Towards a policy improvement algorithm in continuous time

Saul Jacka, Warwick Statistics

Oslo 20 April, 2015



 The general problem

 The policy improvement algorithm (PIA)
 Setup

 Examples
 Examples

 Proofs
 Proofs

Problem: the optimal control problem: Given a filtered probability space Ω , (\mathcal{F}_t) , \mathcal{F} , \mathbb{P}) and a jointly continuous f, find for each x

$$V(x) \stackrel{\text{def}}{=} \sup_{\Pi \in \mathcal{A}_x} \mathbb{E}[\int_0^\tau f(X_t^{\Pi}, \Pi_t) dt + g(X_{\tau}^{\Pi}) \mathbb{1}_{(\tau < \infty)}]$$

where

(1) X takes value in some topological space S, τ is the first exit from some domain D in S, Π takes values in a (sequentially) compact space A and is adapted.

(2) For each $a \in A$ we assume that the constant process a is in each \mathcal{A}_x and that X^a is a strong Markov process with (martingale) infinitesimal generator L^a and domain \mathbf{D}^a . We assume that \mathbf{C} is a nonempty subset of $\bigcap_{a \in A} \mathbf{D}^a$ with the property that $L^a \phi(x)$ is jointly continuous in $(x, a) \in D \times A$ for each $\phi \in \mathbf{C}$.

(3) A_x consists of all those adapted processes Π such that there exists a unique adapted, right-continuous process X^{Π} with

- 1. $X_0^{\Pi} = x;$
- 2. for each $\phi \in \mathbf{C}$,

$$\phi(X_{t\wedge\tau}^{\Pi}) - \int_{0}^{t\wedge\tau} L^{\Pi_{s}} \phi(X_{s}^{\Pi}) ds \text{ is a martingale}; \qquad (1)$$

and defining J by

$$J(x,\Pi) = \int_0^\tau f(X_t^\Pi,\Pi_t) dt + g(X_\tau^\Pi) \mathbb{1}_{(\tau<\infty)},$$

we have

3.

$$\int_0^{t\wedge\tau} f(X^\Pi_t,\Pi_t)dt + g(X^\Pi_\tau)1_{(\tau<\infty)} \xrightarrow{L^1} J(x,\Pi).$$

We refer to elements of \mathcal{A}_{x} as controls.

- 1. Discounted infinite horizon problem. Here X^a is a killed Markov process with $S = D \cup \{\partial\}$ with ∂ an isolated cemtery state. Killing to ∂ is at rate α and τ is the death time of the process.
- 2. The finite horizon problem. Here we have Y^a a Markov process on S' with infinitesimal generator \mathcal{G} . τ is the time to the horizon Then $S = S' \times \mathbb{R}$ and $D = S' \times \mathbb{R}^{++}$, so if x = (y, T) then $X_t^a = (Y_t^a, T - t), \tau = T$ and $L^a = \mathcal{G} - \frac{\partial}{\partial t}$.

イロト イポト イヨト イヨト

The general problem	Policies and improvements
The policy improvement algorithm (PIA)	Improvement works
Examples	convergence of payoffs
Proofs	Convergence of policies

We define $\mathit{Markov}\ \mathit{policies}\ \mathsf{as}\ \mathsf{follows}:\ \pi\ \mathsf{is}\ \mathsf{a}\ \mathsf{Markov}\ \mathsf{policy}\ \mathsf{if}$

1. $\pi: S \rightarrow A$

and for each $x \in D$ there exists a unique (up to indistinguishability) X such that

2. $X_0 = x;$

3.
$$\Pi$$
 given by $\Pi_t = \pi(X_t)$ is in \mathcal{A}_x

4.
$$X^{\Pi} = X$$
.

Hereafter we denote such an X by X^{π} .

Given x and $\Pi \in A_x$ we define the *payoff*, $V^{\Pi}(x) = \mathbb{E}[J(x, \Pi)]$ and in a corresponding fashion for Markov policies π .

We say that a Markov policy is *improvable* if $V^{\pi} \in \mathbf{C}$ and denote the collection of improvable Markov policies by *I*.

A (2) > (

The general problem	Policies and improvements
The policy improvement algorithm (PIA)	Improvement works
Examples	convergence of payoffs
Proofs	Convergence of policies

If π is a Markov policy, we say that π' is an *improvement* of π if, 1. for each $x \in D$

$$\pi'(x) \in \arg \max_{a \in A} [L^a V^{\pi}(x) + f(x, a)]$$

i.e.

$$L^{\pi'(x)}V^{\pi}(x) + f(x,\pi'(x)) = \sup_{a} [L^{a}V^{\pi}(x) + f(x,a)],$$

and

2. π' is also a Markov policy.

∃ ⊳

The PIA works by defining a sequence of improvements and their associated payoffs: so π_{n+1} is the improvement of π_n .

Assumptions A

A1 There exists a non-empty subset I^* of I such that $\pi_0 \in I^*$ implies that $\pi_n \in I^*$ for each n (issue is whether $V^{\pi_n} \in \mathbf{C}$ and whether the sup is attained) and each π_n is continuous.

A2 For $\pi_0 \in I^*$,

$$V^{\pi_{n+1}}(X^{\pi_{n+1}}_{t\wedge\tau}) - V^{\pi_n}(X^{\pi_{n+1}}_{t\wedge\tau}) \xrightarrow{L^1} Z_x \geq 0 \text{ a.s. for each } x \in D.$$

The general problem	Policies and improvements
The policy improvement algorithm (PIA)	Improvement works
Examples	convergence of payoffs
Proofs	Convergence of policies

Theorem 1 Under Assumptions A1 and A2,

 $V^{\pi_{n+1}} \geq V^{\pi_n}$ for each n.

イロト イヨト イヨト イヨト

臣

Assume from now on that Assumptions A1 and A2 hold and that we have fixed a π_0 in I^* .

Assumptions **B**

A3 V is finite on D. A4 There is a subsequence $(n_k)_{k\geq 1}$ such that $L^{\pi_{n_k+1}}V^{\pi_{n_k}}(x)+f(x,\pi_{n_k+1}(x)) \xrightarrow{n\to\infty} 0$ uniformly in $x\in D$. A5 For each x, each $\Pi \in \mathcal{A}_x$ and each n

$$V^{\pi_n}(X^{\Pi}_{t\wedge au}) \stackrel{L^1}{
ightarrow} g(X^{\Pi}_{t\wedge au}) \mathbb{1}_{(au < \infty)}$$

イロト イポト イヨト イヨト

The general problem	Policies and improvements
The policy improvement algorithm (PIA)	Improvement works
Examples	convergence of payoffs
Proofs	Convergence of policies

Theorem 2 Under Assumptions A and B,

 $V^{\pi_n} \uparrow V.$

イロン イヨン イヨン イヨン

æ

The general problem The policy improvement algorithm (PIA) Examples Proofs Proofs Convergence of policies

Assume from now on that Assumptions A1 to A5 hold and that we have fixed a π_0 in I^* .

Assumptions C

A6 For any $\pi_0 \in I^*$, $(\pi_n)_{n \ge 1}$ is sequentially precompact in the sup norm topology.

A7 For any sequence $\pi_{n}\in I^{*}$, if

φ_n ∈ C for all n and φ_n →∞ φ pointwise
 L^{π_n}φ_n →∞ Q
 π_n →∞ π in sup norm

then

$$\phi \in \mathbf{C} \text{ and } L^{\pi} \phi = Q.$$

A8 For each x, each $\Pi \in \mathcal{A}_x$

$$V(X_{t\wedge au}^{\mathsf{\Pi}}) \stackrel{L^1}{\to} g(X_{t\wedge au}^{\mathsf{\Pi}}) \mathbb{1}_{(au < \infty)}$$

The general problem	Policies and improvements
The policy improvement algorithm (PIA)	Improvement works
Examples	convergence of payoffs
Proofs	Convergence of policies

Theorem 3 Under Assumptions A1 to A8, for any π_0 in I^* , there is a subsequence π_{n_k} such that $\pi_{n_k} \xrightarrow{n \to \infty} \pi^*$ and $V^{\pi^*} = V$

• 3 >

Discounted, infinite horizon controlled diffusion. Take $D = \mathbb{R}^d$ and $S = \mathbb{R}^d \cup \{\partial\}$ and $\mathbf{C} = C_b^2(\mathbb{R}^d, \mathbb{R})$, the bounded, C^2 , real-valued functions on \mathbb{R}^d . Suppose that X is a controlled (killed) Ito diffusion in \mathbb{R}^d so that

$$\mathcal{L}^{\boldsymbol{a}}\phi = rac{1}{2}\sigma(\cdot, \boldsymbol{a})^{T}\mathcal{H}\phi\sigma(\cdot, \boldsymbol{a}) + \mu(\cdot, \boldsymbol{a})^{T}\nabla\phi - \alpha(\cdot, \boldsymbol{a})\phi,$$

where $H\phi$ is the Hessian $\left(\frac{\partial^2 \phi}{\partial x_i \partial x_j}\right)$. Assume that

Assumption $\aleph 1 \ \sigma(x, a), \mu(x, a), \alpha(x, a)$ and f(x, a) are uniformly (in a) Lipschitz on compacts in \mathbb{R}^d and are continuous in a; α is bounded below by $\lambda > 0, \sigma$ is uniformly elliptic and f is uniformly bounded by M.

Assumption $\aleph 2$ Suppose that the control set A is a compact interval [a, b].

For every $h \in \mathbf{C}$ and $x \in \mathbb{R}^d$, let $I_h(x)$ denote an element of $\arg \max_{a \in A} [L^a h(x, a) + f(x, a)]$.

Assumption $\aleph 3$ If the sequence $(h_n) \in C^2$, if the sequence $(Hh_n)_{n\geq 1}$ is uniformly bounded on compacts, then we may choose the sequence I_{h_n} to be uniformly Lipschitz on compacts.

Remark This assumption is very strong. Neverthless, if σ is independent of a and bounded, $\mu = \mu_1(x) - ma$, $\alpha(x, a) = \alpha_1(x) + ca$ and $f(x, a) = f_1(x) - f_2(a)$ with $f_2 \in C^1$ and with strictly positive derivative on A, and assumptions $\aleph 1$ and $\aleph 2$ hold then $\aleph 3$ holds.

・ロト ・聞ト ・ヨト ・ヨト

Proposition 4

Under Assumptions $\aleph 1$ to $\aleph 3$, Assumptions A1 to A8 hold and the PIA converges for π_0 locally Lipschitz.

Proof Note: $L^{a}\phi$ is jointly continuous if ϕ is in **C** and (with the usual trick to deal with killing) (1) holds for any Π such that there is a solution to the killed equation

$$X_t^{\Pi} = (x + \int_0^t \sigma(X_s^{\Pi}, \Pi_s) dB_s + \int_0^t \mu(X_s^{\Pi}, \Pi_s) ds) \mathbb{1}_{(t < \tau)} + \partial \mathbb{1}_{(t \ge \tau)}.$$

and any locally Lipschitz π is a Markov policy (by strong uniqueness of the solution to the SDE).

- (A1) If π_0 is Lipschitz on compacts then by Assumption $\aleph 3$, A1 holds.
- (A3) Boundedness of V (A3) follows from the boundedness of f and the fact that α is bounded away from 0.
- (A6) Assumption ℵ3 implies that (π_n) are uniformly Lipschitz and hence sequentially precompact in the sup-norm topology (A6) by the Arzela-Ascoli Theorem.
- (A5) g = 0 and since α is bounded away from 0, for any Π , $X_t^{\Pi} \rightarrow \partial$. Now $V^n(\partial) = 0$ and so, by bounded convergence, (A5) holds:

$$V^{\pi_n}(X^{\mathsf{\Pi}}_{t\wedge au}) \stackrel{L^1}{
ightarrow} g(X^{\mathsf{\Pi}}_{t\wedge au}) \mathbb{1}_{(au < \infty)}.$$

(A2) Similarly, (A2) holds:

$$V^{\pi_{n+1}}(X^{n+1}_{t\wedge\tau}) - V^{\pi_n}(X^{n+1}_{t\wedge\tau}) \xrightarrow{L^1}_{\mathfrak{S} \to \mathfrak{S}} 0.$$

(A4) (A4) is tricky. Note that we have (A1), (A2) so by Theorem 1, V^n \uparrow . Moreover, since (A3) holds, $V^n \uparrow V^{lim}$. Now take a subsequence (n_k) such that $(\pi_{n_{\iota}}, \pi_{n_{\iota+1}}) \rightarrow (\pi^*, \tilde{\pi})$ uniformly on compacts. Then the corresponding σ etc. must also converge. Denote the limits by σ^* , $\tilde{\sigma}$ etc. Then (see Friedman [1]), $V^{lim} \in \mathbf{C}^2_{L}$ and $\nabla V^{n_k}, \nabla V^{n_{k+1}} \to \nabla V^{lim}$. HV^{n_k} . $HV^{n_{k+1}} \rightarrow HV^{lim}$ uniformly on compacts and $L^{\tilde{\pi}}V^{lim} + f(\cdot, \tilde{\pi}(\cdot)) = 0$. Now, from the convergence of the derivatives of V^{n_k} . $L^{\pi_{n_{k+1}}}V^{n_k} + f(\cdot, \pi_{n_{k+1}}(\cdot)) \rightarrow L^{\tilde{\pi}}V^{lim} + f(\cdot, \tilde{\pi}(\cdot)) = 0$ uniformly on compacts.

(A7) and (A8) From Friedman.

Finite horizon controlled diffusion.

This is very similar to the previous example if we add the requirement that g is Lipschitz and bounded.

Remark In both examples we need to prove that V is continuous before we can apply the usual pde arguments.

Lemma 4 Under Assumptions A1 and A2,

$$L^{\pi_n}V^{\pi_n}(x) + f(x,\pi_n(x)) = 0$$
 for all $x \in D$

Proof We know that

$$V^{\pi_n}(X^{\pi_n}_{t\wedge\tau}-\int_0^{t\wedge\tau}L^{\pi_n}V^{\pi_n}(X^{\pi_n}_s)ds$$

is a martingale and the ususal Markovian argument shows that therefore

$$\int_0^{t\wedge\tau}(L^{\pi_n}V^{\pi_n}+f(\cdot,\pi_n(\cdot))(X^{\pi_n}_s)ds=0.$$

The result then follows from continuity of $L^{\pi_n}V^{\pi_n} + f(\cdot, \pi_n(\cdot))$ and the right continuity of X^{π_n} .

Proof of Theorem 1 Take $\pi_0 \in I^*$ and $x \in D$ and define

$$S_t = (V^{\pi_{n+1}} - V^{\pi_n})(X^{\pi_n}_{t\wedge \tau}).$$

By assumption, $V^{\pi_{n+1}}$ and V^{π_n} are in **C** so

$$V^{\pi_k}(X_{t\wedge au}^{\pi_{n+1}}-\int_0^{t\wedge au}L^{\pi_{n+1}}V^{\pi_k}(X_s^{\pi_{n+1}})ds$$

is a martingale for k = n, n + 1. So,

$$S_t = (V^{\pi_{n+1}} - V^{\pi_n})(x) + M_{t \wedge \tau} + \int_0^{t \wedge \tau} (L^{\pi_{n+1}} V^{\pi_{n+1}} - L^{\pi_{n+1}} V^{\pi_n})(X_s^{\pi_{n+1}}) ds,$$

where M is a martingale. Thus

$$S_t = (V^{\pi_{n+1}} - V^{\pi_n})(x) + M_{t \wedge \tau} - \int_0^{t \wedge \tau} \sup_{a} [L^a V^{\pi_n} + f(\cdot, a)](X_s^{\pi_{n+1}}) ds,$$

L Dag

by Lemma 4 and the definition of π_{n+1}

Appealing to Lemma 4 again, the integrand is non-negative and hence S is a supermartingale. Taking expectations and letting $t \rightarrow \infty$ we obtain the result using A2.

イロト イポト イヨト イヨト

æ

Proof of Theorem 2

From Theorem 1 and A3, $V^{\pi_n} \uparrow V^{lim}$ for a suitable finite limit bounded above by V. Fix x and $\Pi \in \mathcal{A}_x$ and take the subsequence in A4. Set

$$S_t^k = (V^{\pi_{n_k}}(X_{t\wedge\tau}^{\Pi}) + \int_0^{t\wedge\tau} f(X_s^{\Pi},\Pi_s))ds,$$

It follows that there is a martingale M^k such that

$$S_{t}^{k} = S_{0}^{k} + M_{t\wedge\tau}^{k} + \int_{0}^{t\wedge\tau} [L^{\Pi_{s}}V^{\pi_{n_{k}}} + f(\cdot,\Pi_{s})](X_{s}^{\Pi})ds$$

$$\leq S_{0}^{k} + M_{t\wedge\tau}^{k} + \int_{0}^{t\wedge\tau} \max_{a} [L^{a}V^{\pi_{n_{k}}} + f(\cdot,a)](X_{s}^{\Pi})ds$$

$$= S_{0}^{k} + M_{t\wedge\tau}^{k} + \int_{0}^{t\wedge\tau} [L^{\pi_{n_{k}+1}}V^{\pi_{n_{k}}} + f(\cdot,\pi_{n_{k}+1}(\cdot))](X_{s}^{\Pi})ds$$

$$\mathbb{E}S_t^k \leq S_0^k + \mathbb{E}[\int_0^{t\wedge\tau} [L^{\pi_{n_k+1}}V^{\pi_{n_k}} + f(\cdot, \pi_{n_k+1}(\cdot))](X_s^{\Pi})ds]. \tag{2}$$

Letting $k \to \infty$ in (2) we obtain, by monotone convergence, that

$$\mathbb{E}[(V^{\textit{lim}}(X_{t\wedge au}^{\mathsf{\Pi}})+\int_{0}^{t\wedge au}f(X_{s}^{\mathsf{\Pi}},\mathsf{\Pi}_{s}))ds]\leq V^{\textit{lim}}(x).$$

Now by A5, since $V^{lim} \ge V^{\pi_{n_k}}$ for each k we get

$$\lim_t \inf \mathbb{E} V^{\textit{lim}}(X^{\Pi}_{t\wedge au}) \geq \mathbb{E} g(X^{\Pi}_{t\wedge au}) \mathbb{1}_{(au < \infty)},$$

and so $V^{lim} \ge V^{\Pi}$ for each $\Pi \in \mathcal{A}_x$ and so $V^{lim} \ge V$. However $V^{lim} \le V$ so we have equality

(日) (部) (注) (注) (注)

Proof of Theorem 3 From A5

$$V^{\pi_n}(X_{t\wedge \tau}^{\mathsf{\Pi}}) \xrightarrow{L^1} g(X_{t\wedge \tau}^{\mathsf{\Pi}}) \mathbb{1}_{(\tau < \infty)}.$$

uniformly in x and now take a subsequence, denoted (m_i) so that

$$\pi_{m_j} \to \pi^*.$$

By A7, $V \in \mathbf{C}$ and $L^{\pi^*}V + f(\cdot, \pi^*(\cdot)) = 0$ so, defining

$$M_{t\wedge au}^{j} \stackrel{def}{=} (V^{\pi^{*}}(X_{t\wedge au}^{\pi^{*}}) + \int_{0}^{t\wedge au} f((X_{s}^{\pi^{*}}, \pi^{*}(X_{s}^{\pi^{*}})) ds,$$

is a martingale. Thus, defining

$$S_t^j \stackrel{def}{=} (V^{\pi_{m_j}}(X_{t\wedge\tau}^{\pi^*}) + \int_0^{t\wedge\tau} f((X_s^{\pi^*}, \pi^*(X_s^{\pi^*}))ds,$$

イロト イポト イヨト イヨト

we have

$$S_{t}^{j} = V^{m^{j}}(X_{t\wedge\tau}^{\pi^{*}}) + \int_{0}^{t\wedge\tau} (L^{\pi^{*}}V^{\pi_{m_{j}}} + f(\cdot,\pi^{*}(\cdot))(X_{s}^{\pi^{*}})$$
(3)

Now for each t, $S_t^j \uparrow V(X_{t\wedge\tau}^{\pi^*}) + \int_0^{t\wedge\tau} f((X_s^{\pi^*}, \pi^*(X_s^{\pi^*}))ds)$, by A5, while the L^1 limit of the RHS of (3) is V(x) by A4. Letting $t \to \infty$ we obtain the result that $V^{\pi^*} = V$ by A8

A Friedman, *Partial Differential Equations of Parabolic Type*. Prentice-Hall, Englewood Cliffs, N.J., 1964.

・ロト ・ 同ト ・ ヨト ・ ヨト

æ