold for all powers of Q ,

$$\lambda_i q_{i,j}^{(k)} = \lambda_i \sum_{\ell \in I} q_{i,\ell} q_{\ell,j}^{(k-1)} = \sum_{\ell \in I} q_{\ell,i} \lambda_\ell q_{\ell,j}^{(k-1)} = \sum_{\ell \in I} q_{j,\ell}^{(k-1)} q_{\ell,i} \lambda_j = \lambda_j q_{j,i}^{(k)}.$$

Henceforth

$$\lambda_i P_t(i, j) = \lambda_j P_t(j, i), \quad t \geq 0. \quad (3.26)$$

We shall check that

$$\mathbb{P}(X_{t_k} = i_k, 0 \leq k \leq n) = \mathbb{P}(X_{T-t_k} = i_k, 0 \leq k \leq n). \quad (3.27)$$

Using (3.26) several times we get

$$\begin{aligned} \text{L.H.S. of (3.27)} &= \lambda_{i_0} P_{t_1-t_0}(i_0, i_1) \cdots P_{t_n-t_{n-1}}(i_{n-1}, i_n) \\ &= P_{t_1-t_0}(i_1, i_0) \lambda_{i_1} P_{t_2-t_1}(i_1, i_2) \cdots P_{t_n-t_{n-1}}(i_{n-1}, i_n) \\ &= \cdots \\ &= P_{t_1-t_0}(i_0, i_1) P_{t_2-t_1}(i_1, i_2) \cdots P_{t_n-t_{n-1}}(i_n, i_{n-1}) \lambda(i_n). \end{aligned}$$

We rearrange this to obtain the right hand side of (3.27) as

$$\lambda_{i_n} P_{t_n-t_{n-1}}(i_n, i_{n-1}) \cdots = \mathbb{P}(X_{T-t_k} = i_k, 0 \leq k \leq n).$$

Conversely, suppose now that the process is reversible and put $n = 1$, $i_0 = i \in I$, $j_0 = j \in I$ and let $T > 0$. Then reversibility gives

$$\lambda_i P_T(i, j) = \lambda_j P_T(j, i).$$

We differentiate this with respect to the parameter T and set $T = 0$ to obtain the DBEs using that $\dot{P}_t(i, j) = q_{i,j}$. \square

Notation 3.19 (Time reversed process) We denote the time reversed process (reversed about $T > 0$) by $(X_t^{(\text{tr})})_{0 \leq t \leq T}$ which is defined by

$$\mathbb{P}(X_0^{(\text{tr})} = i_0, \dots, X_T^{(\text{tr})} = i_n) = \mathbb{P}(X_0 = i_n, \dots, X_{T-t_1} = i_1, X_T = i_0).$$

4 Percolation theory

We give a brief introduction in percolation theory in Section 4.1, provide important basic tools in Section 4.2, and study and prove the important Kesten Theorem for bond percolation in Section 4.3.

4.1 Introduction

Percolation theory was founded by Broadbent and Hammersley 1957, in order to model the flow of a fluid in a porous medium with randomly blocked channels. Percolation is a simple probabilistic model which exhibits a phase transition (as we explain below). The simplest version takes place on \mathbb{Z}^2 , which we view as a graph with edges between neighboring vertices. All edges of \mathbb{Z}^2 are, independently of each other, chosen to be open with probability p and closed with probability $1 - p$. A basic question in this model is "What is the probability that there exists an open path, i.e., a path all of whose edges are open, from the origin to the exterior of the square $\Lambda_n := [-n, n]^2$?" This question was raised by Broadbent in 1954 at a symposium on Monte Carlo methods. It was then taken up by Broadbent and Hammersley, who regarded percolation as a model for a random medium. They interpreted the edges of \mathbb{Z}^2 as channels through which fluid or gas could flow if the channel was wide enough (an open edge) and not if the channel was too narrow (a closed edge). It was assumed that the fluid would move wherever it could go, so that there is no randomness in the behavior of the fluid, but all randomness in this model is associated with the medium. We shall use 0 to denote the origin. A limit as $n \rightarrow \infty$ of the question raised above is "What is the probability that there exists an open path from 0 to infinity?" This probability is called the percolation probability and denoted by $\theta(p)$. Clearly $\theta(0) = 0$ and $\theta(1) = 1$, since there are no open edges at all when $p = 0$ and all edges are open when $p = 1$. It is also intuitively clear that the function $p \mapsto \theta(p)$ is nondecreasing. Thus the graph of θ as a function of p should have the form indicated in Figure (XX), and one can define the critical probability by $p_c = \sup\{p \in [0, 1] : \theta(p) = 0\}$. Why is this model interesting? In order to answer this we define the (open) cluster $C(x)$ of the vertex $x \in \mathbb{Z}^2$ as the collection of points connected to x by an open path. The clusters $C(x)$ are the maximal connected components of the collection of open edges of \mathbb{Z}^2 , and $\theta(p)$ is the probability that $C(0)$ is infinite. If $p < p_c$, then $\theta(p) = 0$ by definition, so that $C(0)$ is finite with probability 1. It is not hard to see that in this case all open clusters are finite. If $p > p_c$, then $\theta(p) > 0$ and there is a strictly positive probability that $C(0)$ is infinite. An application of Kolmogorov's zero-one law shows that there is then with probability 1

some infinite cluster. In fact, it turns out that there is a unique infinite cluster. Thus, the global behavior of the system is quite different for $p < p_c$ and for $p > p_c$. Such a sharp transition in global behavior of a system at some parameter value is called a phase transition or a critical phenomenon by statistical physicists, and the parameter value at which the transition takes place is called a critical value. There is an extensive physics literature on such phenomena. Broadbent and Hammersley proved that $0 < p_c < 1$ for percolation on Z^2 , so that there is indeed a nontrivial phase transition. Much of the interest in percolation comes from the hope that one will be better able to analyze the behavior of various functions near the critical point for the simple model of percolation, with all its built-in independence properties, than for other, more complicated models for disordered media. Indeed, percolation is the simplest one in the family of the so-called random cluster or Fortuin-Kasteleyn models, which also includes the celebrated Ising model for magnetism. The studies of percolation and random cluster models have influenced each other.

Let us begin and collect some obvious notations. $Z^d, d \geq 1$, is the set of all vectors $x = (x_1, \dots, x_d)$ with integral coordinates. The (graph-theoretic) distance $\delta(x, y)$ from x to y is defined by

$$\delta(x, y) = \sum_{i=1}^d |x_i - y_i|,$$

and we write $|x|$ for $\delta(0, x)$. We turn Z^d into a graph, called the d -dimensional cubic lattice, by adding edges between all pairs x, y of points of Z^d with $\delta(x, y) = 1$. We write for this graph $\mathbb{L}^d = (Z^d, \mathbb{E}^d)$ where \mathbb{E}^d is the set of edges. If $\delta(x, y) = 1$ we say that x and y are adjacent, and we write in this case $x \sim y$ and represent the edges from x to y as $\langle x, y \rangle$. We shall introduce now some probability. Denote by

$$\Omega = \prod_{e \in \mathbb{E}^d} \{0, 1\} = \{0, 1\}^{Z^d} = \{\omega: \mathbb{E}^d \rightarrow \{0, 1\}\}$$

the set of configurations $\omega = (\omega(e))_{e \in \mathbb{E}^d}$ (set of all mappings $\mathbb{E}^d \rightarrow \{0, 1\}$) with the interpretation that the edge $e \in \mathbb{E}^d$ is **closed** for the configuration ω if $\omega(e) = 0$ and the edge e is **open** for the configuration ω if $\omega(e) = 1$. The set Ω will be our sample or probability space. We need further a σ -algebra and a measure for this sample space. An obvious choice for the σ -algebra of events is the one which is generated by all **cylinder** events $\{\omega \in \Omega: \omega(e) = a_e, a_e \in \{0, 1\}, e \in \Delta, \Delta \subset \mathbb{E}^d \text{ finite}\}$, and we call it \mathcal{F} . For

every $e \in \mathbb{E}^d$ let μ_e be the Bernoulli (probability) measure on $\{0, 1\}$ defined by

$$\mu_e(\omega(e) = 0) = 1 - p \text{ and } \mu_e(\omega(e) = 1) = p, \quad p \in [0, 1].$$

Then the product of these measures defines a probability measure on the space of configurations Ω , denoted by

$$\mathbb{P}_p = \prod_{e \in \mathbb{E}^d} \mu_e.$$

In the following we are going to consider only the measure $\mathbb{P}_p \in \mathcal{M}_1(\Omega)$ for different parameters $p \in [0, 1]$. As the probability measure \mathbb{P}_p is a product measure (over all edges) it is a model for the situation where each edges is open (or closed) independently of all other edges with probability p (respectively with probability $1 - p$). If one considers a probability measure on Ω which is not a product of probability measures on the single edges, one calls the corresponding percolation model dependent. In this course we only study independent (hence the product measure \mathbb{P}_p) percolation models.

A **path** in \mathbb{L}^d is an alternating sequence $x_0, e_0, x_1, e_1, \dots, e_{n-1}, x_n$ of distinct vertices x_i and edges $e_i = \langle x_i, x_{i+1} \rangle$; such a path has length n and is said to connect x_0 to x_n . A **circuit** is a closed path. Consider the random subgraph of \mathbb{L}^d containing the vertex set \mathbb{Z}^d and the open edges (bonds) only. The connected components of the graph are called **open clusters**. We write $C(x)$ for the open cluster containing the vertex x . If A and B are set of vertices we write $A \longleftrightarrow B$ if there exists an open path joining some vertex in A to some vertex in B . Hence,

$$C(x) = \{y \in \mathbb{Z}^d : x \longleftrightarrow y\},$$

and we denote by $|C(x)|$ the number of vertices in $C(x)$. As above we write $C = C(0)$ for the open cluster containing the origin.

$$\theta(p) = \mathbb{P}_p(|C| = \infty) = 1 - \sum_{n=1}^{\infty} \mathbb{P}_p(|C| = n).$$

It is fundamental to percolation theory that there exists a critical value $p_c = p_c(d)$ of p such that

$$\theta(p) \begin{cases} = 0 & \text{if } p < p_c, \\ > 0 & \text{if } p > p_c; \end{cases}$$

$p_c(d)$ is called the **critical probability**. As above $p_c(d) = \sup\{p \in [0, 1] : \theta(p) = 0\}$. In dimension $d = 1$ for any $p < 1$ there exist infinitely many closed edges to the left and to the right of the origin almost surely, implying $\theta(p) = 0$

for $p < 1$, and thus $p_c(1) = 1$. The situation is quite different for higher dimensions. Note that the d -dimensional lattice \mathbb{L}^d may be embedded in \mathbb{L}^{d+1} in a natural way as the projection of \mathbb{L}^{d+1} onto the subspace generated by the first d coordinates; with this embedding, the origin of \mathbb{L}^{d+1} belongs to an infinite open cluster for a particular value of p whenever it belongs to an infinite open cluster of the sublattice \mathbb{L}^d . Thus

$$p_c(d+1) \leq p_c(d), \quad d \geq 1.$$

Theorem 4.1 *If $d \geq 2$ the $0 < p_c(d) < 1$.*

This means that in two or more dimension there are two phases of the process. In the **subcritical phase** $p < p_c(d)$, every vertex is almost surely in a finite open cluster. In the **supercritical phase** when $p > p_c(d)$, each vertex has a strictly positive probability of being in an infinite open cluster.

Theorem 4.2 *The probability $\Psi(p)$ that there exists an infinite open cluster satisfies*

$$\Psi(p) = \begin{cases} 0 & \text{if } \theta(p) = 0, \\ 1 & \text{if } \theta(p) > 0. \end{cases}$$

We shall prove both theorems in the following. For that we derive the following non-trivial upper and lower bounds for $p_c(d)$ when $d \geq 2$.

$$\frac{1}{\lambda(2)} \leq p_c(2) \leq 1 - \frac{1}{\lambda(2)}, \quad (4.28)$$

and

$$\frac{1}{\lambda(d)} \leq p_c(d) \quad \text{for } d \geq 3; \quad (4.29)$$

where $\lambda(d)$ is the connective constant of \mathbb{L}^d , defined as

$$\lambda(d) = \lim_{n \rightarrow \infty} \sqrt[n]{\sigma(n)},$$

with $\sigma(n)$ being the number of paths (or 'self-avoiding walks') of \mathbb{L}^d having length n and beginning at the origin. It is obvious that $\lambda(d) \leq 2d - 1$; to see this, note that each new step in a self-avoiding walk has at most $2d - 1$ choices since it must avoid the current position. Henceforth $\sigma(n) \leq 2d(2d - 1)^{n-1}$. Inequality (4.29) implies that $(2d - 1)p_c(d) \geq 1$, and it is known that further $p_c(d) \sim (2d)^{-1}$ as $d \rightarrow \infty$.

Proof of Theorem 4.1 and (4.28). As $p_c(d+1) \leq p_c(d)$ it suffices to show that $p_c(d) > 0$ for $d \geq 2$ and that $p_c(2) < 1$.

We show that $p_c(d) > 0$ for $d \geq 2$: We consider bond percolation on \mathbb{L}^d when $d \geq 2$. It suffices to show that $\theta(p) = 0$ whenever p is sufficiently close to 0. As above denote by $\sigma(n)$ the number of paths ('self-avoiding walks') of length n starting at the origin and denote by $N(n)$ the number of those paths which are open. Clearly, $\mathbb{E}_p(N(n)) = p^n \sigma(n)$. If the origin belongs to an infinite open cluster then there exist open paths of all lengths beginning at the origin, so that

$$\theta(p) \leq \mathbb{P}_p(N(n) \geq 1) \leq \mathbb{E}_p(N(n)) = p^n \sigma(n) \text{ for all } n.$$

We have that $\sigma(n) = (\lambda(d) + o(1))^n$ as $n \rightarrow \infty$, hence,

$$\theta(p) \leq (p\lambda(d) + o(1))^n \rightarrow 0 \text{ as } n \rightarrow \infty \text{ if } p\lambda(d) < 1.$$

Thus we have shown that $p_c(d) \geq \lambda(d)^{-1}$ where $\lambda(d) \leq 2d - 1 < \infty$ and henceforth $p_c(d) > 0$.

We show that $p_c(2) < 1$: We use the famous 'Peierls argument' in honour of Rudolf Peierls and his 1936 article on the Ising model. We consider bond percolation on \mathbb{L}^2 . We shall show that $\theta(p) > 0$ if p is sufficiently close to 1. Let $(\mathbb{Z}^2)^*$ be the dual lattice, i.e. $(\mathbb{Z}^2)^* = \mathbb{Z}^2 + (-1/2, 1/2)$, see Figure 1 where the dotted edges are the ones for the dual lattice.

There is a one-one correspondence between the edges of \mathbb{L}^2 and the edges of the dual, since each edge of \mathbb{L}^2 is crossed by a unique edge of the dual. We declare an edge of the dual to be open or closed depending respectively on whether it crosses an open or closed edge of \mathbb{L}^2 . We thus obtain a bond percolation process on the dual with the same edge-probability. Suppose that the open cluster at the origin of \mathbb{L}^2 is finite, see Figure 2. We see that the origin is surrounded by a necklace of closed edges which are blocking off all possible routes from the origin to infinity. Clearly, this is satisfied when the corresponding edges of the dual contain a closed circuit in the dual having the origin of \mathbb{L}^2 in its interior. If the origin is in the interior of a closed circuit in the dual then the open cluster at the origin is finite

$$|C| < \infty \Leftrightarrow 0 \in \text{interior of a closed circuit in dual.}$$

Similarly to the first part we now count the number of such closed circuits in the dual. Let $\rho(n)$ be the number of circuits of length n in the dual which contain the origin of \mathbb{L}^2 . We get an upper bound for this number as follows. Each circuit passes through some vertex (lattice site) of the form $(k + 1/2, 1/2)$ for some integer $0 \leq k < n$. Furthermore, a circuit contains a self-avoiding walk of length n from a vertex of the form $(k + 1/2, 1/2)$ for

Figure Dual lattice

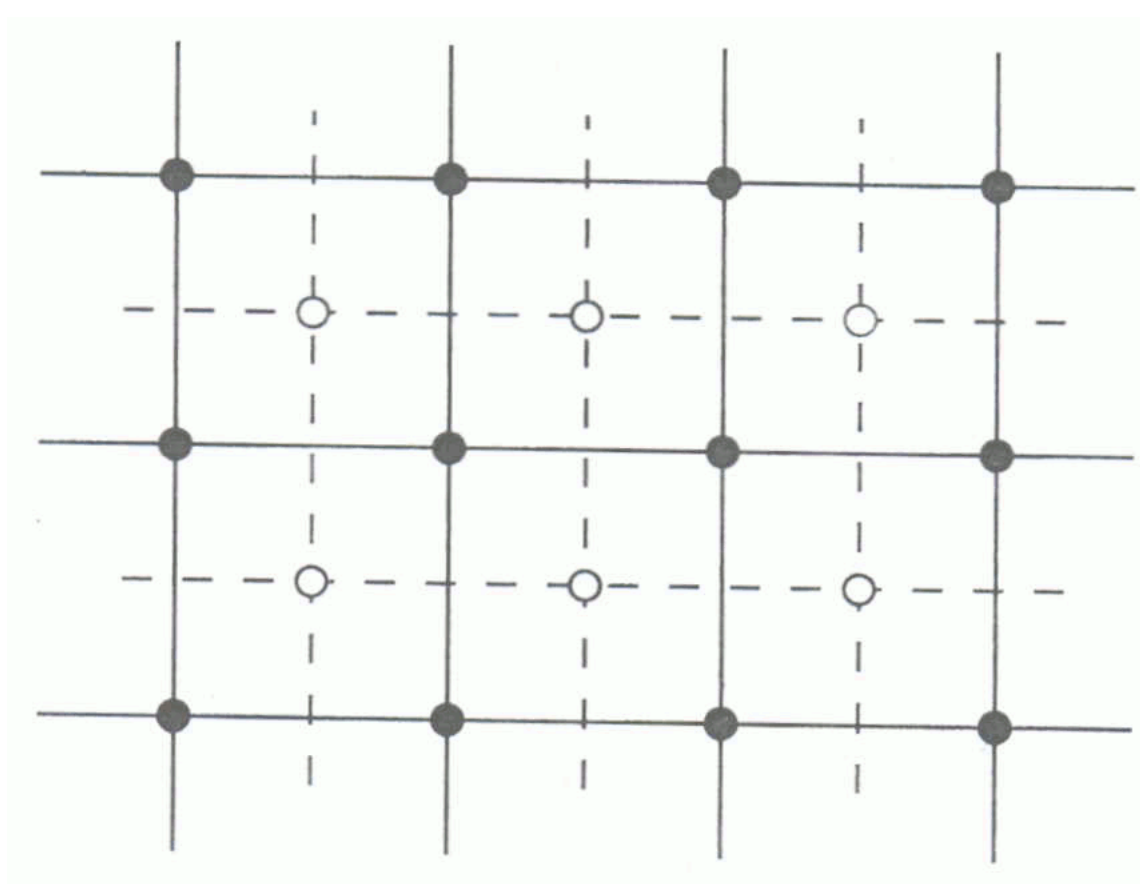


Figure 1: Dual lattice

some integer $0 \leq k < n$. The number of such self-avoiding walks is at most $n\sigma(n-1)$. Hence, the upper bound follows

$$\rho(n) \leq n\sigma(n-1).$$

In the following denote by \mathcal{C}_0^* the set of circuits in the dual containing the origin of \mathbb{L}^2 . We estimate (we write $|\gamma|$ for the length of any path/circuit), recalling that $q = 1 - p$ is the probability of an edge to be closed,

$$\begin{aligned} \sum_{\gamma \in \mathcal{C}_0^*} \mathbb{P}_p(\gamma \text{ is closed}) &= \sum_{n=1}^{\infty} \sum_{\gamma \in \mathcal{C}_0^*, |\gamma|=n} \mathbb{P}_p(\gamma \text{ is closed}) \leq \sum_{n=1}^{\infty} q^n \sigma(n-1) \\ &\leq \sum_{n=1}^{\infty} qn(q\lambda(2) + o(1))^{n-1} < \infty, \end{aligned}$$

if $q\lambda(2) < 1$. Furthermore, $\sum_{\gamma \in \mathcal{C}_0^*} \mathbb{P}_p(\gamma \text{ is closed}) \rightarrow 0$ as $q = 1 - p \rightarrow 0$. Hence, there exists $\tilde{p} \in (0, 1)$ such that

$$\sum_{\gamma \in \mathcal{C}_0^*} \mathbb{P}_p(\gamma \text{ is closed}) \leq \frac{1}{2} \quad \text{for } p > \tilde{p}.$$

Let $M(n)$ be the number of circuits of \mathcal{C}_0^* having length n . Then

$$\begin{aligned} \mathbb{P}_p(|C| = \infty) &= \mathbb{P}_p(M(n) = 0 \text{ for all } n) = 1 - \mathbb{P}_p(M(n) \geq 1 \text{ for some } n) \\ &\geq 1 - \sum_{\gamma \in \mathcal{C}_0^*} \mathbb{P}_p(\gamma \text{ is closed}) \geq \frac{1}{2} \end{aligned}$$

if we pick $p > \tilde{p}$. This gives $p_c(2) \leq \tilde{p} < 1$. We need to improve the estimates to obtain that $p_c(2) \leq 1 - \lambda(2)^{-1}$. We do this a bit later below. \square

Proof of Theorem 4.2. The event

$$\{\mathbb{L}^d \text{ contains an infinite open cluster}\}$$

does not depend upon the states of any finite collection of edges. Hence, we know by the Zero-one law (Kolmogorov) that the probability $\Psi(p)$ can only take the values 0 or 1. If $\theta(p) = 0$ then

$$\Psi(p) \leq \sum_{x \in \mathbb{Z}^d} \mathbb{P}_p(|C(x)| = \infty) = 0.$$

If $\theta(p) > 0$ then

$$\Psi(p) \geq \mathbb{P}_p(|C| = \infty) > 0,$$

so that $\Psi(p)$ by the zero-one law. □

Another 'macroscopic' quantity such as $\theta(p)$ and $\Psi(p)$ is the mean (or expected) size of the open cluster at the origin, $\chi_p = \mathbb{E}_p(|C|)$.

$$\chi_p = \infty \mathbb{P}_p(|C| = \infty) + \sum_{n=1}^{\infty} n \mathbb{P}_p(|C| = n).$$

Clearly, $\chi_p = \infty$ if $p > p_c(d)$. The converse is not at all obvious: is it that $\chi(p) < \infty$ if $p < p_c(d)$? We will answer this question later. However, this indicates that the 'macroscopic' quantities θ and χ manifest critical behaviour at the same value of p . It is believed that most 'macroscopic' quantities are smooth functions of the parameter p except at the critical value $p_c(d)$. In our percolation model we have exactly two phases - the **subcritical phase** ($p < p_c(d)$) and the **supercritical phase** ($p > p_c(d)$).

Subcritical phase: When $p < p_c(d)$, all open clusters are finite almost surely. One can show that the tail of the size $|C|$ of an open cluster C decreases exponentially, which is to say there exists an $\alpha(p) > 0$ such that

$$\mathbb{P}_p(|C| = n) \approx e^{-n\alpha(p)} \quad \text{as } n \rightarrow \infty,$$

when $p < p_c(d)$.

Supercritical phase: When $p > p_c(d)$, there exist infinite open clusters almost surely, but how many? If time permits we shall show later that the infinite open cluster is unique almost surely.

4.2 Some basic techniques

4.3 Bond percolation in \mathbb{Z}^2