

Lecture 3

Domg Borel-Serre for GL_n

Notation

$$G = GL_n \mathbb{R} \quad K = O(n) \quad H = \left\{ \begin{pmatrix} \lambda & 0 \\ 0 & \lambda^{-1} \end{pmatrix} \mid \lambda > 0 \right\}$$

$P \subset G$ a parabolic subgp, $K_P = K \cap P$

$$X = KH \backslash G \quad \Gamma = GL_n \mathbb{Z}$$

We want to add a euclidean space $e(P)$ to X for each rational parabolic subgroup P

$$(P = \text{stab } V_1 \subset \dots \subset V_k, \quad V_i \subset \mathbb{R}^n \text{ rational})$$

changing basis conjugates P

Can choose a basis w/ $v_{i_1}, \dots, v_{i_l} \in V_1$
 $v_{i_{l+1}}, \dots, v_{i_2} \in V_2$
etc

Change basis so $v_i \mapsto e_i$

Then P is conjugate to $\text{stab}(E_1 \cap \dots \cap E_k)$

which is block lower triangular:

i^{th} diagonal block
of size
 $\dim(E_i) \sim \dim(E_{i+1})$

$$\left(\begin{array}{c|cc|c} * & & & \\ \hline * & * & & \\ \hline * & * & * & \\ \hline * & * & * & * \end{array} \right)$$

The block lower triangular matrices
are the standard parabolics

For $n=3$ they are

$$P_1 = \left(\begin{array}{c|cc} * & & \\ \hline * & * & * \\ \hline * & * & * \end{array} \right)$$

$= \text{stab}(e_1)$

$$P_2 = \left(\begin{array}{cc|c} * & * & \\ \hline * & * & \\ \hline * & * & * \end{array} \right)$$

$= \text{stab}(e_1, e_2)$

$$B = \left(\begin{array}{c|cc} * & & \\ \hline * & * & \\ \hline * & * & * \end{array} \right) = P_1 \cap P_2 = \text{stab}(e_1) \cap (e_1, e_2)$$

Prop: $P \hookrightarrow G$ induces a

homeomorphism $H\mathbb{K}_P \setminus P \rightarrow H\mathbb{K} \setminus G$

PF We may assume P is standard

The right action of G on

$X = H\mathbb{K} \setminus G$ restricts to a right action of P .

By Gram-Schmidt (also known as the "QR" algorithm) every $g \in GL(n, \mathbb{R})$ can be written $g = qr$, with $q \in O(n)$ and r lower triangular

So each coset $H\mathbb{K}$ is equal

to $H\mathbb{K}qr = H\mathbb{K}r$, $r \in \underline{P}$!

i.e. P acts transitively on X .

The stabilizer of HK is

$$HK \cap P = H \cdot K_p$$

so $HK \backslash G = X = HK_p \backslash P$

Fundamental fact about group actions:

If G acts on X then the orbit of $x \in X$ can be identified with $G/\text{stab } x$

Note $g \in HK_p = HK \cap P$

\Rightarrow rows of g are orthogonal
(in std form)

e.g. $\left(\begin{array}{c|cc} * & 0 & 0 \\ x & * & * \\ y & * & * \end{array} \right) \in HK_p \Rightarrow x=y=0$

In general g is block diagonal:

$$HK_P \subset \begin{pmatrix} & & \\ & & \\ & & \\ \text{---} & \text{---} & \text{---} \\ & & \\ & & \end{pmatrix} := L_P$$

"Levi component of P "

The center of L_P is diagonal matrices which are constant in each block.

Def $A_P = \left\{ \begin{pmatrix} \lambda_1 I & & & \\ & \ddots & & \\ & & \ddots & \\ & & & \lambda_k I \end{pmatrix} \mid \lambda_i > 0 \right\}$

$S_0 \subseteq \text{center of } L_P$ (so in particular commutes with K_P)

Now can see that there is a left action of A_P on X !

Left Action of A_p :

Write $x \in X$ as $H K_p p$, $p \in P$

If $a \in A_p$, $a \cdot H K_p p = H K_p a p$
 $\quad\quad\quad (\neq H K_p p a !)$

This is not the same as the right action

We think we understand $n=2$, so:

How does this play out for $n=2$?

$$P = \left(\begin{smallmatrix} * & 0 \\ * & * \end{smallmatrix} \right) = \text{stab } \langle e_1 \rangle$$

$$K_p = P \cap O(2) = \left(\begin{smallmatrix} \varepsilon_1 & 0 \\ 0 & \varepsilon_2 \end{smallmatrix} \right) \quad \varepsilon_i = \pm 1$$

[pf: $\left(\begin{smallmatrix} x & 0 \\ y & z \end{smallmatrix} \right) \left(\begin{smallmatrix} x & y \\ 0 & z \end{smallmatrix} \right) = \left(\begin{smallmatrix} x^2 & xy \\ xy & y^2 + z^2 \end{smallmatrix} \right) = \left(\begin{smallmatrix} 1 & 0 \\ 0 & 1 \end{smallmatrix} \right)$]

\cap
 $P \cap O(2)$

$$g \in GL_2(\mathbb{R})$$

$$HKg \in X$$

is represented thus by $HK \begin{pmatrix} x & 1 \\ y & 0 \end{pmatrix}$ with $y > 0$
 $\Leftrightarrow x+iy \in H$

We want to write it as $HK_p p \in HK_p \backslash P$

But $\begin{pmatrix} x & 1 \\ y & 0 \end{pmatrix}$ is not in P (it's not in any parabolic!)

So choose a different coset representative which is in P (we know it exists)

$$\begin{aligned} HKg &= HK \begin{pmatrix} x & 1 \\ y & 0 \end{pmatrix} = HK \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x & 1 \\ y & 0 \end{pmatrix} \\ &= HK \begin{pmatrix} -y & 0 \\ x & 1 \end{pmatrix} \end{aligned}$$

$$\hookrightarrow HK_p \begin{pmatrix} -y & 0 \\ x & 1 \end{pmatrix} \left\{ \pm \begin{pmatrix} -y & 0 \\ x & 1 \end{pmatrix}, \pm \begin{pmatrix} y & 0 \\ x & 1 \end{pmatrix} \right\} \in HK_p \backslash P$$

$$a \in A_p = \begin{pmatrix} s & 0 \\ 0 & t \end{pmatrix} \quad s, t > 0$$

$$\begin{pmatrix} s & 0 \\ 0 & t \end{pmatrix} H K_p \begin{pmatrix} -y & 0 \\ x & 1 \end{pmatrix} = H K_p \begin{pmatrix} -sy & 0 \\ zx & t \end{pmatrix}$$

$$= H K_p \begin{pmatrix} -sy & 0 \\ x & 1 \end{pmatrix}$$

$$\iff x + i \frac{s}{t} y \quad \left(\frac{s}{t} > 0 \right)$$

i.e. the orbits of A_p are the vertical lines in H

The stabilizer in A_p of $H K_p$ is H :

$$\text{(Pf: } a \cdot H K_p = H K_p \Rightarrow a \in H K_p \Rightarrow a \in H K_p \cap A_p.$$

$$\text{Since } K_p \cap A_p = \langle I \rangle, \quad a = \lambda I \in H.)$$

So each orbit is $\iff H \backslash A_p$

$$\text{Note } A_p \approx (R_{>0})^{k+1}$$

$$\text{so } H\backslash A_p \approx (R_{>0})^k$$

The action of A_p on X is called the
geodesic action associated to P

The orbits of A_p foliate $X \approx \mathbb{R}^d$
($d = \frac{n(n+1)}{2} - 1$), each orbit is $\approx \mathbb{R}^k$

Claim the orbit space $\overset{A_p}{\backslash} X := e(P)$
is homeomorphic to \mathbb{R}^{d-k} .

To see this

$$\text{note } A_p \backslash X = A_p \backslash H \backslash K_P = A_p K_P \backslash P$$

$$(H < A_p)$$

eq $P = \text{stab } e_1 \subset e_1 e_2 \subset \dots \subset e_1 \dots e_{n-1}$

$$P = \begin{pmatrix} * & & & 0 \\ & * & & \\ & & * & \\ & & & * \end{pmatrix} \quad K_P = \begin{pmatrix} \varepsilon_1 & & & \\ & \ddots & & \\ & & \varepsilon_n & \end{pmatrix}, \varepsilon_i = \pm 1$$

$$A_P = \begin{pmatrix} s_1 & & & \\ & \ddots & & \\ & & s_n & \end{pmatrix}, s_i > 0$$

$$K_P A_P^{-P} = \begin{pmatrix} 1 & 0 \\ * & 1 \end{pmatrix} \approx \mathbb{R}^{\frac{n(n-1)}{2}}$$

$$\left[d - k = \begin{aligned} & \left(\frac{n(n+1)}{2} - 1 \right) - (n-1) \\ & = \frac{n^2 + n - 2}{2} - 2n + 2 \\ & = \frac{n^2 - n}{2} \quad \checkmark \end{aligned} \right]$$

eq $P = \text{stab } \langle e_1 \dots e_k \rangle$

$$p = \begin{pmatrix} 1 & & \\ \vdash & \ddots & \\ & & 1 \end{pmatrix} \in P \quad K_P = \begin{pmatrix} O(k) & O \\ \hline O & O(n-k) \end{pmatrix}$$

$K_P p$ has a! coset representative

$$\begin{pmatrix} a_1, 0 & O \\ * & a_k \\ \hline * & \end{pmatrix} \quad \begin{pmatrix} O \\ \hline b_1, 0 \\ * & \ddots \\ * & b_k \end{pmatrix}$$

$A_p K_p \dot{P}$ was ! coset rep

1	0	
*	*	*
*	*	*

	1	
*	*	*
*	*	*

$$\approx \mathbb{R}^{\frac{n(n-1)}{2}} \times \mathbb{R}_{>0}^{k-1} \times \mathbb{R}_{>0}^{n-k-1} \approx \mathbb{R}^{\frac{n(n-1)}{2} + n - 2}$$

codimension 1? $\left(\frac{n(n+1)}{2} - 1\right) - \left(\frac{n(n-1)}{2} + n - 2\right)$

$$= \frac{(n+1)(n-2) - (n-1)n + 4}{2}$$

$$= \frac{2}{2} = 1 \quad \checkmark$$

Exercise: General case.

note: for $n > 2$

The subgroups intersect, so the orbits will too.

P acts on $e(P) = A_p K_p \dot{P}$ (on the right):

$$(K_p A_p \dot{P}) \cdot g = K_p A_p \dot{P} g$$

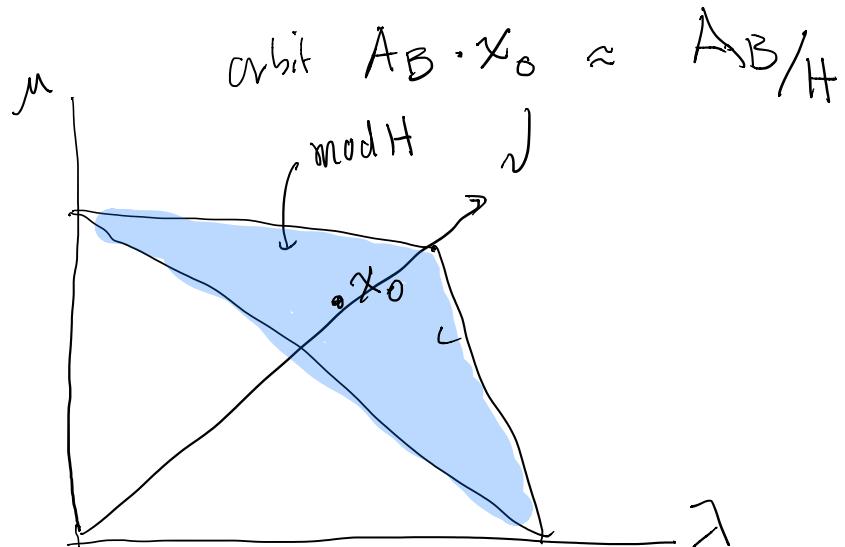
Specialize to $n=3$ so we can draw pictures. The standard parabolics are:

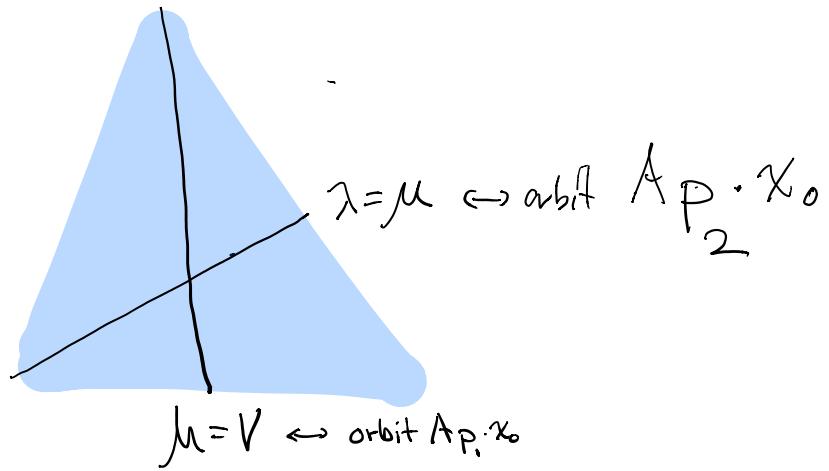
$$P_1 = \left(\begin{array}{c|cc} * & 0 & 0 \\ \hline * & * & * \\ * & * & * \end{array} \right) \quad P_2 = \left(\begin{array}{c|cc} ** & 0 & 0 \\ \hline ** & 0 & 0 \\ \hline ** & * & * \end{array} \right) \quad B = \left(\begin{array}{c|cc} * & 0 & 0 \\ \hline * & * & 0 \\ \hline * & * & * \end{array} \right)$$

$$(B = P_1 \cap P_2)$$

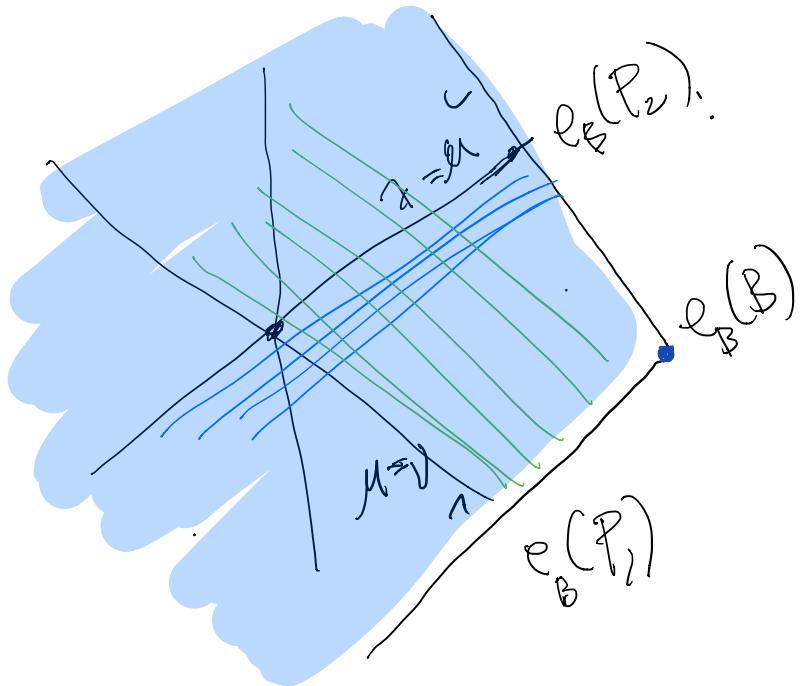
$$A_{P_1} = \begin{pmatrix} \lambda & & \\ & \mu & \\ & & \mu \end{pmatrix} \quad A_{P_2} = \begin{pmatrix} \lambda & & \\ & \lambda & \\ & & \mu \end{pmatrix} \quad A_B = \begin{pmatrix} \lambda & & \\ & \mu & \\ & & \lambda \end{pmatrix}$$

orbit of $x_0 = kH\mathbf{e}$ under A_B





Better picture



blue = orbit $A_B x_0$

green lines = orbits $A_{P_1}x$ for $x \in A_B x_0$

blue lines = orbits $A_{P_2}x$ for $x \in A_B x_0$

$e_B(B)$ is one point, for the orbit $A_B X_0$

$e(B)$ has one point for each A_B orbit
in X , $\approx \mathbb{R}^3$

$e_B(P_i)$ has one point for each orbit
in this picture so is $\approx \mathbb{R}$

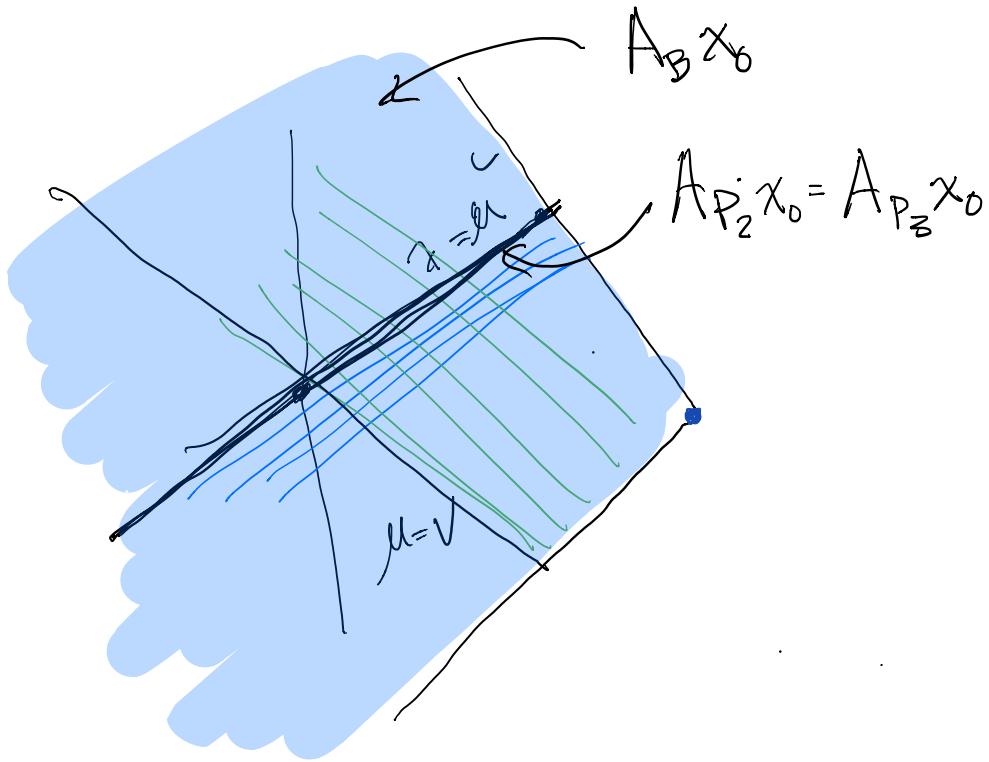
$$e(P_i) = e_B(P_i) \times \mathbb{R}^3 \approx \mathbb{R}^4$$

We want to add on $e(P)$ for every parabolic

eg $P_3 = \text{stab } \langle c_3 \rangle = \left(\begin{array}{cc|c} * & * & * \\ * & * & * \\ \hline 0 & 0 & t \end{array} \right)$

But note: $A_{P_3} = \begin{pmatrix} \lambda & \\ & \mu \end{pmatrix} = A_{P_2}^{-1}$

so $A_{P_3} \cdot K^H = A_{P_2} \cdot K^H = \text{same line in } A_B X_0$.



but action of A_{P_3} is in opposite direction

$$\begin{pmatrix} \lambda & & \\ & \lambda & \\ & & \mu \end{pmatrix} \begin{pmatrix} A & | & 0 \\ \hline x & y & | & b \end{pmatrix} = \begin{pmatrix} \lambda A & | & 0 \\ \hline \mu x & \mu y & | & \mu b \end{pmatrix}$$

$$\begin{pmatrix} \lambda & & \\ & \lambda & \\ & & \mu \end{pmatrix} \begin{pmatrix} A & | & x \\ \hline 0 & 0 & | & b \end{pmatrix} = \begin{pmatrix} \lambda A & | & \lambda x \\ \hline 0 & 0 & | & \mu b \end{pmatrix}$$

(compare rank 2 :)

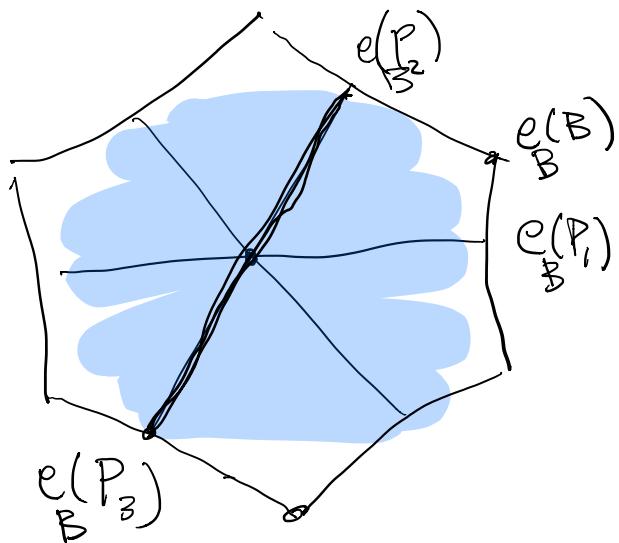
$$\begin{pmatrix} \lambda & \\ \mu & \end{pmatrix} \begin{pmatrix} -y & 0 \\ x & 1 \end{pmatrix} = \begin{pmatrix} -\lambda y & 0 \\ \mu x & \mu \end{pmatrix}$$

$$\sim \begin{pmatrix} -\frac{\lambda}{\mu} y & 0 \\ x & 1 \end{pmatrix}$$

$$\begin{pmatrix} \lambda & \\ \mu & \end{pmatrix} \begin{pmatrix} 1 & x \\ 0 & -y \end{pmatrix} = \begin{pmatrix} \lambda & \lambda x \\ 0 & -\mu y \end{pmatrix}$$

$$\sim \begin{pmatrix} 1 & x \\ 0 & -\frac{\mu}{\lambda} y \end{pmatrix}$$

$$\frac{\lambda}{\mu} \rightarrow \infty \Leftrightarrow \frac{\mu}{\lambda} \rightarrow 0$$



So want to glue a hexagon to $A_B x_0$

recall X is foliated by the

A_B -orbits, so $c_B(B)$ is a

point but $e(B) = \text{pt} \times \mathbb{R}^3$

$e_B(P_i)$ is a line but

$e(P_i) = \text{line} \times \mathbb{R}^3 \approx \mathbb{R}^4$

Note: $B = \text{stab } e_1 \cap e_1 e_2 = \text{stab } e_1 \cap \text{stab } e_1 e_2$

P_1 and P_2 are the only parallels containing B

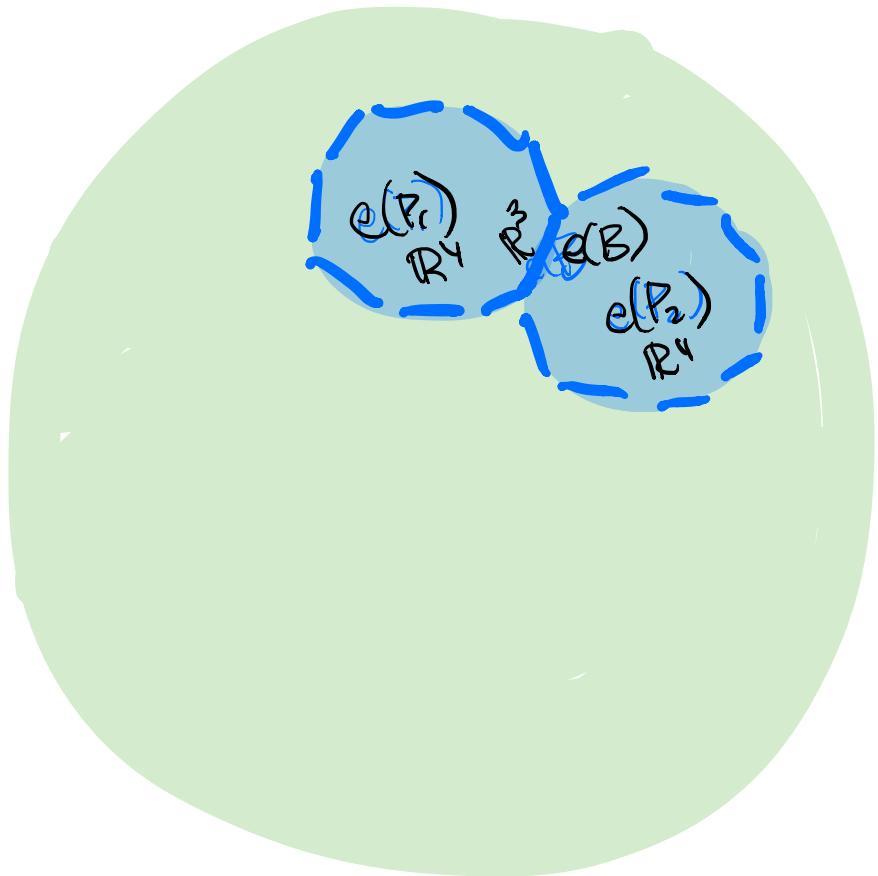
so $e(P_1)$ and $e(P_2)$ are the only $e(P)$'s containing $e(B)$.

on the other hand, P_2 contains lots of conjugates of B :

Take any line $l \in \langle e_1 e_2 \rangle$

$$B_l = \text{stab}(l) \cap \langle e_1 e_2 \rangle \subset P_2$$

so $e(P)$ contains lots of $e(B)$'s



$$X \approx \mathbb{R}^5$$

Define

$$\bar{X} = X \cup \bigcup_P e(P)$$

To Do

* Describe the topology on \overline{X}
(what is a neighbourhood of a point?)

Then show

* the enlarged space \overline{X} is still contractible

* the action extends

* stabilizers are finite and

* the quotient is compact



That's the tricky part

