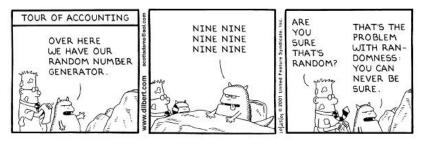
Generalised Uniformity Testing

Tuğkan Batu Clément Canonne

Workshop on Data Summarization, University of Warwick 19 March 2018



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Asking questions such as

- Are two distributions similar?
- Are two random variables independent?
- Is the distribution monotone?
- What is the entropy of the distribution?

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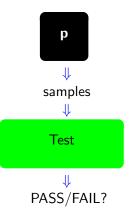
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No assumptions on the underlying distribution

Focus: large discrete domains/alphabets



•  $[n] = \{1, \ldots, n\}$  (typically known)

- **p**: black-box distribution over [*n*]
  - generates i.i.d. samples
- $p_i = \Pr[\mathbf{p} \text{ outputs } i]$
- ► Error probability < 0.01
- Sample complexity in terms of *n*?

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## A Brief History of Testing Distributions

Many results in testing of discrete distributions over domain [*n*]: uniformity, identity, closeness, independence, monotonicity, log-concavity, juntas, MHR, PBD, SIIRV, histograms, ....[GR00,BFR+00,BFF+01, BKR04, Pan08, LRR11, VV14, ADK15, DKN15, BFR+10, CDVV14, Can16, DK16, DKS17,...]

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We focus on **Uniformity.** 

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## **Testing Uniformity**

#### Lower bound (Impossibility):

 $\Omega(\sqrt{n})$  samples are needed

- Consider  $\mathbf{p} = U_{[n]}$  and  $\mathbf{p}' = U_{[n/2]}$
- In o(√n) samples from p (or p'), no repetitions (Birthday Problem)

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### Upper bound (Algorithm):

Techniques from [Goldreich Ron '00] extend to give a Uniformity Test with sample complexity  $O(\sqrt{n}/\epsilon^4)$ 

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Estimate collision probability

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Estimate collision probability

[Paninski '08] shows sample complexity  $\Theta(\sqrt{n}/\epsilon^2)$ .

Domain size *n* must be given as input.

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- It may be irrelevant.

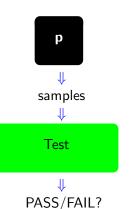
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- Domain size *n* must be given as input.
  - It may be unavailable.
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- Non-adaptive algorithms that always match the worst case.

Usually not optimal for the given input distribution.

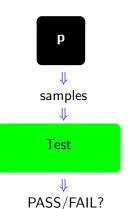
## Testing Distributions Obliviously



- ▶ p: black-box distribution over unknown S ⊆ N
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- $p_i = \Pr[\mathbf{p} \text{ outputs } i]$
- ► Error probability < 0.01
- Sample complexity in terms of some f(p)?

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## Testing Distributions Obliviously

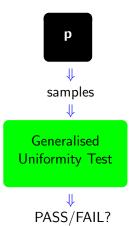


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- $p_i = \Pr[\mathbf{p} \text{ outputs } i]$
- ► Error probability < 0.01
- Sample complexity in terms of some f(p)?

#### Questions:

- What should f(p)?
- How to detect when it has a large enough sample set?
- Optimal for each input distribution?

## Generalised Uniformity Testing



#### Goal:

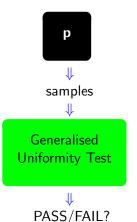
• If  $\mathbf{p} = U_S$  for some  $S \subset \mathbb{N}$ , then PASS

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▶ If,  $\forall S \subseteq \mathbb{N}$ ,  $\Delta(\mathbf{p}, U_S) > \epsilon$ , then FAIL

 $\Delta(\cdot, \cdot)$ : total variation distance

## Generalised Uniformity Testing



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- If  $\mathbf{p} = U_S$  for some  $S \subset \mathbb{N}$ , then PASS
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 $\Delta(\cdot, \cdot)$ : total variation distance

- How many samples are needed?
- How do we know when to stop?

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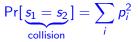
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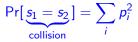
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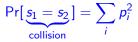
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Lemma ([Goldreich Ron 00]) Using  $O(\sqrt{n})$  samples, we can estimate  $\|\mathbf{p}\|_2^2$  very well.

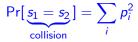
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## For a uniform **p**, $\frac{1}{\|\mathbf{p}\|_2^2}$ is the support size.

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For any distribution **p**, we can estimate  $\|\mathbf{p}\|_2^2$  within  $1 \pm \epsilon$  using  $\Theta(\frac{1}{\epsilon^2 \cdot \|\mathbf{p}\|_2})$  samples.

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Tight in terms of  $\|\mathbf{p}\|_2$ .

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Tight in terms of  $\|\mathbf{p}\|_2$ .

#### Lemma

Estimating  $\|p\|_2^2$  requires  $\Omega(\frac{1}{\|p\|_2})$  samples.

## We got $\|\mathbf{p}\|_2^2$ ! What do we do?

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**Observation:** For a fixed value for  $\|\mathbf{p}\|_2$ , the uniform distribution on  $\frac{1}{\|\mathbf{p}\|_2^2}$  will generate the fewest 3-way collisions.

#### Lemma

Let p be a distribution over  $\mathbb N$  and  $N\in\mathbb N$  such that

$$\frac{1-\epsilon}{N} \leq \|\mathbf{p}\|_2^2 \leq \frac{1+\epsilon}{N} \qquad \text{and} \qquad ||\mathbf{p}||_3^3 \leq \frac{1+\delta}{N^2},$$

for some  $0 < \epsilon, \delta < 0.04$ . Then, the  $\ell_1$  distance of **p** to any uniform distribution **q** can be upper bounded as

 $\Delta(\mathbf{p},\mathbf{q}) \leq 9\sqrt[3]{\delta+3\epsilon}.$ 

### Putting It Altogether

- 1: Algorithm Test-Uniformity( $\mathbf{p}, \epsilon$ )
- 2:  $\delta \leftarrow O(\epsilon^3), \ k \leftarrow \lceil \epsilon^{-18} \rceil$
- 3:  $N \leftarrow 1/\text{ESTIMATE} \ell_2 \text{NORM}(\mathbf{p}, \delta)$
- 4: Keep taking samples from **p** until *k* 3-way collisions are observed or  $M = \sqrt[3]{3(1-4\delta)k}N^{2/3}$  samples are taken

- 5: if more than k 3-way collisions are observed then
  6: return REJECT
- 7: **else**
- 8: return ACCEPT

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#### Theorem

The test above, with probability at least 3/4, accepts a uniform distribution and rejects a distribution  $\epsilon$ -far from any uniform distribution. The expected sample complexity is  $\Theta(\frac{1}{\epsilon^6 \cdot ||\mathbf{p}||_3})$ .

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Essentially tight. We certainly need  $\Omega(\frac{1}{||\mathbf{p}||_3})$ .

### Instance-specific Lower Bound

#### Theorem

For any fixed non-uniform distribution  $\mathbf{q}$ , distinguishing between (i)  $\mathbf{p} = \mathbf{q}$  (up to a permutation) and (ii) uniform  $\mathbf{p}$ requires  $\Omega(1/||\mathbf{p}||_3)$  samples from  $\mathbf{p}$ .

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- Instance-specific not worst-case
- Proof uses Wishful Thinking Theorem of [Valiant11].



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- ▶ Follow-up work of Diakonikolas, Kane, and Stewart 17:
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Extensions to other distribution testing problems

- ▶ Follow-up work of Diakonikolas, Kane, and Stewart 17:
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- Instance-specific lower bounds

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Thank You!

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