

Optimal Transport in a Nutshell

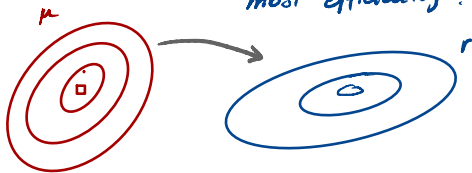
Part 2



ICMS workshop on
'Connections between interacting particle dynamics and data science'

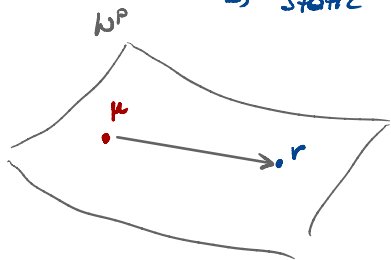
Recap

OT problem: How can we move mass from a source to a target most efficiently?



-) Monge map $T(x)$
-) Kantorovich plan $\pi(x, y)$
-) Dual Kantorovich potential ψ

→ static formulation of OT



TODAY

-) Solutions do (X^p) define metric
-) Dynamic OT Benamou - Brenier
-) Wasserstein gradient flows
-) Computational OT

Wasserstein distance: Given two probabilities μ and $\nu \in \mathcal{P}_p(X)$ we define

Monge-Kantorovich

↑
Vaserstein

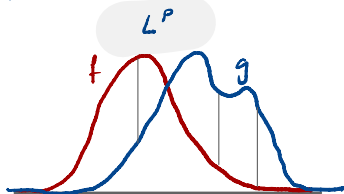
$$d_{W_p}(\mu, \nu) := \min_{\pi \in \Pi(\mu, \nu)} \left(\int_{X \times X} |x - y|^p d\pi(\mu, \nu) \right)^{\frac{1}{p}}$$

Earth-mover distance

$$c(x, y) = |x - y|^p$$

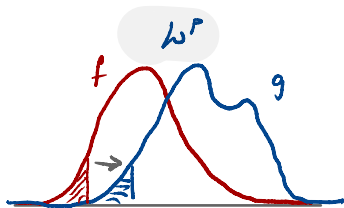
$$\mathcal{P}_p(X) = \{ \mu \in \mathcal{P}(X) : \int |x|^p d\mu(x) < \infty \}$$

$$W^p(X) = (\mathcal{P}_p(X), d_{W^p})$$



$$\|f - g\|_{L^p} = \int |f - g|^p dx$$

vertical distance



horizontal distance

very natural way to describe interacting particle systems

used everywhere

measure to compare distributions

Calculating the Wasserstein distance

- In 1D:** Let $\mu, \nu \in \mathcal{P}(\mathbb{R})$ with cdf F and G respectively. Let the cost be a function of the distance, that is $c(x, y) = h(x - y)$, where $h: \mathbb{R} \rightarrow [0, \infty)$ is convex and continuous. Then the Kantorovich cost is given by

$$\min_{\pi \in \Pi(\mu, \nu)} K(\pi) = \int_0^1 h(F^{-1}(t) - G^{-1}(t)) dt.$$

- Between Gaussians:** Let $\mu = \mathcal{N}(m_\mu, \Sigma_\mu)$ and $\nu = \mathcal{N}(m_\nu, \Sigma_\nu)$ be two Gaussians in \mathbb{R}^d , then the map

$$T: x \rightarrow m_\nu + A(x - m_\mu) \leftarrow \begin{array}{l} \text{Gradient of } \varphi \\ \varphi(x) = \frac{1}{2} \langle x - m_\mu, A(x - m_\mu) \rangle \\ \quad + \langle m_\nu, x \rangle \end{array}$$

with $A = \Sigma_\nu^{-\frac{1}{2}} \left(\Sigma_\mu^{-\frac{1}{2}} \Sigma_\nu \Sigma_\mu^{-\frac{1}{2}} \right)^{\frac{1}{2}} \Sigma_\mu^{-\frac{1}{2}} = A^T$ satisfies $T_{\#} \rho_\mu = \rho_\nu$.

1D For μ the CDF $F(x) = \int_{-\infty}^x d\mu(x)$
Pseudo-inverse $F^{-1}(t) = \min_{x \in \mathbb{R}} \{x \in \mathbb{R} \cup \{-\infty\} \mid F(x) \geq t\}$

$$d_W^p = \|F^{-1} - G^{-1}\|_{L^p([0,1])}^p = \int_0^1 |F^{-1}(t) - G^{-1}(t)|^p dt$$

in general \rightarrow computationally expensive!

Properties of the Wasserstein distance

- The Wasserstein distance is a metric on $\mathcal{P}_p(X)$.
- Equivalence of W_p distances: for $p \leq q$ Jensen's inequality implies

$$d_{W_p} \quad \left(\int d(x, y)^p d\pi \right)^{\frac{1}{p}} \leq \left(\int d(x, y)^q d\pi \right)^{\frac{1}{q}},$$

and therefore $W_p(\mu, \nu) \leq W_q(\mu, \nu)$.

- Convergence in the Wasserstein space:

$$\mu_n \rightarrow \mu \Leftrightarrow d_{W_p}(\mu_n, \mu) \rightarrow 0.$$

Metric:

a) symmetric ✓

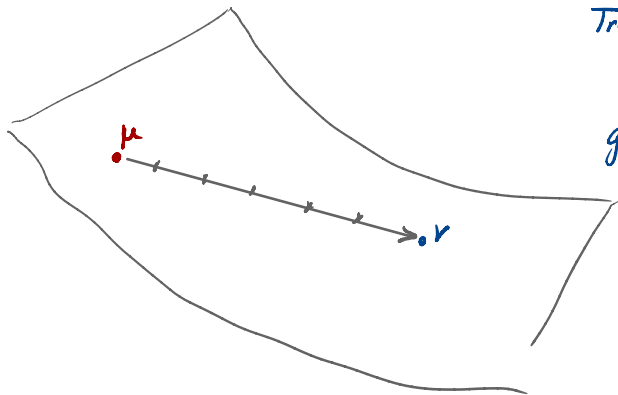
b) $d_{W_p}(\mu, \nu) = 0$

$\Rightarrow \exists! \pi$ s.t. $\int d(x, y)^p d\pi = 0$

$$\pi = (\text{Id}, \text{Id})\# \mu$$

c) Triangle inequality gluing lemmas... ✓

$W^p - (\mathcal{P}_p(\Omega), d_{W^p})$



Transport plans/maps

$\hat{=}$

geodesics in
Wasserstein
space

Geodesics $\hat{=}$ shortest path wrt. Wasserstein distance

\Rightarrow how can we characterise them?

Curves in metric spaces

- A curve $\omega: [0, 1] \rightarrow X$ is called *absolutely continuous* if there exists a $g \in L^1([0, 1])$ such that $d(\omega(t_0), \omega(t_1)) \leq \int_{t_0}^{t_1} g(s) ds$ for every $t_0 < t_1$.
- Consider a curve $\omega: [0, 1] \rightarrow X$. Its *length* is defined as

$$\text{Length}(\omega) := \sup \left\{ \sum_{k=0}^{n-1} d(\omega(t_k), \omega(t_{k+1})) : n \geq 1, 0 = t_0 < t_1 \dots t_n = 1 \right\}.$$

If $\omega \in AC(X)$ then $\text{Length}(\omega) = \int_0^1 |\omega'(t)| dt$.

- A curve $\omega: [0, 1] \rightarrow X$ is a *geodesic* between x_0 and $x_1 \in X$, if it minimises the length among all curves ω connecting x_0 and x_1 .
- A curve $\omega: [0, 1] \rightarrow X$ is a *constant speed geodesic*, if

$$d(\omega(t), \omega(s)) = |t - s| d(\omega(0), \omega(1)) \quad \text{for all } s, t \in [0, 1].$$

Let $\mu, \nu \in \mathcal{P}_p(X)$, $X = \mathbb{R}^d$ compact & convex. Let $\pi \in \Pi(\mu, \nu)$ be OT plan. Define

$$\mu_t = ((\text{Id} - t)x + ty)_{\#} \pi \quad \Leftarrow \text{the convex interpolation}$$

$\mu_t \dots$ constant speed geodesic between μ and

Characterise μ_t

-) Consider particles initially distributed according to ρ_0
-) Move by a given velocity field v_t

Eulerian description $\rho(x,t)$... density of particles

$$\Rightarrow \partial_t \rho_t + \nabla \cdot (\rho_t v_t) = 0 \quad \Leftarrow \text{conservation of mass}$$

$\rho_0 = \rho_0(x)$

Dynamic formulation

Given $\mu, \nu \hat{=}$ initial & final distribution of particles
at $t=0$ & $t=1$

If $\exists!$ v_t that is sufficiently smooth

$$\partial_t \rho + \nabla \cdot (\rho v_t) = 0$$

$\rho_0 = \mu \quad \text{and} \quad \rho_1 = \nu$

Benamou & Brenier: (1990)

$$A_p(\mu_1, \mu_2) = \int_0^1 \int \|v_t\|^p d\mu(x) dt$$

energy action functional

Theorem

Let $X \subset \mathbb{R}^d$ be compact and consider two probability measures $\mu_i \in \mathcal{P}(X)$, $i = 1, 2$ with densities ϱ_i wr.t. the Lebesgue measure. Let $V(\varrho_0, \varrho_1)$ denote the set of all $(\varrho_t, v_t)_{t \in [0,1]}$ satisfying

- The map $t \in [0, 1] \rightarrow \rho_t$ is continuous in $\mathcal{P}(X)$ in the weak topology
- The continuity equation $\partial_t \varrho + \nabla \cdot (\varrho_t \cdot v_t) = 0$ holds in the weak sense for $v_t \in L^2(\mu_t)$ with initial and terminal conditions given by

$$\varrho_{t=0} = \varrho_0 \text{ and } \varrho_{t=1} = \varrho_1.$$

Then

$$\min_{\pi \in \Pi(\mu, \nu)} K(\pi) = \inf_{(\varrho, v) \in V(\varrho_0, \varrho_1)} \int_0^1 \int_{\Omega} |v_t|^2 \varrho_t(x) dx dt.$$

⇒ most prominent way to calculate OT plan til 2000'

⇒ Augmented Lagrange

$$\inf \int_0^1 \int |v_t|^2 \rho \, dx \, dt$$

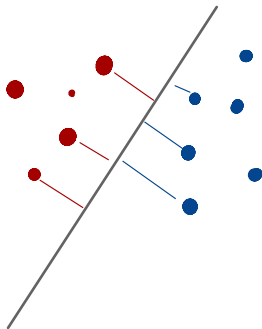
s.t. $\partial_t \rho + \nabla \cdot (\rho v) = 0$

$\rho(x, 0) = \rho_0$
 $\rho(x, 1) = \rho_1$

The sliced Wasserstein distance between two probability densities μ and ν in $\mathcal{P}(\mathbb{R}^d)$ is given by

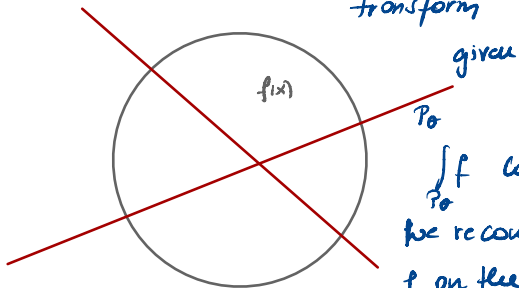
$$d_{SW_2}(\mu, \nu) := \left(\int_{S^d} d_{W_2}^2((P_\theta)_\# \mu, (P_\theta)_\# \nu) d\theta \right)^{\frac{1}{2}},$$

where $S^d = \{\theta \in \mathbb{R}^d : \|\theta\| = 1\}$ and $P_\theta: \mathbb{R}^d \rightarrow \mathbb{R}$ is the projection.



\Rightarrow project on different lines

\Rightarrow Connection to Roudou transform



$\int_{P_0} f$ can
be reconstruct
 f on the
whole domain

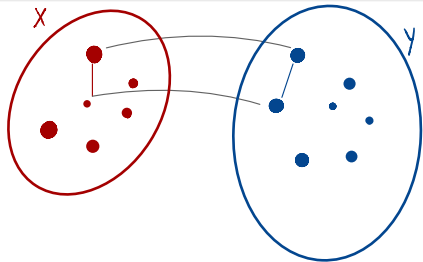
The Gromov-Wasserstein distance

Let $\mu = \sum_{i=1}^n a_i \delta_{x_i} \in \mathcal{P}(\mathbb{R}^p)$ and $\nu = \sum_{j=1}^m b_j \delta_{y_j} \in \mathcal{P}(\mathbb{R}^q)$ with $p \leq q$ with $\sum_{i=1}^n a_i = 1$ and $\sum_{j=1}^m b_j = 1$. Let $c_X: \mathbb{R}^p \times \mathbb{R}^p \rightarrow \mathbb{R}^+$, respectively $c_Y: \mathbb{R}^q \times \mathbb{R}^q \rightarrow \mathbb{R}^+$ denote the cost. Then the Wasserstein-Gromov distance is defined as

$$d_{GW_2}^2(c_X, c_Y, \mu, \nu) = \min_{\pi \in \Pi(\mu, \nu)} J(c_X, c_Y, \pi)$$

where

$$J(c_X, c_Y, \pi) = \sum_{i,j,k,l} |c_X(x_i, x_k) - c_Y(y_j, y_l)|^2 \pi_{ij} \pi_{kl}.$$



\Rightarrow Captures topological features

\Rightarrow more costly.

Gradient flows

- Metric space: Consider a function $F : \mathbb{R}^d \rightarrow \mathbb{R}$ and a $x_0 \in \mathbb{R}^d$:

$$x'(t) = -\nabla F(x(t))$$

$$x(0) = x_0$$

Giorgi

- ⇒ Minimising movement scheme: let $\tau > 0$, define a sequence of points (x_k^T) s.t.

$$x_{k+1}^T \in \operatorname{argmin}_x F(x) + \frac{|x - x_k^T|^2}{2\tau}$$

$d(x_1, x_0^T)^2$
 ← less regularity on F

- Wasserstein space The JKO version of the game

$$\textcircled{*} \varrho_{k+1}^T \in \operatorname{argmin}_\varrho F(\varrho) + \frac{d_{W_2}^2(\varrho, \varrho_{(k)}^T)}{2\tau}$$

Jordan
 Otto
 Kinderlehrer
 1998

Limiting PDE of $\textcircled{*}$

- Show that $\textcircled{*}$ has a unique solution
- Optimality cond. (wrt p)

$$\frac{\delta F}{\delta p} + \frac{\varphi}{\tau} = \text{const}$$

$\varphi \dots$ Kontinuität pot.

- Transport map

$$T(x) = x - \nabla \varphi \Rightarrow \frac{T(x) - x}{\tau} = -\frac{\nabla \varphi}{\tau} = \nabla \left(\frac{\delta F}{\delta p} \right)$$

← displacement / time $\hat{=}$ velocity

4) As $\tau \rightarrow 0$ iterates converge

$$\partial_t \rho - \nabla \cdot \left(\rho \underbrace{\nabla \left(\frac{\delta F}{\delta \rho} \right)}_{=v} \right) = 0$$

Example:

$$F(\rho) = \int \rho (\log \rho - 1) dx$$

$$\frac{\delta F}{\delta \rho} = \log \rho - 1 + \rho \cdot \frac{1}{\rho} = \log \rho$$

$$\partial_t \rho = \text{div} \left(\rho \cdot \frac{1}{\rho} \nabla \rho \right) = \Delta \rho$$

Fokker Planck,

$$\partial_t \rho = \nabla \cdot \left(\underbrace{D(\rho)}_{\substack{\uparrow \\ \text{non-linear} \\ \text{mobility}}} \nabla \left(\underbrace{E'(\rho)}_{\substack{\uparrow \\ \text{internal} \\ \text{energy}}} + V + \underbrace{W * \rho}_{\substack{\uparrow \\ \text{interaction} \\ \text{energy}}} \right) \right)$$

\swarrow given potential

\Rightarrow entropy methods

Connection to data science

o) Ensemble / particle methods SDEs, density of the mean limit satisfies nonlinear FPE

⇒ large time behavior $N \rightarrow \infty$ # particles
 $t \rightarrow \infty$ time

equilibration behavior aka quasi-invariant limit

⇒ existence, structure of s.

⇒ speed to equilibrium

o) Generalise this for different costs.

⇒ Frouca

⇒ Andrew Duncan Stein Wasserstein
GV

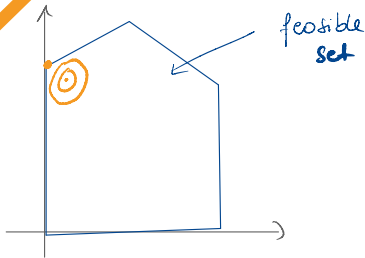
Entropic regularisation

The regularised OT problem reads as

$$\min \left(\sum_{ij} c_{ij} P_{ij} + \overbrace{\varepsilon P_{ij} \log P_{ij}}^{\text{entropic regularisation}} \right), \quad (\text{OT})_{\varepsilon}$$

among all admissible transportation plans and for a given $\varepsilon > 0$. The second term corresponds to the variational derivative of the negative entropy

objective $H(P) := - \sum_{ij} P_{ij} (\log(P_{ij}) - 1)$.



o) $\varepsilon = 0$ minimisers lie on boundary of feasible set

o) $\varepsilon > 0$ moves the min to interior

\Rightarrow unique

\Rightarrow solution to $(\text{OT})_{\varepsilon}$ blurred

$(OT)_\epsilon$

\rightarrow $\exists!$ unique solution P

\Rightarrow Solutions of $(OT)_\epsilon$ converge to sol of (OT)
but NO convergence rates

P_ϵ P

\Rightarrow Convergence of $(OT)_\epsilon$ deteriorates as $\epsilon \rightarrow 0$

\Rightarrow Solve problem extremely efficiently!

\Rightarrow Sinkhorn-Knopp

Sinkhorn

Given matrix A with pos. entries, can we find D_1 and D_2 s.t. $D_1 A D_2$ is doubly stochastic

Ide: \rightarrow Heuristic prop. fitting (IFPP)
 \rightarrow RAS method
 \rightarrow matrix scaling

Kullback-Leibler divergence between discrete measures

$$KL(P, K) := \sum_{ij} f\left(\frac{P_{ij}}{K_{ij}}\right) K_{ij} \text{ for } f(t) = \begin{cases} t \log t & \text{if } t \geq 0 \\ +\infty & \text{if } t < 0. \end{cases}$$

Gibb's
kernel
- C/ϵ
 $\kappa = e^{-C/\epsilon}$

$(OT)_\epsilon$ is equivalent to

$$\min K_\epsilon KL(P, K)$$

$$(OT)_\epsilon = \sum C_{ij} P_{ij} + \epsilon P_{ij} \log P_{ij}$$

$$KL(P, K) = \frac{P_{ij}}{K_{ij}} \log\left(\frac{P_{ij}}{K_{ij}}\right) K_{ij} = P_{ij} \log P_{ij} + \frac{1}{\epsilon} P_{ij} C_{ij}$$

Proposition

The regularised OT problem has a unique solution $P \in \mathbb{R}^{n \times m}$ of the form

$$P_{ij} = u_i K_{ij} v_j,$$

where $u \in \mathbb{R}_+^n$ and $v \in \mathbb{R}_+^m$ are two (unknown) scaling vectors.

K - Gibbs kernel

Dual variables: $\varphi \in \mathbb{R}^n$, $\psi \in \mathbb{R}^m$

$$\mathcal{L}(P, \varphi, \psi) = \langle P, C \rangle - \varepsilon H(P) - \langle \varphi, P \mathbb{1}_m - \mu \rangle \\ - \langle \psi, P^T \mathbb{1}_n - \nu \rangle$$

OC:

$$\frac{\partial \mathcal{L}}{\partial P_{ij}} = C_{ij} - \varepsilon \log P_{ij} - \varphi_i - \psi_j = 0$$
$$\begin{array}{ccc} -\varphi_i/\varepsilon & -C_{ij}/\varepsilon & -\psi_j/\varepsilon \\ P_{ij} = e & e & e \\ \underbrace{\quad} & \underbrace{\quad} & \underbrace{\quad} \\ := u & := K & := v \end{array}$$

Sinkhorn algorithm: Let $\mu \in \mathbb{R}^n$ and $\nu \in \mathbb{R}^m$, initialise v^0 and set $\varepsilon > 0$.

- Update $u^{(k+1)} := \frac{\mu}{Kv^k}$
- Update $v^{(k+1)} := \frac{\nu}{K^T u^{(k)}}$
- Go to first bullet until convergence

Calculate the corresponding OT plan

$$P = \text{diag}(u) K \text{diag}(v).$$

o) (u, v) have to be chosen that constraints are satisfied

$$\begin{aligned} \text{diag}(u) K \text{diag}(v) \mathbb{1}_m &= \mu & \Rightarrow & u \odot (Kv) = \mu \\ \text{diag}(v) K^T \text{diag}(u) \mathbb{1}_n &= \nu \end{aligned}$$

element wise mult
↓

o) $\varepsilon \rightarrow 0$ $K = c^{-c/\varepsilon} \Leftarrow$ problematic \Rightarrow Log scaling
Schmitzer...

Rapid developments:

- o) Different reg. terms
- o) Connections to proximal alg.

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