

# Heat Kernels in Graphs:

A Journey from **Random Walks** to **Geometry**, and Back

He Sun

University of Edinburgh

## Notation

---

Let  $G$  be an undirected  $d$ -regular graph with  $n$  vertices.

## Notation

---

Let  $G$  be an undirected  $d$ -regular graph with  $n$  vertices.

### Laplacian Matrix

The **normalised Laplacian matrix** of  $G$  is defined by

$$\mathcal{L} \triangleq \mathbf{I} - \frac{1}{d} \cdot \mathbf{A},$$

where  $\mathbf{A}$  is the adjacency matrix of  $G$ .

## Notation

Let  $G$  be an undirected  $d$ -regular graph with  $n$  vertices.

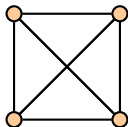
### Laplacian Matrix

The **normalised Laplacian matrix** of  $G$  is defined by

$$\mathcal{L} \triangleq \mathbf{I} - \frac{1}{d} \cdot \mathbf{A},$$

where  $\mathbf{A}$  is the adjacency matrix of  $G$ .

Example:



$$\mathcal{L}_G = \begin{pmatrix} 1 & -1/3 & -1/3 & -1/3 \\ -1/3 & 1 & -1/3 & -1/3 \\ -1/3 & -1/3 & 1 & -1/3 \\ -1/3 & -1/3 & -1/3 & 1 \end{pmatrix}$$

## Notation

Let  $G$  be an undirected  $d$ -regular graph with  $n$  vertices.

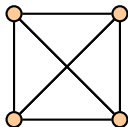
### Laplacian Matrix

The **normalised Laplacian matrix** of  $G$  is defined by

$$\mathcal{L} \triangleq \mathbf{I} - \frac{1}{d} \cdot \mathbf{A},$$

where  $\mathbf{A}$  is the adjacency matrix of  $G$ .

Example:



$$\mathcal{L}_G = \begin{pmatrix} 1 & -1/3 & -1/3 & -1/3 \\ -1/3 & 1 & -1/3 & -1/3 \\ -1/3 & -1/3 & 1 & -1/3 \\ -1/3 & -1/3 & -1/3 & 1 \end{pmatrix}$$

Matrix  $\mathcal{L}$  has eigenvalues  $0 = \lambda_1 \leq \dots \leq \lambda_n$  with corresponding eigenvectors

$$f_1, \dots, f_n.$$

## Heat Kernel: a Fundamental Solution of a PDE

---

Let  $\mathcal{M}$  be a compact Riemannian manifold, and

$$u : \mathcal{M} \times [0, \infty) \rightarrow \mathbb{R}$$

be a smooth function describing the temperature at a point in  $\mathcal{M}$  and time  $t$ .

## Heat Kernel: a Fundamental Solution of a PDE

Let  $\mathcal{M}$  be a compact Riemannian manifold, and

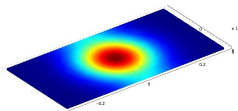
$$u : \mathcal{M} \times [0, \infty) \rightarrow \mathbb{R}$$

be a smooth function describing the temperature at a point in  $\mathcal{M}$  and time  $t$ .

### Heat Kernel

Let  $\mathcal{M}$  be a compact Riemannian manifold and  $\Delta$  the Laplacian operator. Then the heat kernel is the fundamental solution of the following PDE:

$$\frac{\partial u}{\partial t} + \Delta u = 0.$$



## Heat Kernel: a Fundamental Solution of a PDE

Let  $\mathcal{M}$  be a compact Riemannian manifold, and

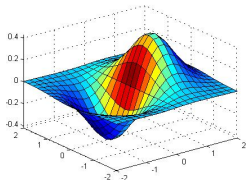
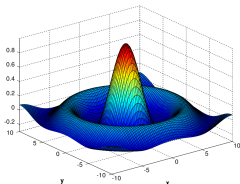
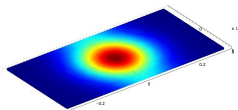
$$u : \mathcal{M} \times [0, \infty) \rightarrow \mathbb{R}$$

be a smooth function describing the temperature at a point in  $\mathcal{M}$  and time  $t$ .

### Heat Kernel

Let  $\mathcal{M}$  be a compact Riemannian manifold and  $\Delta$  the Laplacian operator. Then the heat kernel is the fundamental solution of the following PDE:

$$\frac{\partial u}{\partial t} + \Delta u = 0.$$





## Heat Kernel Defines a Continuous-Time Random Walk

### Heat Kernel in Graphs

When  $\Delta$  is the Laplacian matrix  $\mathcal{L}$  of graph  $G$ , for any  $t \geq 0$  the heat kernel of  $G$  can be written as

$$\mathbf{H}_t = e^{-t\mathcal{L}} = \sum_{k=0}^{\infty} \frac{t^k e^{-t}}{k!} \mathbf{P}^k,$$

where  $\mathbf{P}$  is the random walk matrix of  $G$ .

### Heat Kernel in Graphs

When  $\Delta$  is the Laplacian matrix  $\mathcal{L}$  of graph  $G$ , for any  $t \geq 0$  the heat kernel of  $G$  can be written as

$$\mathbf{H}_t = e^{-t\mathcal{L}} = \sum_{k=0}^{\infty} \frac{t^k e^{-t}}{k!} \mathbf{P}^k,$$

where  $\mathbf{P}$  is the random walk matrix of  $G$ .

Heat kernel defines a continuous-time random walk:

- Vertices choose a neighbour according to  $\mathbf{P}$ ;
- Jumps occur after **Poisson(1)** waiting times.

## Heat Kernel Defines a Continuous-Time Random Walk

### Heat Kernel in Graphs

When  $\Delta$  is the Laplacian matrix  $\mathcal{L}$  of graph  $G$ , for any  $t \geq 0$  the heat kernel of  $G$  can be written as

$$\mathbf{H}_t = e^{-t\mathcal{L}} = \sum_{k=0}^{\infty} \frac{t^k e^{-t}}{k!} \mathbf{P}^k,$$

where  $\mathbf{P}$  is the random walk matrix of  $G$ .

Heat kernel defines a continuous-time random walk:

- Vertices choose a neighbour according to  $\mathbf{P}$ ;
- Jumps occur after **Poisson(1)** waiting times.

**Continuous-time Random Walks  $\approx$  Discrete-time Random Walks!**

## Heat Kernel Defines a Continuous-Time Random Walk

### Heat Kernel in Graphs

When  $\Delta$  is the Laplacian matrix  $\mathcal{L}$  of graph  $G$ , for any  $t \geq 0$  the heat kernel of  $G$  can be written as

$$\mathbf{H}_t = e^{-t\mathcal{L}} = \sum_{k=0}^{\infty} \frac{t^k e^{-t}}{k!} \mathbf{P}^k,$$

where  $\mathbf{P}$  is the random walk matrix of  $G$ .

Heat kernel defines a continuous-time random walk:

- Vertices choose a neighbour according to  $\mathbf{P}$ ;
- Jumps occur after **Poisson(1)** waiting times.

### Continuous-time Random Walks $\approx$ Discrete-time Random Walks!

The heat kernel defines a semi-group, i.e.,

$$\mathbf{H}_{t+s} = \mathbf{H}_t \cdot \mathbf{H}_s, \forall t, s \geq 0 \quad \text{and} \quad \lim_{t \rightarrow 0} \mathbf{H}_t = \mathbf{I}.$$

## Heat Kernel in Graphs: Towards a Geometric Interpretation

---

For any time-step  $t \geq 0$ , define an embedding  $\psi_t : V \mapsto \mathbb{R}^n$  by

$$\psi_t(v) = \left( e^{-t\lambda_1} f_1(v), e^{-t\lambda_2} f_2(v), \dots, e^{-t\lambda_n} f_n(v) \right).$$

## Heat Kernel in Graphs: Towards a Geometric Interpretation

---

For any time-step  $t \geq 0$ , define an embedding  $\psi_t : V \mapsto \mathbb{R}^n$  by

$$\psi_t(v) = \left( e^{-t\lambda_1} f_1(v), e^{-t\lambda_2} f_2(v), \dots, e^{-t\lambda_n} f_n(v) \right).$$

Let the heat kernel distance between vertices  $u$  and  $v$  be

$$d_t(u, v) = \|\psi_t(u) - \psi_t(v)\|^2.$$

## Heat Kernel in Graphs: Towards a Geometric Interpretation

---

For any time-step  $t \geq 0$ , define an embedding  $\psi_t : V \mapsto \mathbb{R}^n$  by

$$\psi_t(v) = \left( e^{-t\lambda_1} f_1(v), e^{-t\lambda_2} f_2(v), \dots, e^{-t\lambda_n} f_n(v) \right).$$

Let the heat kernel distance between vertices  $u$  and  $v$  be

$$d_t(u, v) = \|\psi_t(u) - \psi_t(v)\|^2.$$

Heat kernel distance can be viewed as the derivative of the effective resistance of the same edge, i.e.,

$$\int_0^\infty d_t(u, v) dt = R(u, v).$$

## Heat Kernel in Graphs: Towards a Geometric Interpretation

---

For any time-step  $t \geq 0$ , define an embedding  $\psi_t : V \mapsto \mathbb{R}^n$  by

$$\psi_t(v) = \left( e^{-t\lambda_1} f_1(v), e^{-t\lambda_2} f_2(v), \dots, e^{-t\lambda_n} f_n(v) \right).$$

Let the heat kernel distance between vertices  $u$  and  $v$  be

$$d_t(u, v) = \|\psi_t(u) - \psi_t(v)\|^2.$$

Heat kernel distance can be viewed as the derivative of the effective resistance of the same edge, i.e.,

$$\int_0^\infty d_t(u, v) dt = R(u, v).$$

A simple calculation shows that  $d_t(u, v) = \sum_{w \in V} (\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$ .



## Heat Kernel Distance: From Geometry to Random Walks

---

Assume that  $t \approx$  local mixing time, which can will be found by binary search.

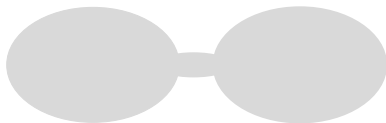
$$d_t(u, v) = \sum_{w \in V} (\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$$

## Heat Kernel Distance: From Geometry to Random Walks

---

Assume that  $t \approx$  local mixing time, which can will be found by binary search.

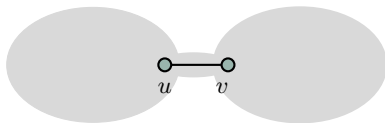
$$d_t(u, v) = \sum_{w \in V} (\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$$



## Heat Kernel Distance: From Geometry to Random Walks

Assume that  $t \approx$  local mixing time, which can will be found by binary search.

$$d_t(u, v) = \sum_{w \in V} (\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$$

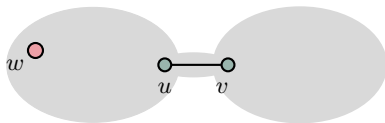


edge  $\{u, v\}$  is along a sparse cut

## Heat Kernel Distance: From Geometry to Random Walks

Assume that  $t \approx$  local mixing time, which can will be found by binary search.

$$d_t(u, v) = \sum_{w \in V} (\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$$

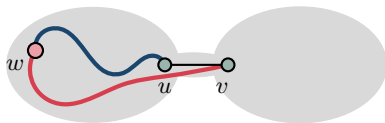


edge  $\{u, v\}$  is along a sparse cut

## Heat Kernel Distance: From Geometry to Random Walks

Assume that  $t \approx$  local mixing time, which can will be found by binary search.

$$d_t(u, v) = \sum_{w \in V} (\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$$



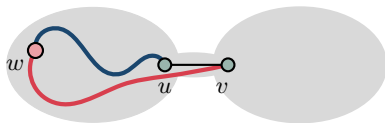
edge  $\{u, v\}$  is along a sparse cut

- One of the two walks needs to go across a sparse cut.

## Heat Kernel Distance: From Geometry to Random Walks

Assume that  $t \approx$  local mixing time, which can will be found by binary search.

$$d_t(u, v) = \sum_{w \in V} (\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$$



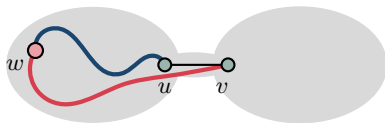
edge  $\{u, v\}$  is along a sparse cut

- One of the two walks needs to go across a sparse cut.
- For any vertex  $w$ , the value of  $(\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$  is big.

## Heat Kernel Distance: From Geometry to Random Walks

Assume that  $t \approx$  local mixing time, which can will be found by binary search.

$$d_t(u, v) = \sum_{w \in V} (\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$$



edge  $\{u, v\}$  is along a sparse cut

- One of the two walks needs to go across a sparse cut.
- For any vertex  $w$ , the value of  $(\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$  is big.
- Hence,  $d_t(u, v)$  is big.

## Heat Kernel Distance: From Geometry to Random Walks

Assume that  $t \approx$  local mixing time, which can will be found by binary search.

$$d_t(u, v) = \sum_{w \in V} (\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$$



edge  $\{u, v\}$  is along a sparse cut

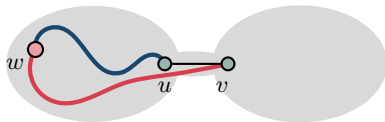
- One of the two walks needs to go across a sparse cut.
- For any vertex  $w$ , the value of  $(\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$  is big.
- Hence,  $d_t(u, v)$  is big.



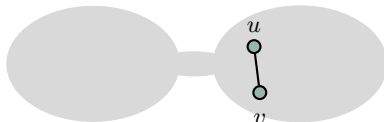
## Heat Kernel Distance: From Geometry to Random Walks

Assume that  $t \approx$  local mixing time, which can will be found by binary search.

$$d_t(u, v) = \sum_{w \in V} (\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$$



edge  $\{u, v\}$  is along a sparse cut



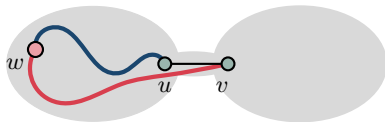
edge  $\{u, v\}$  is at one side of a sparse cut

- One of the two walks needs to go across a sparse cut.
- For any vertex  $w$ , the value of  $(\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$  is big.
- Hence,  $d_t(u, v)$  is big.

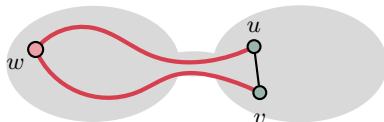
## Heat Kernel Distance: From Geometry to Random Walks

Assume that  $t \approx$  local mixing time, which can will be found by binary search.

$$d_t(u, v) = \sum_{w \in V} (\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$$



edge  $\{u, v\}$  is along a sparse cut



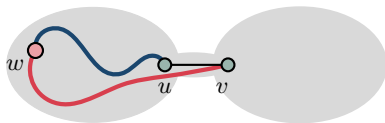
edge  $\{u, v\}$  is at one side of a sparse cut

- One of the two walks needs to go across a sparse cut.
- For any vertex  $w$ , the value of  $(\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$  is big.
- Hence,  $d_t(u, v)$  is big.

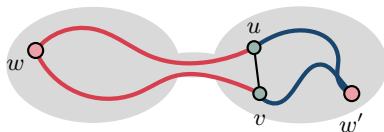
## Heat Kernel Distance: From Geometry to Random Walks

Assume that  $t \approx$  local mixing time, which can will be found by binary search.

$$d_t(u, v) = \sum_{w \in V} (\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$$



edge  $\{u, v\}$  is along a sparse cut



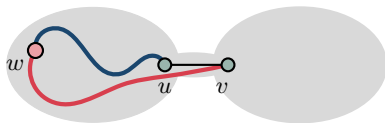
edge  $\{u, v\}$  is at one side of a sparse cut

- One of the two walks needs to go across a sparse cut.
- For any vertex  $w$ , the value of  $(\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$  is big.
- Hence,  $d_t(u, v)$  is big.

## Heat Kernel Distance: From Geometry to Random Walks

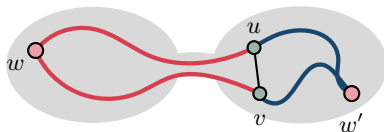
Assume that  $t \approx$  local mixing time, which can will be found by binary search.

$$d_t(u, v) = \sum_{w \in V} (\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$$



edge  $\{u, v\}$  is along a sparse cut

- One of the two walks needs to go across a sparse cut.
- For any vertex  $w$ , the value of  $(\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$  is big.
- Hence,  $d_t(u, v)$  is big.



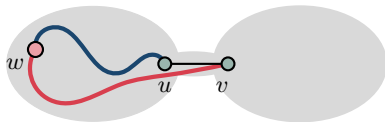
edge  $\{u, v\}$  is at one side of a sparse cut

- The values of two  $\mathbf{H}_t(w, \cdot)$ s are close to each other.

## Heat Kernel Distance: From Geometry to Random Walks

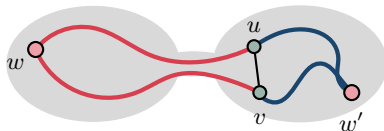
Assume that  $t \approx$  local mixing time, which can will be found by binary search.

$$d_t(u, v) = \sum_{w \in V} (\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$$



edge  $\{u, v\}$  is along a sparse cut

- One of the two walks needs to go across a sparse cut.
- For any vertex  $w$ , the value of  $(\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$  is big.
- Hence,  $d_t(u, v)$  is big.



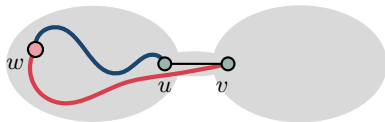
edge  $\{u, v\}$  is at one side of a sparse cut

- The values of two  $\mathbf{H}_t(w, \cdot)$ s are close to each other.
- Hence,  $(\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$  is small for any vertex  $w$ .

## Heat Kernel Distance: From Geometry to Random Walks

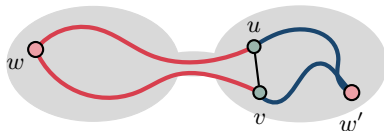
Assume that  $t \approx$  local mixing time, which can will be found by binary search.

$$d_t(u, v) = \sum_{w \in V} (\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$$



edge  $\{u, v\}$  is along a sparse cut

- One of the two walks needs to go across a sparse cut.
- For any vertex  $w$ , the value of  $(\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$  is big.
- Hence,  $d_t(u, v)$  is big.



edge  $\{u, v\}$  is at one side of a sparse cut

- The values of two  $\mathbf{H}_t(w, \cdot)$ s are close to each other.
- Hence,  $(\mathbf{H}_t(w, u) - \mathbf{H}_t(w, v))^2$  is small for any vertex  $w$ .
- Hence,  $d_t(u, v)$  is small.

## Key Questions

---

- Are our intuitions based on random walks correct?

## Key Questions

---

- Are our intuitions based on random walks correct?
- How do we apply these intuitions to design algorithms?



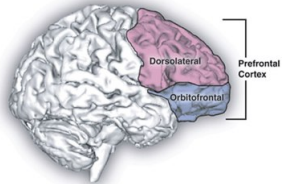
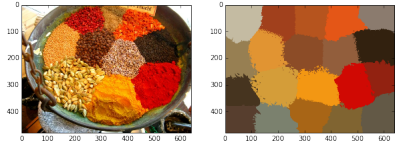
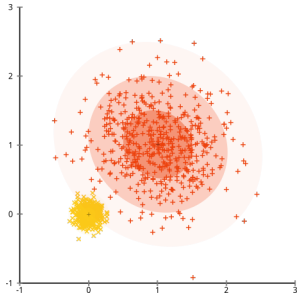
## Key Questions

---

- Are our intuitions based on random walks correct?
- How do we apply these intuitions to design algorithms?
- Do heat kernels give us an entirely new technique to design algorithms for large datasets?

# Graph Clustering

## Applications in clustering:



## Graph Conductance

---

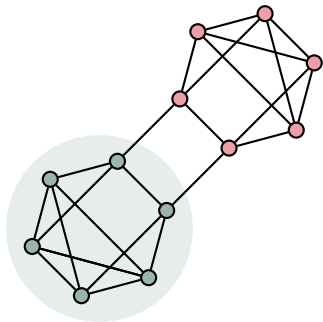
The conductance of a set  $S$  is defined by

$$\phi_G(S) \triangleq \frac{|E(S, V \setminus S)|}{d \cdot |S|}.$$

## Graph Conductance

The conductance of a set  $S$  is defined by

$$\phi_G(S) \triangleq \frac{|E(S, V \setminus S)|}{d \cdot |S|}.$$



$$\phi_G(S) = \frac{2}{4 \cdot 6} = \frac{1}{12}$$

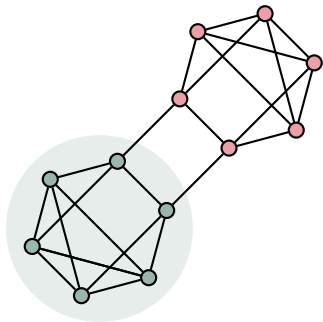
## Graph Conductance

The conductance of a set  $S$  is defined by

$$\phi_G(S) \triangleq \frac{|E(S, V \setminus S)|}{d \cdot |S|}.$$

The conductance of a graph  $G$  is defined by

$$\phi_G \triangleq \min_{S: |S| \leq |V|/2} \phi_G(S).$$



$$\phi_G(S) = \frac{2}{4 \cdot 6} = \frac{1}{12}$$

## Graph Conductance

The conductance of a set  $S$  is defined by

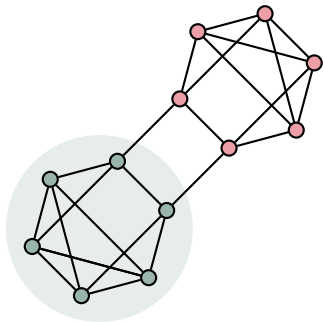
$$\phi_G(S) \triangleq \frac{|E(S, V \setminus S)|}{d \cdot |S|}.$$

The conductance of a graph  $G$  is defined by

$$\phi_G \triangleq \min_{S: |S| \leq |V|/2} \phi_G(S).$$

**Cheeger's Inequality**

$$\frac{\lambda_2}{2} \leq \phi_G \leq \sqrt{2\lambda_2}.$$

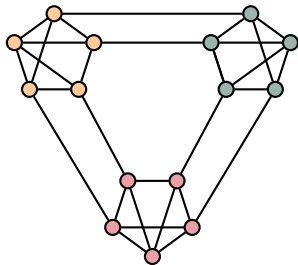


$$\phi_G(S) = \frac{2}{4 \cdot 6} = \frac{1}{12}$$

## $k$ -Way Expansion

The  $k$ -way expansion constant is defined by

$$\rho(k) = \min_{\text{partition } A_1, \dots, A_k} \max_{1 \leq i \leq k} \phi_G(A_i).$$



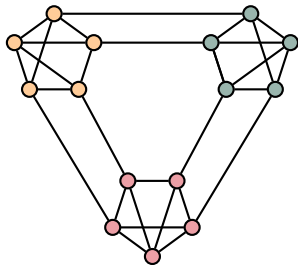
## $k$ -Way Expansion

The  $k$ -way expansion constant is defined by

$$\rho(k) = \min_{\text{partition } A_1, \dots, A_k} \max_{1 \leq i \leq k} \phi_G(A_i).$$

Higher-Order Cheeger's Inequality

$$\frac{\lambda_k}{2} \leq \rho(k) \leq O(k^3) \sqrt{\lambda_k}.$$





## $k$ -Way Expansion

The  $k$ -way expansion constant is defined by

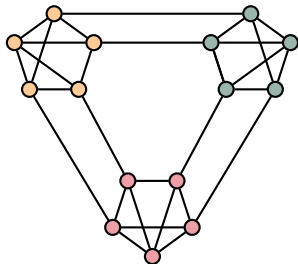
$$\rho(k) = \min_{\text{partition } A_1, \dots, A_k} \max_{1 \leq i \leq k} \phi_G(A_i).$$

Higher-Order Cheeger's Inequality

$$\frac{\lambda_k}{2} \leq \rho(k) \leq O(k^3) \sqrt{\lambda_k}.$$

A large gap between  $\lambda_{k+1}$  and  $\rho(k)$  implies that

- existence of a  $k$ -way partition with bounded  $\rho(k)$ .



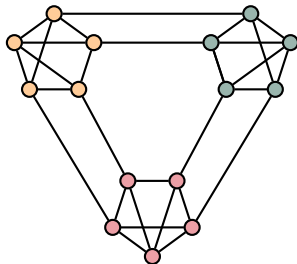
## $k$ -Way Expansion

The  $k$ -way expansion constant is defined by

$$\rho(k) = \min_{\text{partition } A_1, \dots, A_k} \max_{1 \leq i \leq k} \phi_G(A_i).$$

Higher-Order Cheeger's Inequality

$$\frac{\lambda_k}{2} \leq \rho(k) \leq O(k^3) \sqrt{\lambda_k}.$$



A large gap between  $\lambda_{k+1}$  and  $\rho(k)$  implies that

- existence of a  $k$ -way partition with bounded  $\rho(k)$ .
- any  $(k + 1)$ -way partition contains a set with conductance at least  $\lambda_{k+1}/2$ .

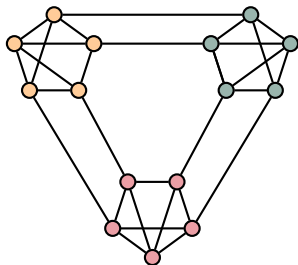
## $k$ -Way Expansion

The  $k$ -way expansion constant is defined by

$$\rho(k) = \min_{\text{partition } A_1, \dots, A_k} \max_{1 \leq i \leq k} \phi_G(A_i).$$

Higher-Order Cheeger's Inequality

$$\frac{\lambda_k}{2} \leq \rho(k) \leq O(k^3) \sqrt{\lambda_k}.$$



A large gap between  $\lambda_{k+1}$  and  $\rho(k)$  implies that

- existence of a  $k$ -way partition with bounded  $\rho(k)$ .
- any  $(k + 1)$ -way partition contains a set with conductance at least  $\lambda_{k+1}/2$ .
- Graph  $G$  has exactly  $k$  clusters.

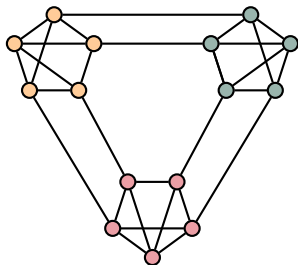
## $k$ -Way Expansion

The  $k$ -way expansion constant is defined by

$$\rho(k) = \min_{\text{partition } A_1, \dots, A_k} \max_{1 \leq i \leq k} \phi_G(A_i).$$

Higher-Order Cheeger's Inequality

$$\frac{\lambda_k}{2} \leq \rho(k) \leq O(k^3) \sqrt{\lambda_k}.$$



A large gap between  $\lambda_{k+1}$  and  $\rho(k)$  implies that

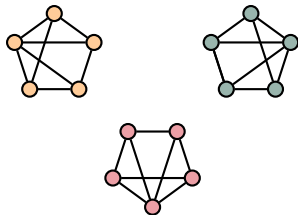
- existence of a  $k$ -way partition with bounded  $\rho(k)$ .
- any  $(k + 1)$ -way partition contains a set with conductance at least  $\lambda_{k+1}/2$ .
- Graph  $G$  has exactly  $k$  clusters.

The key parameter:  $\Upsilon \triangleq \frac{\lambda_{k+1}}{\rho(k)}.$

## The Structure Theorem

---

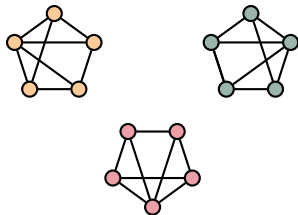
Let  $G$  be a  $d$ -regular graph with  $k$  disjoint components  $S_1, \dots, S_k$ .



## The Structure Theorem

Let  $G$  be a  $d$ -regular graph with  $k$  disjoint components  $S_1, \dots, S_k$ . For any  $1 \leq i \leq k$  let

$$\chi_i(v) = \begin{cases} 1 & \text{if } v \in S_i, \\ 0 & \text{otherwise.} \end{cases}$$



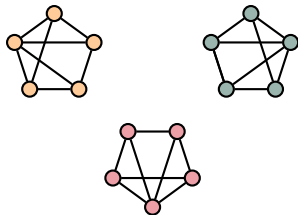
## The Structure Theorem

Let  $G$  be a  $d$ -regular graph with  $k$  disjoint components  $S_1, \dots, S_k$ . For any  $1 \leq i \leq k$  let

$$\chi_i(v) = \begin{cases} 1 & \text{if } v \in S_i, \\ 0 & \text{otherwise.} \end{cases}$$

Then

$$\text{span} \{f_1, \dots, f_k\} = \text{span} \{\chi_1, \dots, \chi_k\}.$$



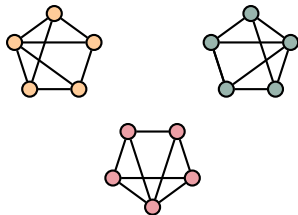
## The Structure Theorem

Let  $G$  be a  $d$ -regular graph with  $k$  disjoint components  $S_1, \dots, S_k$ . For any  $1 \leq i \leq k$  let

$$\chi_i(v) = \begin{cases} 1 & \text{if } v \in S_i, \\ 0 & \text{otherwise.} \end{cases}$$

Then

$$\text{span} \{f_1, \dots, f_k\} = \text{span} \{\chi_1, \dots, \chi_k\}.$$



Lemma (Peng-S.-Zanetti, 2017)

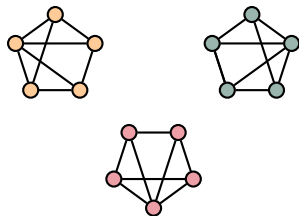
$\Upsilon = \Omega(k)$  implies that  $\text{span} \{f_1, \dots, f_k\} \approx \text{span} \{\chi_1, \dots, \chi_k\}$ .



## The Structure Theorem

Let  $G$  be a  $d$ -regular graph with  $k$  disjoint components  $S_1, \dots, S_k$ . For any  $1 \leq i \leq k$  let

$$\chi_i(v) = \begin{cases} 1 & \text{if } v \in S_i, \\ 0 & \text{otherwise.} \end{cases}$$



Then

$$\text{span} \{f_1, \dots, f_k\} = \text{span} \{\chi_1, \dots, \chi_k\}.$$

Lemma (Peng-S.-Zanetti, 2017)

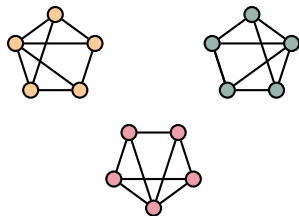
$\Upsilon = \Omega(k)$  implies that  $\text{span} \{f_1, \dots, f_k\} \approx \text{span} \{\chi_1, \dots, \chi_k\}$ .

Define  $F(v) = (f_1(v), \dots, f_k(v))$ .

## The Structure Theorem

Let  $G$  be a  $d$ -regular graph with  $k$  disjoint components  $S_1, \dots, S_k$ . For any  $1 \leq i \leq k$  let

$$\chi_i(v) = \begin{cases} 1 & \text{if } v \in S_i, \\ 0 & \text{otherwise.} \end{cases}$$



Then

$$\text{span} \{f_1, \dots, f_k\} = \text{span} \{\chi_1, \dots, \chi_k\}.$$

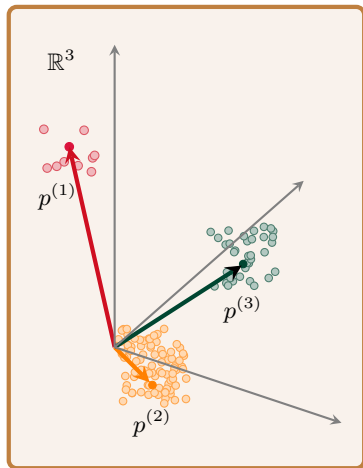
Lemma (Peng-S.-Zanetti, 2017)

$\Upsilon = \Omega(k)$  implies that  $\text{span} \{f_1, \dots, f_k\} \approx \text{span} \{\chi_1, \dots, \chi_k\}$ .

Define  $F(v) = (f_1(v), \dots, f_k(v))$ .

There are points  $p^{(1)}, \dots, p^{(k)}$ , s.t. cluster  $S_i$  is concentrated around  $p^{(i)}$ .

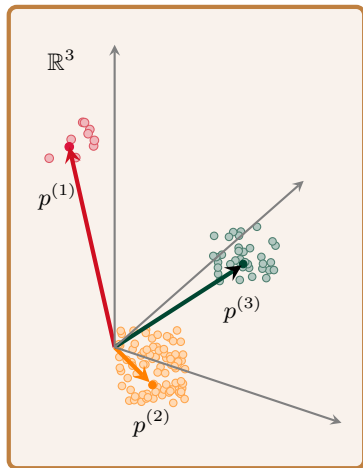
## Corollaries of the Structure Theorem



$$\sum_{i=1}^k \sum_{u \in S_i} \|F(u) - p^{(i)}\|^2 \leq k^2/\Upsilon.$$

Points from  $S_i$  concentrate around  $p^{(i)}$ s.

## Corollaries of the Structure Theorem



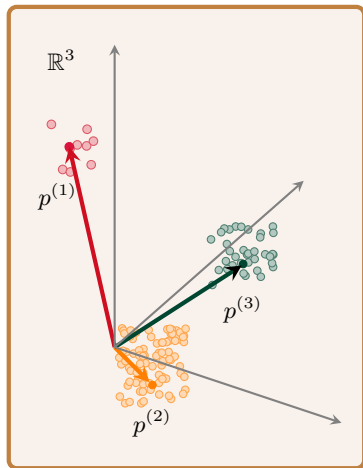
$$\sum_{i=1}^k \sum_{u \in S_i} \|F(u) - p^{(i)}\|^2 \leq k^2 / \Upsilon.$$

Points from  $S_i$  concentrate around  $p^{(i)}$ .

$$\|p^{(i)}\|^2 \in \left( \frac{9}{10}, \frac{11}{10} \right) \cdot \frac{1}{|S_i|}$$

“Bigger” clusters are closer to the origin.

## Corollaries of the Structure Theorem



$$\sum_{i=1}^k \sum_{u \in S_i} \|F(u) - p^{(i)}\|^2 \leq k^2/\Upsilon.$$

Points from  $S_i$  concentrate around  $p^{(i)}$ .

$$\|p^{(i)}\|^2 \in \left(\frac{9}{10}, \frac{11}{10}\right) \cdot \frac{1}{|S_i|}$$

“Bigger” clusters are closer to the origin.

$$\|p^{(i)} - p^{(j)}\|^2 \geq \frac{1}{k \min\{|S_i|, |S_j|\}}$$

Distance between different clusters inversely  $\approx$  the smaller cluster.

## A Simple Algorithm For Graph Clustering

---

**ASSUME** we know the pairwise distances of the points for free!

## A Simple Algorithm For Graph Clustering

**ASSUME** we know the pairwise distances of the points for free!

1. Obtain a set  $C$  of candidate centres.

Algorithm

```
for  $i = 1$  to  $K = \Theta(k \log k)$  do  
  set  $c_i = v$  with prob. proportional to  $\|F(v)\|^2$ .  
return  $C \triangleq \{c_1, \dots, c_K\}$ .
```

## A Simple Algorithm For Graph Clustering

**ASSUME** we know the pairwise distances of the points for free!

1. Obtain a set  $C$  of candidate centres.

Algorithm

```
for  $i = 1$  to  $K = \Theta(k \log k)$  do  
  set  $c_i = v$  with prob. proportional to  $\|F(v)\|^2$ .  
return  $C \triangleq \{c_1, \dots, c_K\}$ .
```

*With const. prob., each  $S_i$  has at least one vertex sampled.*



## A Simple Algorithm For Graph Clustering

**ASSUME** we know the pairwise distances of the points for free!

1. Obtain a set  $C$  of candidate centres.

Algorithm

```
for  $i = 1$  to  $K = \Theta(k \log k)$  do  
  set  $c_i = v$  with prob. proportional to  $\|F(v)\|^2$ .  
return  $C \triangleq \{c_1, \dots, c_K\}$ .
```

*With const. prob., each  $S_i$  has at least one vertex sampled.*

2. Delete points in  $C$  “close” to each other, until  $|C| = k$ .

## A Simple Algorithm For Graph Clustering

**ASSUME** we know the pairwise distances of the points for free!

1. Obtain a set  $C$  of candidate centres.

Algorithm

```
for  $i = 1$  to  $K = \Theta(k \log k)$  do
  set  $c_i = v$  with prob. proportional to  $\|F(v)\|^2$ .
return  $C \triangleq \{c_1, \dots, c_K\}$ .
```

*With const. prob., each  $S_i$  has at least one vertex sampled.*

2. Delete points in  $C$  “close” to each other, until  $|C| = k$ .

*With const. prob., each  $S_i$  has exactly one vertex remaining in  $C$ .*

## A Simple Algorithm For Graph Clustering

**ASSUME** we know the pairwise distances of the points for free!

1. Obtain a set  $C$  of candidate centres.

Algorithm

```
for  $i = 1$  to  $K = \Theta(k \log k)$  do
  set  $c_i = v$  with prob. proportional to  $\|F(v)\|^2$ .
return  $C \triangleq \{c_1, \dots, c_K\}$ .
```

*With const. prob., each  $S_i$  has at least one vertex sampled.*

2. Delete points in  $C$  “close” to each other, until  $|C| = k$ .

*With const. prob., each  $S_i$  has exactly one vertex remaining in  $C$ .*

3. The other  $n - k$  vertices find their closest neighbours in  $C$ .

## A Simple Algorithm For Graph Clustering

**ASSUME** we know the pairwise distances of the points for free!

1. Obtain a set  $C$  of candidate centres.

Algorithm

```
for  $i = 1$  to  $K = \Theta(k \log k)$  do
  set  $c_i = v$  with prob. proportional to  $\|F(v)\|^2$ .
return  $C \triangleq \{c_1, \dots, c_K\}$ .
```

*With const. prob., each  $S_i$  has at least one vertex sampled.*

2. Delete points in  $C$  “close” to each other, until  $|C| = k$ .

*With const. prob., each  $S_i$  has exactly one vertex remaining in  $C$ .*

3. The other  $n - k$  vertices find their closest neighbours in  $C$ .

*apply approximate nearest neighbour data structures.*

## A Simple Algorithm For Graph Clustering

**ASSUME** we know the pairwise distances of the points for free!

1. Obtain a set  $C$  of candidate centres.

Algorithm

```
for  $i = 1$  to  $K = \Theta(k \log k)$  do
  set  $c_i = v$  with prob. proportional to  $\|F(v)\|^2$ .
return  $C \triangleq \{c_1, \dots, c_K\}$ .
```

*With const. prob., each  $S_i$  has at least one vertex sampled.*

2. Delete points in  $C$  “close” to each other, until  $|C| = k$ .

*With const. prob., each  $S_i$  has exactly one vertex remaining in  $C$ .*

3. The other  $n - k$  vertices find their closest neighbours in  $C$ .

*apply approximate nearest neighbour data structures.*

**Runtime is  $O(n \cdot \text{poly} \log n)$ , even for a large value of  $k$ !**

## Obtaining the Pairwise Distances via Heat Kernels

---

Recall the two embeddings discussed so far:

- $F(v) = (f_1(v), \dots, f_k(v))$
- $\psi_t(v) = (e^{-t\lambda_1} f_1(v), \dots, e^{-t\lambda_n} f_n(v))$

## Obtaining the Pairwise Distances via Heat Kernels

Recall the two embeddings discussed so far:

- $F(v) = (f_1(v), \dots, f_k(v))$
- $\psi_t(v) = (e^{-t\lambda_1} f_1(v), \dots, e^{-t\lambda_n} f_n(v))$

**Lemma (Peng-S.-Zanetti, 2017)**

We can compute in  $O(nd \cdot \log^{10} n)$  time an embedding such that, with high probability, it holds that

$$(1 - \varepsilon) \|F(u) - F(v)\|^2 \leq \|\psi_t(u) - \psi_t(v)\|^2 \leq \|F(u) - F(v)\|^2.$$

## Obtaining the Pairwise Distances via Heat Kernels

Recall the two embeddings discussed so far:

- $F(v) = (f_1(v), \dots, f_k(v))$
- $\psi_t(v) = (e^{-t\lambda_1} f_1(v), \dots, e^{-t\lambda_n} f_n(v))$

**Lemma (Peng-S.-Zanetti, 2017)**

We can compute in  $O(nd \cdot \log^{10} n)$  time an embedding such that, with high probability, it holds that

$$(1 - \varepsilon) \|F(u) - F(v)\|^2 \leq \|\psi_t(u) - \psi_t(v)\|^2 \leq \|F(u) - F(v)\|^2.$$

**Proof Sketch**

- Johnson-Lindenstrauss transformation
- Algorithm for approximating matrix exponential.



## Main Result

---

Theorem (Peng-S.-Zanetti, 2017)

There is a linear-time algorithm that, for a graph  $G$  with  $k$  clusters  $S_1, \dots, S_k$  and  $\Upsilon = \Omega(k^3)$ , outputs a partition  $A_1, \dots, A_k$  such that

$$|A_i \triangle S_i| = O(k^3 \cdot \Upsilon^{-1} \cdot |S_i|).$$

### Theorem (Peng-S.-Zanetti, 2017)

There is a linear-time algorithm that, for a graph  $G$  with  $k$  clusters  $S_1, \dots, S_k$  and  $\Upsilon = \Omega(k^3)$ , outputs a partition  $A_1, \dots, A_k$  such that

$$|A_i \triangle S_i| = O(k^3 \cdot \Upsilon^{-1} \cdot |S_i|).$$

- The heat kernel distances

$$d_t(u, v) = \sum_w (H_t(w, u) - H_t(w, v))^2$$

indeed behave differently among edges inside a cluster and edges crossing different clusters.

### Theorem (Peng-S.-Zanetti, 2017)

There is a linear-time algorithm that, for a graph  $G$  with  $k$  clusters  $S_1, \dots, S_k$  and  $\Upsilon = \Omega(k^3)$ , outputs a partition  $A_1, \dots, A_k$  such that

$$|A_i \triangle S_i| = O(k^3 \cdot \Upsilon^{-1} \cdot |S_i|).$$

- The heat kernel distances

$$d_t(u, v) = \sum_w (H_t(w, u) - H_t(w, v))^2$$

indeed behave differently among edges inside a cluster and edges crossing different clusters.

- This gives us the first linear-time algorithm for graph clustering.

### Theorem (Peng-S.-Zanetti, 2017)

There is a linear-time algorithm that, for a graph  $G$  with  $k$  clusters  $S_1, \dots, S_k$  and  $\Upsilon = \Omega(k^3)$ , outputs a partition  $A_1, \dots, A_k$  such that

$$|A_i \triangle S_i| = O(k^3 \cdot \Upsilon^{-1} \cdot |S_i|).$$

- The heat kernel distances

$$d_t(u, v) = \sum_w (H_t(w, u) - H_t(w, v))^2$$

indeed behave differently among edges inside a cluster and edges crossing different clusters.

- This gives us the first linear-time algorithm for graph clustering.
- Our intuitions are from random walk theory, but our analysis is based on geometry.

### Theorem (Peng-S.-Zanetti, 2017)

There is a linear-time algorithm that, for a graph  $G$  with  $k$  clusters  $S_1, \dots, S_k$  and  $\Upsilon = \Omega(k^3)$ , outputs a partition  $A_1, \dots, A_k$  such that

$$|A_i \triangle S_i| = O(k^3 \cdot \Upsilon^{-1} \cdot |S_i|).$$

- The heat kernel distances

$$d_t(u, v) = \sum_w (H_t(w, u) - H_t(w, v))^2$$

indeed behave differently among edges inside a cluster and edges crossing different clusters.

- This gives us the first linear-time algorithm for graph clustering.
- Our intuitions are from random walk theory, but our analysis is based on geometry.
- BUT, our analysis only holds when there is an eigengap.

Could heat kernels be a general tool for designing fast algorithms?

## Revisit the Graph Expansion Problem

### Graph Expansion

Given a  $d$ -regular graph  $G = (V, E)$  as input, find a set  $S \subseteq V$  of size  $|S| \leq n/2$  of minimum conductance, i.e.,

$$\phi_G(S) = \min_{S': |S'| \leq n/2} \phi_G(S').$$

## Revisit the Graph Expansion Problem

### Graph Expansion

Given a  $d$ -regular graph  $G = (V, E)$  as input, find a set  $S \subseteq V$  of size  $|S| \leq n/2$  of minimum conductance, i.e.,

$$\phi_G(S) = \min_{S': |S'| \leq n/2} \phi_G(S').$$

- This is the simplified version of graph clustering ( $k = 2$  clusters).
- NP-hard to approximate, and there is no constant-factor approximation algorithms assuming the small-set expansion conjecture holds.
- The current best approximation algorithm is based on **SDP + geometric embedding**.  
*Arora-Rao-Vazirani, JACM, 2009*



## Revisit the Graph Expansion Problem

### Graph Expansion

Given a  $d$ -regular graph  $G = (V, E)$  as input, find a set  $S \subseteq V$  of size  $|S| \leq n/2$  of minimum conductance, i.e.,

$$\phi_G(S) = \min_{S': |S'| \leq n/2} \phi_G(S').$$

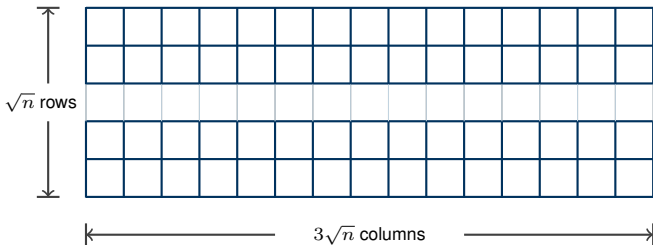
- This is the simplified version of graph clustering ( $k = 2$  clusters).
- NP-hard to approximate, and there is no constant-factor approximation algorithms assuming the small-set expansion conjecture holds.
- The current best approximation algorithm is based on **SDP + geometric embedding**.  
*Arora-Rao-Vazirani, JACM, 2009*

**Improve the state-of-the-art algorithm by heat kernels?**

## Grid Graphs

We define a family of graphs  $\{G\}_n$  as follows:

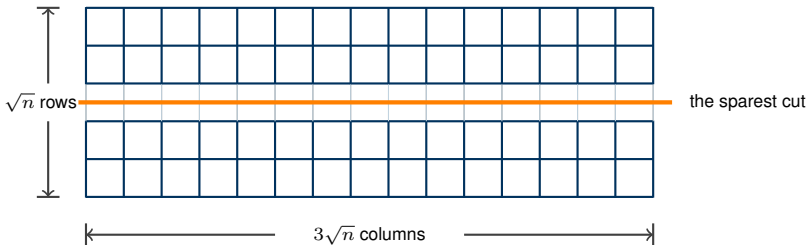
- Every  $G_n$  has  $3n$  vertices, which form a grid of size  $\sqrt{n} \times 3\sqrt{n}$ .
- The weight of every edge in the middle row has weight  $1/\sqrt{n}$ , and all the other edges have weight  $1$ .



## Grid Graphs

We define a family of graphs  $\{G\}_n$  as follows:

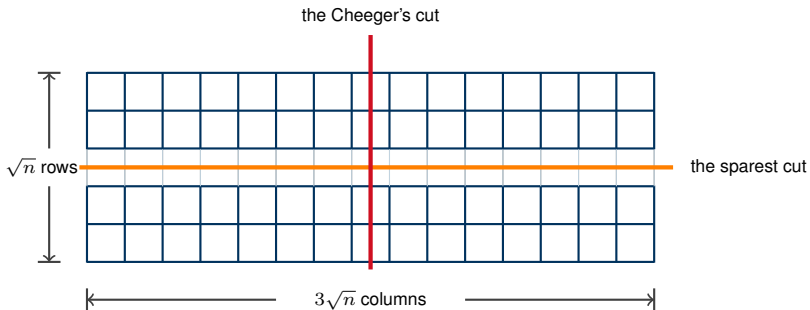
- Every  $G_n$  has  $3n$  vertices, which form a grid of size  $\sqrt{n} \times 3\sqrt{n}$ .
- The weight of every edge in the middle row has weight  $1/\sqrt{n}$ , and all the other edges have weight  $1$ .



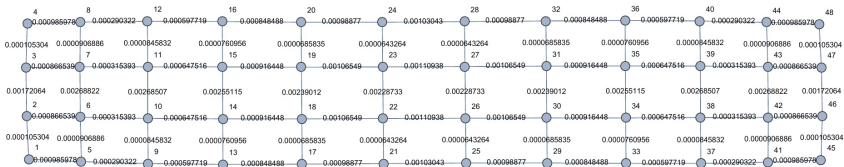
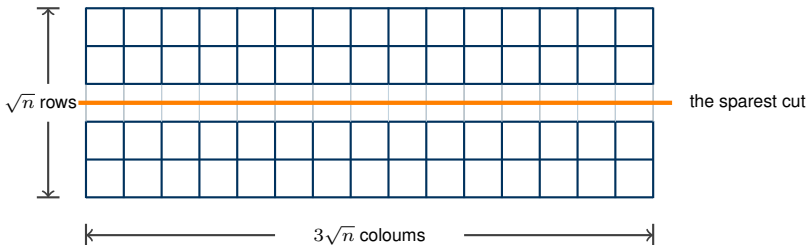
## Grid Graphs

We define a family of graphs  $\{G\}_n$  as follows:

- Every  $G_n$  has  $3n$  vertices, which form a grid of size  $\sqrt{n} \times 3\sqrt{n}$ .
- The weight of every edge in the middle row has weight  $1/\sqrt{n}$ , and all the other edges have weight  $1$ .



# Heat Kernel Distances in the Grid Graphs



## The proposed algorithm

---

Run the following for  $t = 2^i, i = 1, 2, \dots, c \log n$

- Compute heat kernel distances  $h_t(u, v)$  for all edges  $u \sim v$
- Construct a new graph  $Q_t = (V, E, w)$  where  $w(u, v) = \exp(-h_t(u, v))$

## The proposed algorithm

---

Run the following for  $t = 2^i, i = 1, 2, \dots, c \log n$

- Compute heat kernel distances  $h_t(u, v)$  for all edges  $u \sim v$
- Construct a new graph  $Q_t = (V, E, w)$  where  $w(u, v) = \exp(-h_t(u, v))$
- Find a sparse cut of  $Q_t$  by the sweep set algorithm, i.e. the proof from Cheeger inequality
- Store the set  $S \subseteq V$  with minimum conductance found so far.

Output  $S$

## The proposed algorithm

Run the following for  $t = 2^i, i = 1, 2, \dots, c \log n$

- Compute heat kernel distances  $h_t(u, v)$  for all edges  $u \sim v$
- Construct a new graph  $Q_t = (V, E, w)$  where  $w(u, v) = \exp(-h_t(u, v))$
- Find a sparse cut of  $Q_t$  by the sweep set algorithm, i.e. the proof from Cheeger inequality
- Store the set  $S \subseteq V$  with minimum conductance found so far.

Output  $S$

This algorithm finds the optimal cut for the Grid Graph.



## The proposed algorithm

Run the following for  $t = 2^i, i = 1, 2, \dots, c \log n$

- Compute heat kernel distances  $h_t(u, v)$  for all edges  $u \sim v$
- Construct a new graph  $Q_t = (V, E, w)$  where  $w(u, v) = \exp(-h_t(u, v))$
- Find a sparse cut of  $Q_t$  by the sweep set algorithm, i.e. the proof from Cheeger inequality
- Store the set  $S \subseteq V$  with minimum conductance found so far.

Output  $S$

This algorithm finds the optimal cut for the Grid Graph.

What is the approximate ratio of this algorithm?

## Summary

---

- Heat kernel is a basic notion in spectral geometry.

## Summary

---

- Heat kernel is a basic notion in spectral geometry.
- We studied its connections to random walks and geometry, which allows us to design the first linear-time algorithm for graph clustering.

## Summary

---

- Heat kernel is a basic notion in spectral geometry.
- We studied its connections to random walks and geometry, which allows us to design the first linear-time algorithm for graph clustering.
- This leaves us a number of interesting questions, including the powers and limits of heat kernels for designing fast algorithms.

## Summary

---

- Heat kernel is a basic notion in spectral geometry.
- We studied its connections to random walks and geometry, which allows us to design the first linear-time algorithm for graph clustering.
- This leaves us a number of interesting questions, including the powers and limits of heat kernels for designing fast algorithms.

THANK YOU!

Reference: Richard Peng, He Sun, and Luca Zanetti: Partitioning Well-Clustered Graphs: Spectral Clustering Works! SIAM Journal on Computing, 46(2):710-743, 2017.