



Standing and travelling waves in a spherical brain model

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The Nunez model³

- Model for generation of EEG signals.
- Important observations:
 - Long range synaptic interactions excitatory while inhibitory interactions more short ranged.
 - Delays (local and global) important in generating robust human EEG frequencies.
 - Cortical white matter system topologically close to sphere - standing waves can occur via interference
- Model often studied in topologies quite different to the brain (e.g. line¹ or plane²).
- Two forms - damped wave equation and integro-differential equation (which we will use here with delays).

¹V K Jirsa and H Haken. "Field theory of electromagnetic brain activity". In: *Physical Review Letters* 77 (1996), pp. 960–963.

²S Coombes et al. "Modeling electrocortical activity through improved local approximations of integral neural field equations". In: *Physical Review E* 76, 051901 (2007). p. 051901. DOI: 10.1103/PhysRevE.76.051901

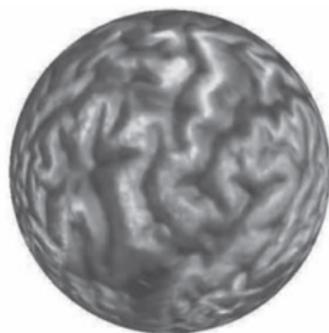
Spherical models



Spherical models



(a) Brain cortex surface



(b) Conformal brain mapping

Overview

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 - Neural field model on a sphere.
 - Integro-differential equation with space-dependent delays.

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 - Equivariant bifurcation theory tells us symmetries of periodic solutions which can exist after dynamic instability...
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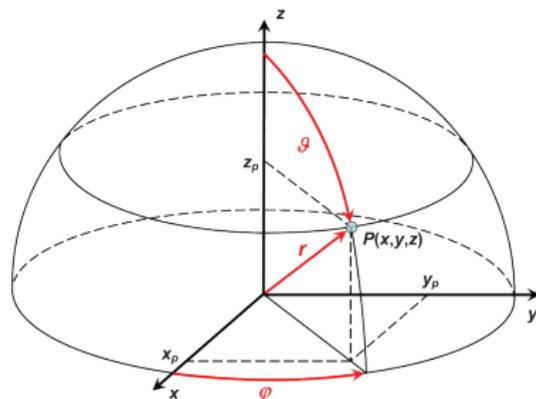
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- 6 Further work.

A little bit of geometry



Polar angle:

$$0 \leq \theta \leq \pi$$

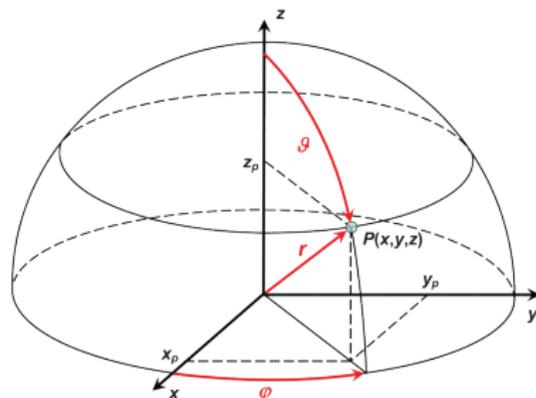
Azimuthal angle:

$$0 \leq \phi \leq 2\pi$$

Point on a sphere of radius R :

$$\mathbf{r} = \mathbf{r}(\theta, \phi) = R(\cos \phi \sin \theta, \sin \phi \sin \theta, \cos \theta)$$

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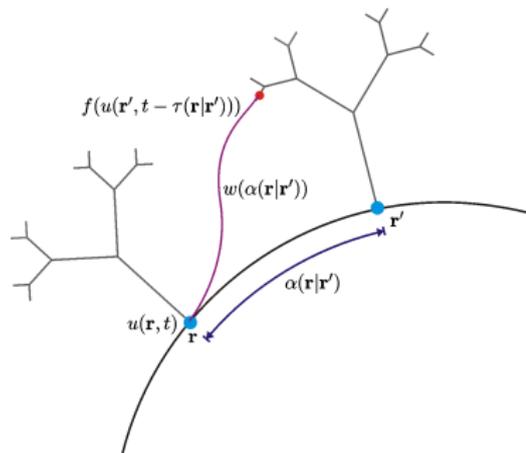
$$\mathbf{r} = \mathbf{r}(\theta, \phi) = R(\cos \phi \sin \theta, \sin \phi \sin \theta, \cos \theta)$$

Distance between two points \mathbf{r} and \mathbf{r}' :

$$\begin{aligned} \alpha(\mathbf{r}|\mathbf{r}') &= R \cos^{-1} (\mathbf{r} \cdot \mathbf{r}' / (|\mathbf{r}||\mathbf{r}'|)) \\ &= R \cos^{-1} (\cos \theta \cos \theta' + \sin \theta \sin \theta' \cos(\phi - \phi')) . \end{aligned}$$

The model

$$\frac{\partial u}{\partial t} = -u + \int_{\Omega} w(\mathbf{r}|\mathbf{r}') f(u(\mathbf{r}', t - \tau(\mathbf{r}|\mathbf{r}'))) d\mathbf{r}'$$

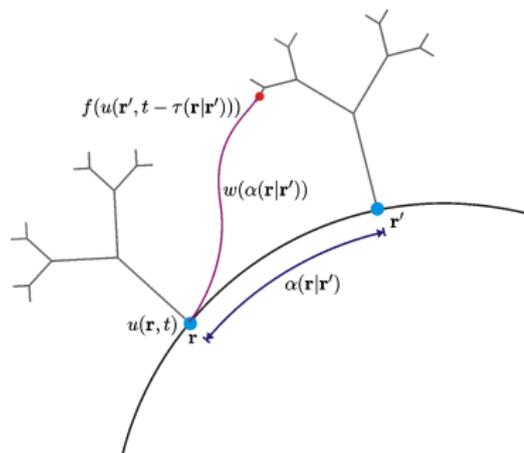


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$O(3)$ invariant connectivity (synaptic kernel):

$$w(\mathbf{r}|\mathbf{r}') = w(\alpha) = A_1 e^{-\frac{\alpha}{\sigma_1}} + A_2 e^{-\frac{\alpha}{\sigma_2}}, \quad \sigma_1 > \sigma_2, \quad A_1 A_2 < 0.$$



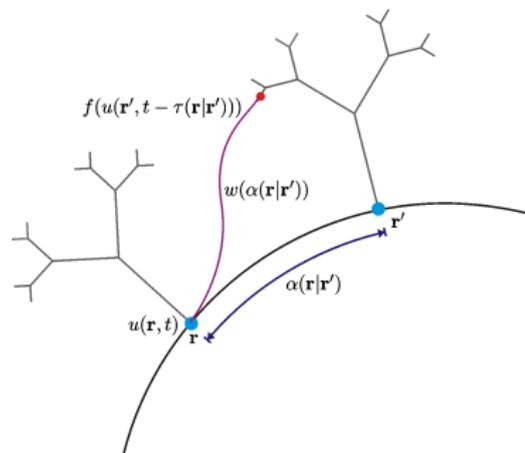
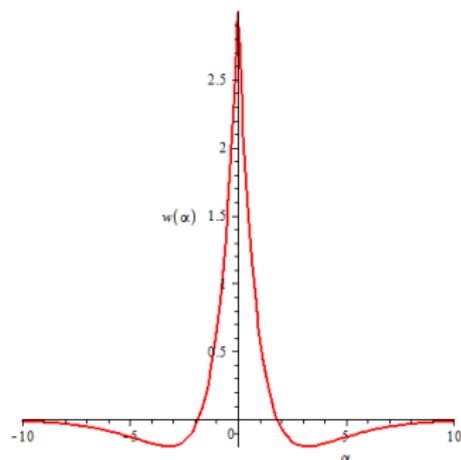
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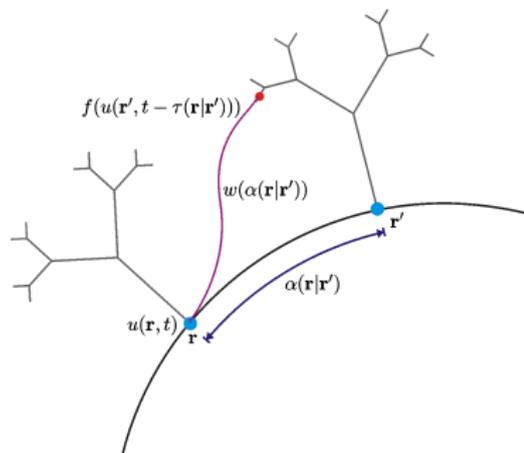
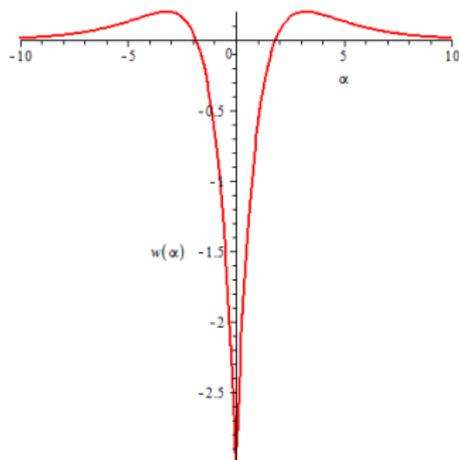
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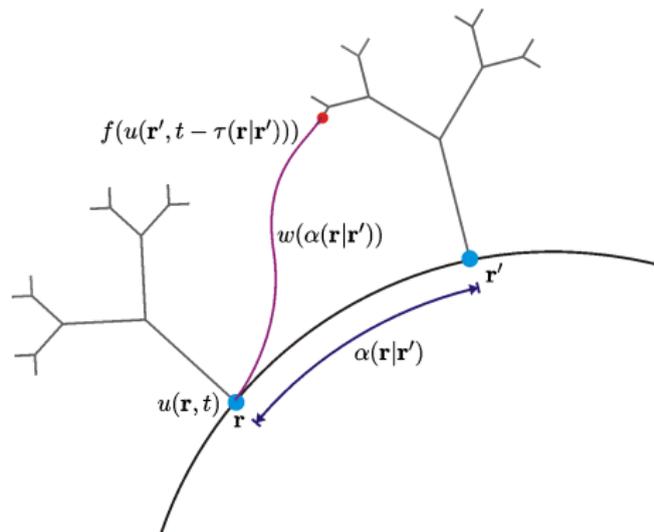
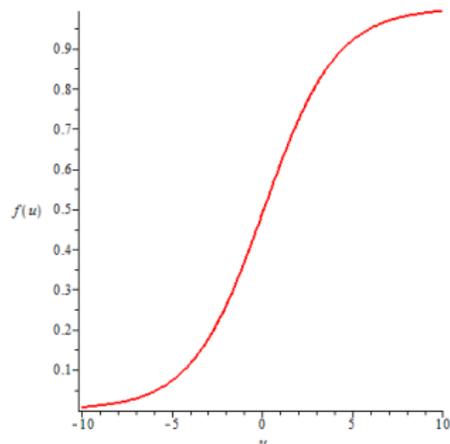


The model

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Firing rate : $f(u) = \frac{1}{1 + e^{-\beta(u-h)}}$, $\beta > 0$,

h a threshold parameter, β controls the slope of the firing rate at threshold.



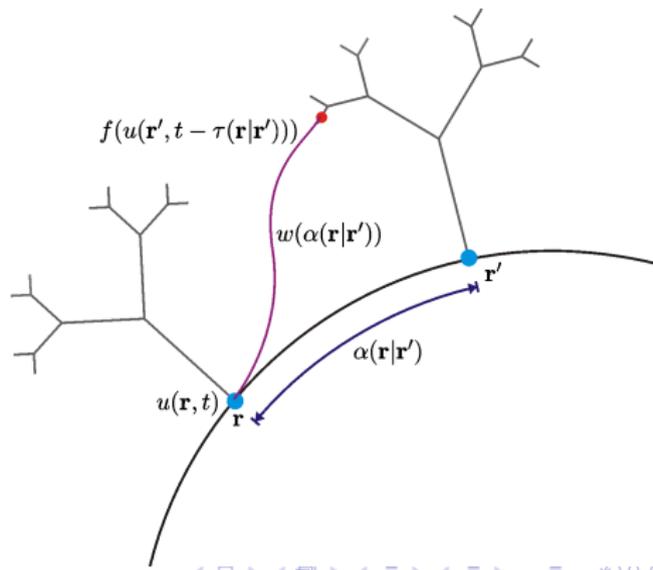
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Delays : $\tau(\mathbf{r}|\mathbf{r}') = \frac{\alpha(\mathbf{r}|\mathbf{r}')}{v} + \tau_0,$

where

- v finite speed of action potentials.
- τ_0 constant delay representing delays caused by synaptic processes.



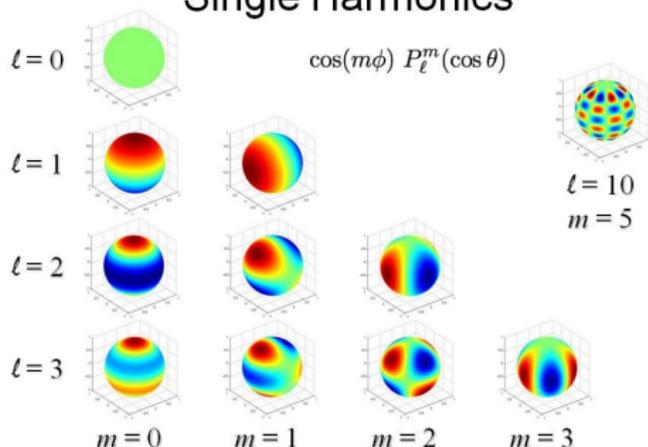
Spherical symmetry

Since we choose $w(\alpha(\mathbf{r}|\mathbf{r}'))$ to be $O(3)$ invariant we can write

$$w(\alpha(\mathbf{r}|\mathbf{r}')) = \sum_{n=0}^{\infty} w_n \sum_{m=-n}^n \overline{Y_n^m(\theta, \phi)} Y_n^m(\theta', \phi')$$

where $Y_n^m(\theta, \phi)$ are **Spherical Harmonics**. There are $2n + 1$ spherical harmonics of degree n .

Single Harmonics



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Here

$$w_n = 2\pi \int_0^\pi \sin \theta d\theta w(R\theta) P_n(\cos \theta).$$

Synaptic kernel $w(\alpha)$ is **balanced** if

$$W := w_0 = \int_{\Omega} w(\mathbf{r}_0|\mathbf{r}') d\mathbf{r}' = 0$$

where $\mathbf{r}_0 \in \Omega$.

Linear stability of homogeneous steady state

$$\frac{\partial u}{\partial t} = -u + \int_{\Omega} w(\mathbf{r}|\mathbf{r}')f(u(\mathbf{r}', t - \tau(\mathbf{r}|\mathbf{r}'))))d\mathbf{r}'$$

Homogeneous steady states \bar{u} satisfy

$$\bar{u} = Wf(\bar{u})$$

(so only one steady state $\bar{u} = 0$ when $W = 0$).

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Linearising about \bar{u} :

$$\frac{\partial u}{\partial t} = -u + \gamma \int_{\Omega} w(\mathbf{r}|\mathbf{r}')u(\mathbf{r}', t - \tau(\mathbf{r}|\mathbf{r}'))d\mathbf{r}'$$

where $\gamma = f'(\bar{u})$.

Linear stability analysis

Consider separable solutions: $u(\mathbf{r}, t) = \psi(\mathbf{r})e^{zt}$ where $\psi(\mathbf{r})$ satisfies

$$0 = \mathcal{L}_z \psi(\mathbf{r}) := (1 + z)\psi(\mathbf{r}) - \gamma \int_{\Omega} G(\alpha(\mathbf{r}|\mathbf{r}'); z)\psi(\mathbf{r}')d\mathbf{r}' \quad (1)$$

where

$$\begin{aligned} G(\alpha; z) &= w(\alpha) \exp(-z\tau_0 - z\alpha/v) \\ &= \sum_{n=0}^{\infty} G_n(z) \sum_{m=-n}^n \overline{Y_n^m(\theta, \phi)} Y_n^m(\theta', \phi') \end{aligned}$$

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Then (1) has solutions of the form $\psi(\mathbf{r}) = Y_n^m(\theta, \phi)$ if there exists eigenvalue λ such that

$$\mathcal{E}_n(\lambda) := 1 + \lambda - \gamma G_n(\lambda) = 0.$$

Linear stability analysis

- Homogeneous steady state is stable if $\text{Re } \lambda < 0$ for all n .
- **Dynamic instability** occurs if (under parameter variation) eigenvalues cross imaginary axis away from origin
 - Expect emergence of travelling or standing waves
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Remark Without delays ($\tau_0 = 0$ and $v \rightarrow \infty$) the eigenvalues are real and given explicitly by

$$\lambda_n = -1 + \gamma w_n.$$

i.e. Dynamic instabilities are not possible.

Dynamic instabilities

We look for dynamic instabilities:

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$$1 + i\omega = \gamma G_n(i\omega),$$

for different values of n . (Remember $G_n(z)$ depends on parameters $A_1, A_2, \sigma_1, \sigma_2, \nu, \tau_0$.)

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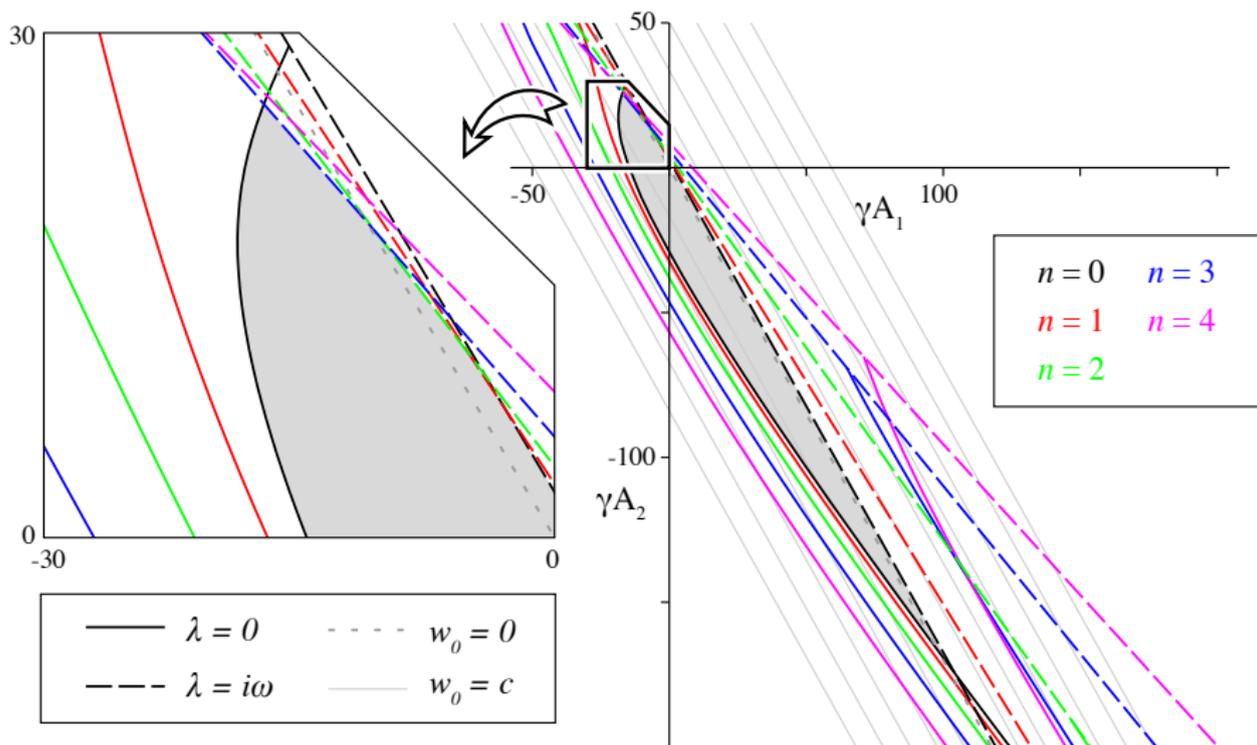
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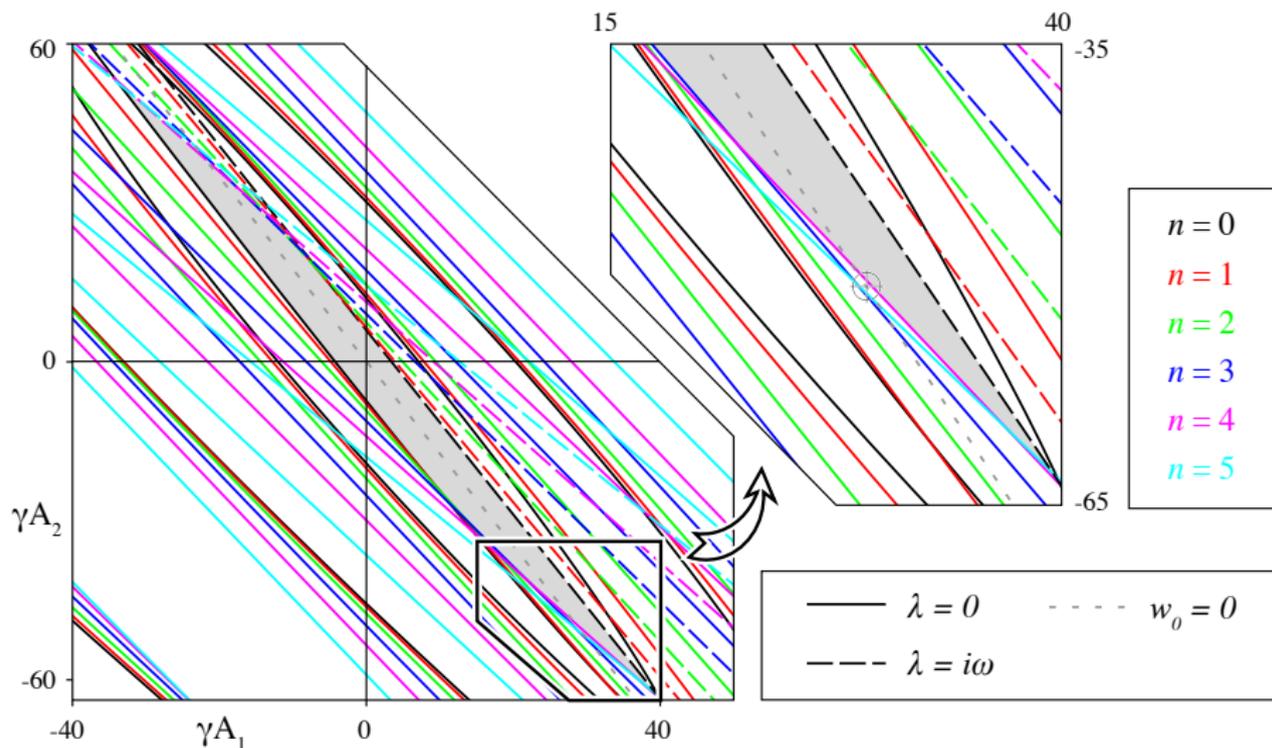
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- For fixed values of $\sigma_1, \sigma_2, \nu, \tau$ we can plot curves in A_1, A_2 plane where Hopf bifurcations of each mode can occur
- Can similarly find solutions of $1 = \gamma G_n(0)$ to locate static instabilities.

$$\tau_0 = 0$$



$$\tau_0 \neq 0$$



What kind of spatiotemporal patterns can exist?

From linear stability analysis we expect to excite a dynamic pattern of the form

$$u_{n_c}(\theta, \phi, t) = \sum_{m=-n_c}^{n_c} z_m e^{i\omega_c t} Y_{n_c}^m(\theta, \phi) + \text{cc},$$

where n_c and ω_c determined using spectral equation. Here the z_m are slowly varying amplitudes and $\mathbf{z} = (z_{-n_c}, \dots, z_{n_c}) \in \mathbb{C}^{2n_c+1}$.

- Near the bifurcation point we expect to see classes of solutions with symmetry that breaks the $O(3) \times S^1$ symmetry of the homogeneous steady state \bar{u} .
- **Equivariant bifurcation theory** can tell us about these solutions using symmetry arguments alone.

Symmetry arguments

- V_{n_c} = space of spherical harmonics of degree n_c and $u_{n_c} \in V_{n_c} \oplus V_{n_c}$.
 - The action of $O(3) \times S^1$ on u_{n_c} is determined by its action on $\mathbf{z} \in \mathbb{C}^{2n_c+1}$
- The amplitudes \mathbf{z} evolve according to $\dot{\mathbf{z}} = g(\mathbf{z})$ where

$$\gamma \cdot g(\mathbf{z}) = g(\gamma \cdot \mathbf{z}) \quad \text{for all } \gamma \in O(3). \quad (2)$$

- Taylor expansion of g to any given order also commutes with action of S^1 .
- We can use symmetry to compute form of g to cubic order. These **amplitude equations** contain a number of coefficients which are model dependent

Spatiotemporal symmetries of periodic solutions

- **Equivariant Hopf theorem** guarantees the existence of periodic solutions of $\dot{\mathbf{z}} = \mathbf{g}(\mathbf{z})$ with certain spatiotemporal symmetries (certain classes of subgroups of $O(3) \times S^1$)
 - $(\gamma, \psi) \in O(3) \times S^1$ is a spatiotemporal symmetry of a periodic solution $\mathbf{z}(\tau)$ if
$$(\gamma, \psi) \cdot \mathbf{z}(\tau) \equiv \gamma \cdot \mathbf{z}(\tau + \psi) = \mathbf{z}(\tau) \quad \text{for all } \tau. \quad (3)$$
 - The subgroups $\Sigma \subset O(3) \times S^1$ which satisfy the Equivariant Hopf theorem fix a two-dimensional subspace of $V_{n_c} \oplus V_{n_c}$, i.e. $\{\mathbf{z} \in \mathbb{C}^{2n_c+1} : \sigma \cdot \mathbf{z} = \mathbf{z} \text{ for all } \sigma \in \Sigma\}$ is two dimensional.
 - Which subgroups of spatiotemporal symmetries satisfy the Equivariant Hopf theorem depends on the value of n_c and have been determined for all values of n_c using group theoretic methods^{4,5}.

⁴M Golubitsky, I Stewart, and D G Schaeffer. *Singularities and Groups in Bifurcation Theory, Volume II*. Springer Verlag, 1988.

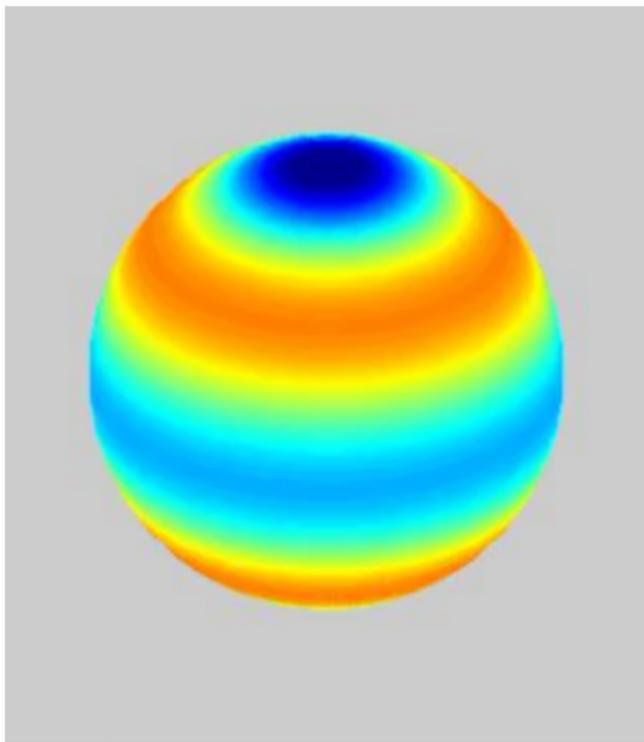
⁵R Sigrist. "Hopf bifurcation on a sphere". In: *Nonlinearity* 23 (2010), pp. 3199–3225.

Example $n_c = 4$

Table: The \mathbf{C} -axial subgroups of $O(3) \times S^1$ for the natural representations on $V_4 \oplus V_4$. Here $H = J \times \mathbb{Z}_2^c$.

Σ	J	K	$\alpha(H)$	$\text{Fix}(\Sigma)$
$\widetilde{\mathbf{O}(2)}$	$\mathbf{O}(2)$	$\mathbf{O}(2) \times \mathbb{Z}_2^c$	$\mathbb{1}$	$\{(0, 0, 0, 0, z, 0, 0, 0, 0)\}$
$\widetilde{\mathbf{O}}$	\mathbf{O}	$\mathbf{O} \times \mathbb{Z}_2^c$	$\mathbb{1}$	$\{(\sqrt{5}z, 0, 0, 0, \sqrt{14}z, 0, 0, 0, \sqrt{5}z)\}$
$\widetilde{\mathbf{T}}$	\mathbf{T}	$\mathbf{D}_2 \times \mathbb{Z}_2^c$	\mathbb{Z}_3	$\{(\sqrt{7}z, 0, \sqrt{12}iz, 0, -\sqrt{10}z, 0, \sqrt{12}iz, 0, \sqrt{7}z)\}$
$\widetilde{\mathbf{D}}_8$	\mathbf{D}_8	$\mathbf{D}_4 \times \mathbb{Z}_2^c$	\mathbb{Z}_2	$\{(z, 0, 0, 0, 0, 0, 0, 0, z)\}$
$\widetilde{\mathbf{D}}_6$	\mathbf{D}_6	$\mathbf{D}_3 \times \mathbb{Z}_2^c$	\mathbb{Z}_2	$\{(0, z, 0, 0, 0, 0, 0, z, 0)\}$
$\widetilde{\mathbf{D}}_4$	\mathbf{D}_4	$\mathbf{D}_2 \times \mathbb{Z}_2^c$	\mathbb{Z}_2	$\{(0, 0, z, 0, 0, 0, z, 0, 0)\}$
$\widetilde{\mathbf{SO}(2)}_4$	$\mathbf{SO}(2)$	$\mathbb{Z}_4 \times \mathbb{Z}_2^c$	S^1	$\{(z, 0, 0, 0, 0, 0, 0, 0, 0)\}$
$\widetilde{\mathbf{SO}(2)}_3$	$\mathbf{SO}(2)$	$\mathbb{Z}_3 \times \mathbb{Z}_2^c$	S^1	$\{(0, z, 0, 0, 0, 0, 0, 0, 0)\}$
$\widetilde{\mathbf{SO}(2)}_2$	$\mathbf{SO}(2)$	$\mathbb{Z}_2 \times \mathbb{Z}_2^c$	S^1	$\{(0, 0, z, 0, 0, 0, 0, 0, 0)\}$
$\widetilde{\mathbf{SO}(2)}_1$	$\mathbf{SO}(2)$	\mathbb{Z}_2^c	S^1	$\{(0, 0, 0, z, 0, 0, 0, 0, 0)\}$

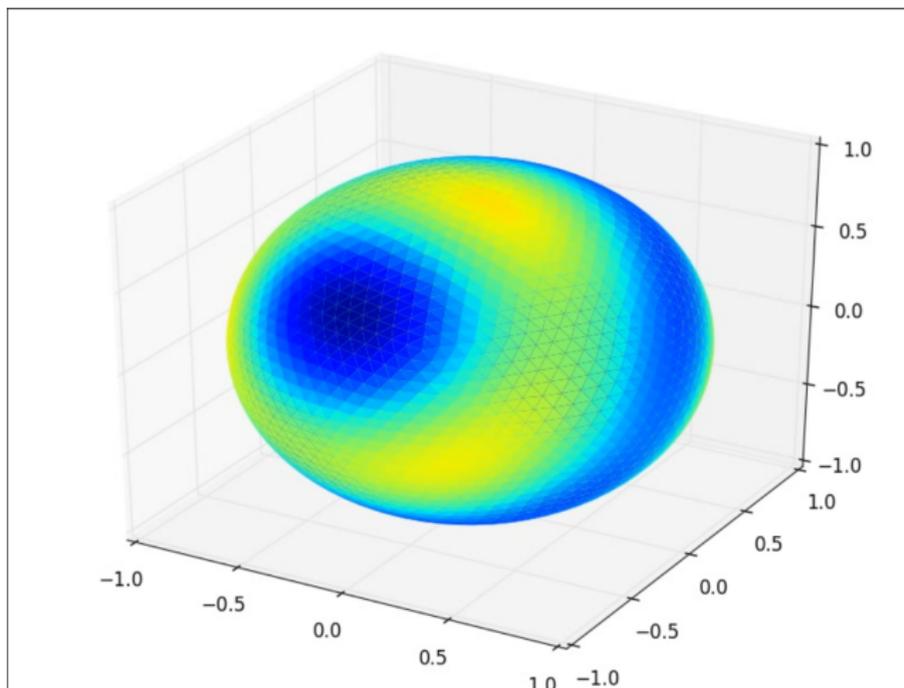
$n_c = 4$ standing and travelling wave solutions



An $n_c = 4$ periodic solution

- Other solutions to amplitude equations may exist (in addition to those guaranteed by Equivariant Hopf theorem)
- Using a bespoke numerical scheme we can simulate the (discretised) integro-differential equation near the $n_c = 4$ dynamic instability
 - New approach required to solve integro-differential equations with delays on large meshes

An $n_c = 4$ periodic solution



Stability

- Symmetry can tell you form of the amplitude equations to any given order and maximal solutions
 - For example if $n_c = 1$ modes become unstable at Hopf bifurcation then using equivariance, to cubic order amplitudes $\mathbf{z} = (z_{-1}, z_0, z_1)$ satisfy

$$\dot{z}_m = \mu z_m + A z_m |\mathbf{z}|^2 + B \hat{\mathbf{z}}_m (z_0^2 - 2z_{-1}z_1)$$

$$|\mathbf{z}|^2 = \sum_{p=-1}^1 |z_p|^2, \quad \hat{\mathbf{z}} = (-\bar{z}_1, \bar{z}_0, -\bar{z}_{-1}).$$

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- But which solutions are stable depends on values of coefficients - model dependent.
- **Weakly nonlinear analysis** can be used to determine values of coefficients for particular model.

Weakly nonlinear analysis

-

$$u_1(\theta, \phi, t) = \sum_{m=-n_c}^{n_c} z_m(\tau) e^{i\omega_c t} Y_{n_c}^m(\theta, \phi) + \text{cc},$$

where $\tau = \epsilon^2 t$.

- Consider perturbation expansion

$$u = \bar{u} + \epsilon u_1 + \epsilon^2 u_2 + \epsilon^3 u_3 + \dots$$

$$f(u) = f(\bar{u}) + \beta_1(u - \bar{u}) + \beta_2(u - \bar{u})^2 + \beta_3(u - \bar{u})^3 + \dots$$

where $\beta_1 = \beta_c + \epsilon^2 \delta$ and dynamic instability occurs at β_c (δ is a measure of distance from bifurcation).

- Get hierarchy of equations by balancing terms at each order in epsilon.
- Solvability condition (here at order ϵ^3) gives values of coefficients.

- For the example where $n_c = 1$

$$\mu = \frac{\delta(1 + i\omega_c)}{\beta_c}$$

$$A = \frac{(1 + i\omega_c)}{10\pi\beta_c} [2\beta_2^2 (5C_{0,0} + C_{2,0} + 3C_{2,2}) + 9\beta_3]$$

$$B = \frac{(1 + i\omega_c)}{20\pi\beta_c} [2\beta_2^2 (5C_{0,2} + 6C_{2,0} - 2C_{2,2}) + 9\beta_3]$$

where

$$C_{m,n} = \frac{G_m(in\omega_c)}{1 + in\omega_c - \beta_c G_m(in\omega_c)}.$$

More interesting solutions?

Direct numerical simulations suggest quasi-periodic behaviour is supported through interaction of modes 0 and 1. (See **spectral diagram** when $\tau_0 = 0$)

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- Complex conjugate eigenvalues cross through imaginary axis simultaneously.
- Two distinct (not rationally related) emergent frequencies.
- Excited pattern:

$$u_1(\theta, \phi, t) = (w_0 Y_0^0(\theta, \phi) e^{i\omega_0 t} + \text{cc}) + \sum_{m=0\pm 1} (z_m Y_1^m(\theta, \phi) e^{i\omega_1 t} + \text{cc}),$$

for slowly evolving w_0 and z_m with $m = 0, \pm 1$, and frequencies ω_0 and ω_1 .

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- Amplitude equations to cubic order (from symmetry):

$$\frac{dw_0}{d\tau} = \mu_1 w_0 + a_1 w_0 |w_0|^2 + a_2 w_0 |\mathbf{z}|^2,$$

$$\frac{dz_m}{d\tau} = \mu_2 z_m + b_1 z_m |\mathbf{z}|^2 + b_2 \hat{\mathbf{z}}_m (z_0^2 - 2z_{-1}z_1) + b_3 z_m |w_0|^2, \quad m = 0, \pm 1,$$

where $\hat{\mathbf{z}} = (-\bar{z}_1, \bar{z}_0, -\bar{z}_{-1})$.

- Values of the coefficients $\mu_1, a_1, a_2, \mu_2, b_1, b_2, b_3$ can be computed using weakly nonlinear analysis.

Secondary bifurcations

Secondary bifurcations to quasi-periodic solutions are possible:

- Similarly to Ermentrout and Cowan⁶ (two populations, no delays).
- Letting $z_1 = Re^{i\phi}$, $w_0 = re^{i\theta}$, $z_0 = z_{-1} = 0$, equations for (r, R) and (θ, ϕ) decouple:

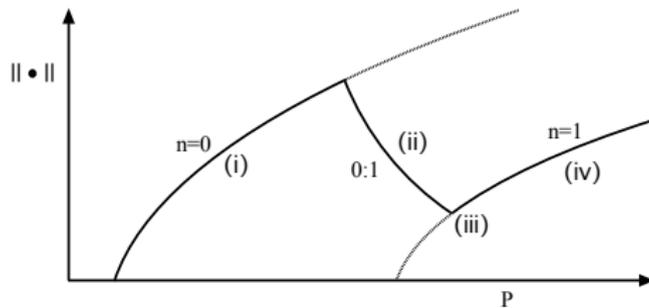
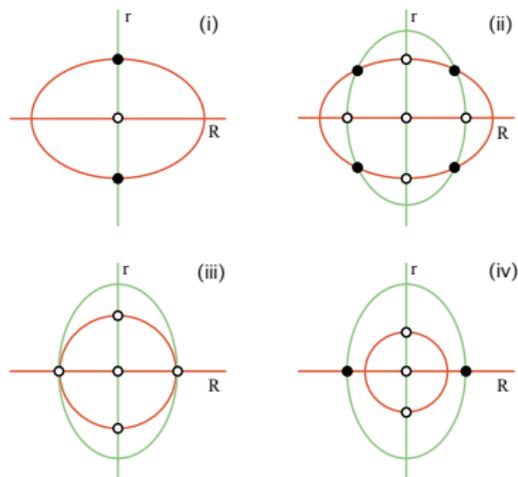
$$\begin{aligned}\frac{dr}{dt} &= r [\mu_1^R + a_1^R r^2 + a_2^R R^2], \\ \frac{dR}{dt} &= R [\mu_2^R + b_1^R R^2 + b_3^R r^2]\end{aligned}$$

where $\mu_i^R = \text{Re } \mu_i$, $a_i^R = \text{Re } a_i$, $b_i^R = \text{Re } b_i$

- Nullclines are r -axis, the R -axis, and a pair of ellipses (which only exist for certain values of coefficients).
- Suppose coefficients depend on a bifurcation parameter P then we could have ...

⁶G B Ermentrout and J D Cowan. "Secondary bifurcation in neuronal networks".
In: *SIAM Journal on Applied Mathematics* 39 (1980), pp. 323–340. 

Quasi-periodic solutions



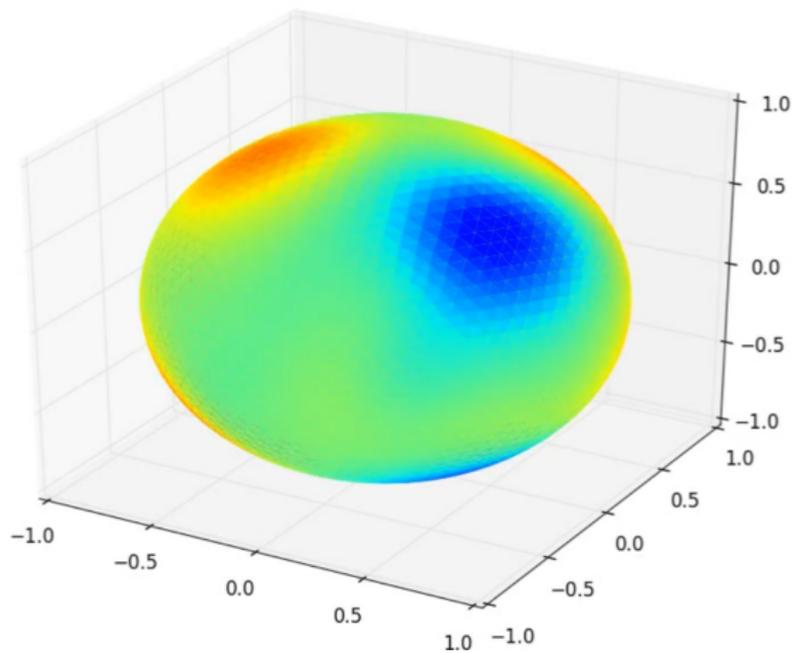
Quasi-periodic solutions

- Transition from a stable $n = 0$ mode to a stable $n = 1$ mode via an intermediate stable 0:1 mode.
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Quasi-periodic solutions

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- As noted by Ermentrout and Cowan, this would allow smooth transition from one frequency ($\sim \omega_0$) to another ($\sim \omega_1$),
 - May provide a mechanistic explanation for the gradual transition from tonic to clonic phases during an epileptic seizure.
 - Stage (i) - Small amplitude bulk oscillation (tonic phase).
 - Stage (ii) - Stable 0:1 quasi-periodic solution (tonic-clonic transition).
 - Stage (iv) - Stable $n = 1$ mode (full clonic phase).

A chaotic solution?



Summary and further work

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- Wide range of spatiotemporal states can be supported in neural models of Nunez type on a sphere with only simple representations for anatomical connectivity, axonal delays and population firing rates.
- Highlighted importance of delays in generating spatiotemporal patterned states.
- Looked at degenerate bifurcations allowing for quasi-periodic behaviour reminiscent of evolution of some epileptic seizures.
- More complex (chaotic?) solutions also found using bespoke numerical scheme.

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Further Work

- Numerical scheme not limited to spherical geometry - can also handle folded cortical structures.
- Localised states (working memory) for steep sigmoidal firing rate and Mexican-hat connectivity.

Thank you

Coming soon to arXiv

S Coombes, R Nicks, and S Visser. “Standing and travelling waves in a spherical brain model: the Nunez model revisited”. In: ()