

# Recent perspectives on Discontinuous Galerkin methods

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From joint works with  
Antonietti, Arnold, Cockburn, Hughes, Marini, Masud, Süli,....

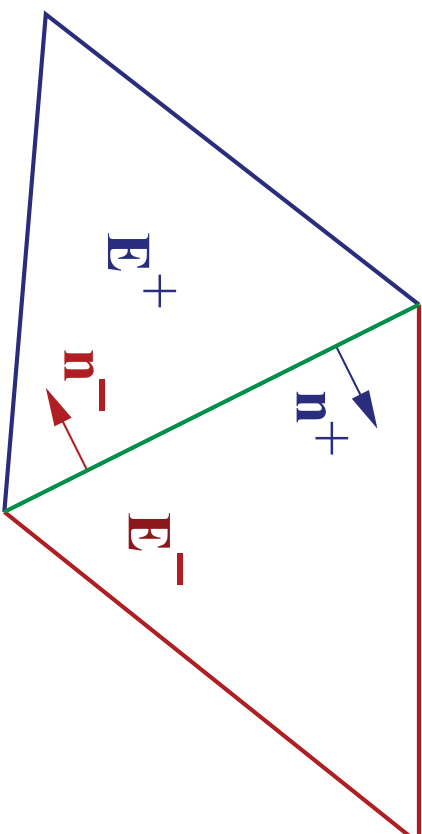
Warwick, June 30th - July 3rd , 2009

## PLAN:

- Original Derivation of DG Methods
- The Weighted Residuals Formulation
- The choice of the weights
- Some numerical Results

## AVERAGES AND JUMPS

$\mathcal{T}_h$ : decomposition of  $\Omega$  in elements  $K$ ;  $\mathcal{E}_h$ =edges of  $\mathcal{T}_h$ .



Definition of average and jump on an internal edge:

$$\{v\} = \frac{v^+ + v^-}{2}; \quad \llbracket v \rrbracket = v^+ \mathbf{n}^+ + v^- \mathbf{n}^- \quad \forall e \in \mathcal{E}_h^\circ \equiv \text{internal edges}$$

$$\{\boldsymbol{\tau}\} = \frac{\boldsymbol{\tau}^+ + \boldsymbol{\tau}^-}{2}; \quad \llbracket \boldsymbol{\tau} \rrbracket = \boldsymbol{\tau}^+ \mathbf{n}^+ + \boldsymbol{\tau}^- \mathbf{n}^- \quad \forall e \in \mathcal{E}_h^\circ \equiv \text{internal edges}$$

On the boundary edges:  $\llbracket v \rrbracket = v \mathbf{n}$ ;  $\{\boldsymbol{\tau}\} = \boldsymbol{\tau}$

## A MAGIC FORMULA

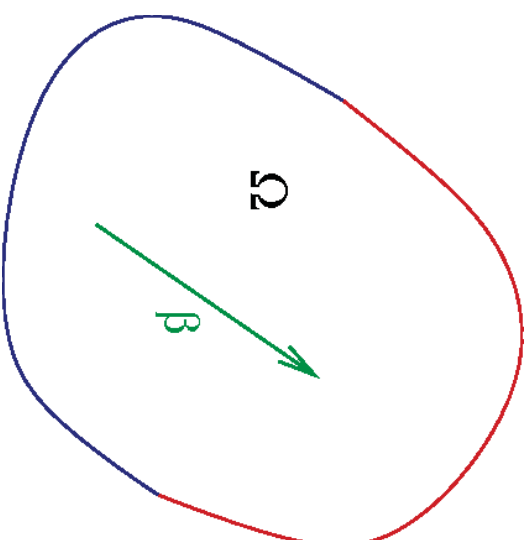
Assume that  $q$  is an edge-wise smooth scalar, and  $\tau$  an edge-wise smooth vector. We obviously accept that they have different values on the two sides of the same edge. Then, using the above definitions of jump  $[[\cdot]]$  and average  $\{\cdot\}$ , we have

$$\sum_K \int_{\partial K} q \tau \cdot \mathbf{n} ds = \sum_e \int_e [[q]] \cdot \{\tau\} ds + \sum_{e'} \int_{e'} \{q\} [[\tau]] ds$$

where  $e$  ranges over all edges and  $e'$  ranges over internal edges.

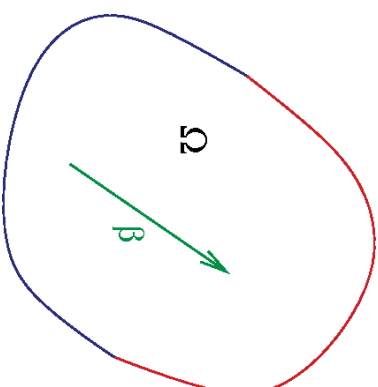
Clearly, there is **nothing** magic or deep: just *reordering terms* in the *sum*. But it is surely **nice**.

## A HYPERBOLIC MODEL PROBLEM



Let  $\Omega$  be a bounded polygonal domain in  $\mathbf{R}^2$ , and let the advective velocity field  $\beta = (\beta_1, \beta_2)^T$  be a vector-valued function defined on  $\overline{\Omega}$  with  $\beta_i \in C^1(\overline{\Omega})$ ,  $i = 1, 2$ .

## A HYPERBOLIC MODEL PROBLEM



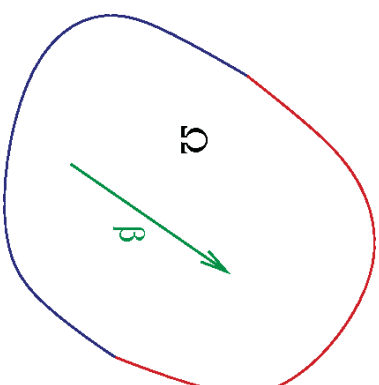
We define the *inflow* and *outflow* parts of  $\Gamma = \partial\Omega$  in the usual fashion:

$$\Gamma_- = \{x \in \Gamma : \beta(x) \cdot \mathbf{n}(x) < 0\} = \text{inflow},$$

$$\Gamma_+ = \{x \in \Gamma : \beta(x) \cdot \mathbf{n}(x) > 0\} = \text{outflow},$$

where  $\mathbf{n}(x)$  denotes the unit **outward** normal vector to  $\Gamma$  at  $x \in \Gamma$ .

## A HYPERBOLIC MODEL PROBLEM



Let moreover  $\gamma \in C(\bar{\Omega})$  be the reactive term,  $f \in L^2(\Omega)$  be the external source, and  $g \in L^2(\Gamma_-)$  be the Dirichlet datum.

As a model problem we will consider the hyperbolic boundary value problem

$$\begin{aligned} \mathcal{L}u \equiv \operatorname{div}(\beta u) + \gamma u &= f && \text{in } \Omega, \\ u &= g && \text{on } \Gamma_- \end{aligned}$$

Let us see the DG formulation (Lesaint-Raviart, Reed-Hill).

## ORIGINAL DERIVATION OF THE DG METHOD

Multiply the equation by a test function  $v_h$ , and integrate over  $\Omega$ :

$$\int_{\Omega} (\operatorname{div}(\beta u) + \gamma u) v_h \, dx = \int_{\Omega} f v_h \, dx.$$

Then integrate by parts the first term:

$$\sum_{K \in \mathcal{T}_h} \int_K (-u (\beta \cdot \nabla v_h) + \gamma u v_h) \, dx + \sum_{K \in \mathcal{T}_h} \int_{\partial K} (\beta \cdot \mathbf{n}) u v_h \, ds = \int_{\Omega} f v_h \, dx.$$

Using the magic formula,  $[[\beta u]] = 0$ , and  $u = g$  on  $\Gamma_-$ :

$$\begin{aligned} & \sum_{K \in \mathcal{T}_h} \int_K (-u (\beta \cdot \nabla v_h) + \gamma u v_h) \, dx \\ & + \sum_{e \in \mathcal{T}_h^-} \int_e \{\beta u\} \cdot [[v_h]] \, ds + \sum_{e \in \mathcal{T}_h^-} \int_e \beta \cdot \mathbf{n} g v_h \, ds = \int_{\Omega} f v_h \, dx. \end{aligned}$$



Then you write the equation putting  $u_h$  instead of  $u$

$$\begin{aligned} & \sum_{K \in \mathcal{T}_h} \int_K (-u_h (\boldsymbol{\beta} \cdot \nabla v_h) + \gamma u_h v_h) dx \\ & + \sum_{e \in \Gamma_-} \int_e \{\beta u_h\} \cdot [v_h] ds + \sum_{e \in \Gamma_-} \int_e \boldsymbol{\beta} \cdot \mathbf{n} g v_h ds = \int_{\Omega} f v_h dx. \end{aligned}$$

Finally you substitute the *average*  $\{\beta u_h\}$  by the *upwind average*  $\{\beta u\}_{up}$ , defined, on every edge, as the value of  $u_h$  **coming from the upwind triangle**:

$$\begin{aligned} & \sum_{K \in \mathcal{T}_h} \int_K (-u_h (\boldsymbol{\beta} \cdot \nabla v_h) + \gamma u_h v_h) dx \\ & + \sum_{e \in \Gamma_-} \int_e \{\beta u_h\}_{up} \cdot [v_h] ds + \sum_{e \in \Gamma_-} \int_e \boldsymbol{\beta} \cdot \mathbf{n} g v_h ds = \int_{\Omega} f v_h dx. \end{aligned}$$

## AN ELLIPTIC MODEL PROBLEM (DARCY)

Let  $\kappa \in \mathcal{L}^\infty(\Omega)$  be the diffusion coefficient, and consider the problem:

$$\begin{cases} Au \equiv -\operatorname{div}(\kappa \nabla u) = f & \text{in } \Omega \\ u = 0 & \text{on } \Gamma = \partial\Omega \end{cases}$$

It is often convenient to introduce the flux  $\boldsymbol{\sigma} = -\kappa \nabla u$  so that the problem splits in two equations

$$\begin{cases} \kappa^{-1} \boldsymbol{\sigma} + \nabla u = 0 & \text{in } \Omega \\ \operatorname{div} \boldsymbol{\sigma} = f & \text{in } \Omega \\ u = 0 & \text{on } \Gamma \end{cases}$$

Let us see its DG formulation (Arnold, Wheeler, Douglas-Dupont)

You multiply the equation by a test function  $v_h$  and integrate over  $\Omega$ . Then integrate by parts.

$$\int_{\Omega} \kappa \nabla u \cdot \nabla_h v_h dx - \sum_K \int_{\partial K} \kappa \nabla u \cdot \mathbf{n} v_h ds = \int_{\Omega} f v_h dx.$$

Rearranging terms with the magic formula you have

$$\int_{\Omega} \kappa \nabla u \cdot \nabla_h v_h - \sum_e \int_e \llbracket v_h \rrbracket \cdot \{ \kappa \nabla u \} - \sum_{e'} \int_{e'} \llbracket \kappa \nabla u \rrbracket \{ v_h \} = \int_{\Omega} f v_h.$$

Now you say: "Oh, but I know that  $u$  is smooth: hence  $\llbracket \kappa \nabla u \rrbracket$  is zero and I can forget about it!" You then write

$$\int_{\Omega} \kappa \nabla u \cdot \nabla_h v_h dx - \sum_e \int_e \llbracket v_h \rrbracket \cdot \{ \kappa \nabla u \} ds = \int_{\Omega} f v_h dx.$$

You had

$$\int_{\Omega} \kappa \nabla u \cdot \nabla_h v_h dx - \sum_e \int_e \llbracket v_h \rrbracket \cdot \{\kappa \nabla u\} ds = \int_{\Omega} f v_h dx.$$

Then you say: "Since  $u$  is smooth, then also  $\llbracket u \rrbracket = 0$ !" And you add a term to restore symmetry

$$\int_{\Omega} \kappa \nabla u \cdot \nabla_h v_h - \sum_e \int_e \llbracket v_h \rrbracket \cdot \{\kappa \nabla u\} - \sum_e \int_e \llbracket u \rrbracket \cdot \{\kappa \nabla_h v_h\} = \int_{\Omega} f v_h.$$

Then you write  $u_h$  in place of  $u$

$$\int_{\Omega} \kappa \nabla_h u_h \cdot \nabla_h v_h - \sum_e \int_e \llbracket v_h \rrbracket \cdot \{\kappa \nabla_h u_h\} - \sum_e \int_e \llbracket u_h \rrbracket \cdot \{\kappa \nabla_h v_h\} = \int_{\Omega} f v.$$

Your discrete problem is now

$$\int_{\Omega} \kappa \nabla_h u_h \cdot \nabla_h v_h - \sum_e \int_e \llbracket v_h \rrbracket \cdot \{ \kappa \nabla_h u_h \} - \sum_e \int_e \llbracket u_h \rrbracket \cdot \{ \kappa \nabla_h v_h \} = \int_{\Omega} f v_h.$$

Then you say: "Gosh! My method is unstable! However, since  $\llbracket u \rrbracket = 0$ , I can add a stabilizing term"

$$\begin{aligned} \int_{\Omega} \kappa \nabla_h u_h \cdot \nabla_h v_h - \sum_e \int_e \llbracket v_h \rrbracket \cdot \{ \kappa \nabla_h u_h \} - \sum_e \int_e \llbracket u_h \rrbracket \cdot \{ \kappa \nabla_h v_h \} \\ + \sum_e \frac{\kappa \gamma}{|e|} \int_e \llbracket u_h \rrbracket \cdot \llbracket v_h \rrbracket = \int_{\Omega} f v_h. \end{aligned}$$

And you are happy. This is "IP" (Interior Penalty).

## DG MIXED FORMULATION

Let us see the DG mixed formulation (Bassi-Rebay, Cockburn-Shu).  
You multiply the equations  $\kappa^{-1}\boldsymbol{\sigma} + \nabla u = 0$  and  $\operatorname{div}\boldsymbol{\sigma} = f$  by the test functions  $\boldsymbol{\tau}$  and  $v$ , respectively, and integrate by parts

$$\begin{aligned} \int_{\Omega} \kappa^{-1} \boldsymbol{\sigma} \cdot \boldsymbol{\tau} - \sum_K \int_K u \operatorname{div} \boldsymbol{\tau} \, dx + \sum_K \int_K \hat{u} \boldsymbol{\tau} \cdot \mathbf{n} \, ds &= 0 \\ - \sum_K \int_K \boldsymbol{\sigma} \cdot \nabla v \, dx + \sum_K \int_K v \hat{\boldsymbol{\sigma}} \cdot \mathbf{n} \, ds &= \int_{\Omega} f v \end{aligned}$$

where  $\hat{u}$  and  $\hat{\boldsymbol{\sigma}}$  are the numerical fluxes meant to approximate  $u|_{\partial E}$  and  $\boldsymbol{\sigma}|_{\partial E} \equiv -\kappa \nabla u|_{\partial E}$  (respectively), to be modelled later on.

Then you apply the magic formula assuming that  $\hat{u}$  and  $\hat{\sigma}$  are single valued

$$\begin{aligned} \int_{\Omega} \kappa^{-1} \boldsymbol{\sigma} \cdot \boldsymbol{\tau} - \int_{\Omega} u \operatorname{div}_h \boldsymbol{\tau} \, dx + \sum_{e'} \int_{e'} \hat{u} [[\boldsymbol{\tau}]] \, ds = 0 \\ - \int_{\Omega} \boldsymbol{\sigma} \cdot \nabla_h v \, dx + \sum_e \int_e \hat{\boldsymbol{\sigma}} [[v]] \, ds = \int_{\Omega} f v \end{aligned}$$

Then you put  $\boldsymbol{\sigma}_h$  in place of  $\boldsymbol{\sigma}$  and  $u_h$  in place of  $u$ , and you integrate by parts back (!) the first equation

$$\begin{aligned} \int_{\Omega} \kappa^{-1} \boldsymbol{\sigma}_h \cdot \boldsymbol{\tau} + \int_{\Omega} \nabla_h u_h \cdot \boldsymbol{\tau} + \sum_{e'} \int_{e'} \{\hat{u} - u_h\} [[\boldsymbol{\tau}]] \, ds + \sum_e \int_e [[u_h]] \{\boldsymbol{\tau}\} \, ds = 0 \\ - \int_{\Omega} \boldsymbol{\sigma} \cdot \nabla_h v \, dx + \sum_e \int_e \hat{\boldsymbol{\sigma}} [[v]] \, ds = \int_{\Omega} f v \end{aligned}$$

If your choice of  $\hat{u}$  depends only on  $u_h$ , and if the gradients of the discretized scalars are contained in the space of discretized vectors, you can use the first equation

$$\int_{\Omega} \kappa^{-1} \boldsymbol{\sigma}_h \cdot \boldsymbol{\tau} + \int_{\Omega} \nabla u_h \cdot \boldsymbol{\tau} + \sum_{e'} \int_{e'} \{ \hat{u} - u_h \} \llbracket \boldsymbol{\tau} \rrbracket ds - \sum_e \int_e \llbracket u_h \rrbracket \{ \boldsymbol{\tau} \} ds = 0$$

to express  $\boldsymbol{\sigma}_h$  directly as an explicit function of  $u_h$

$$\boldsymbol{\sigma}_h = \boldsymbol{\sigma}_h(u_h)$$

and substitute in the second

$$- \int_{\Omega} \boldsymbol{\sigma}(u_h) \cdot \nabla_h v dx + \sum_e \int_e \hat{\boldsymbol{\sigma}} \llbracket v \rrbracket ds = \int_{\Omega} f v.$$

For various choices of  $\hat{u}$  and  $\hat{\boldsymbol{\sigma}}$  you get a whole ZOO of methods (Arnold-B-Cockburn-Marini).



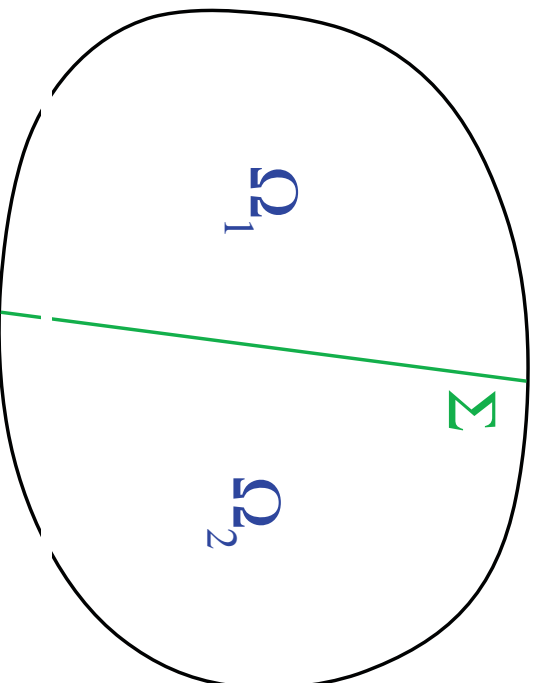
## THE WEIGHTED RESIDUALS APPROACH -1

(B-Cockburn-Marini-Süli - 2006)

Let us see the basic ideas behind it. Assume that we want to solve the problem

$$\operatorname{div}(\beta u) + \gamma u = f \text{ in } \Omega \equiv \Omega_1 \cup \Sigma \cup \Omega_2$$

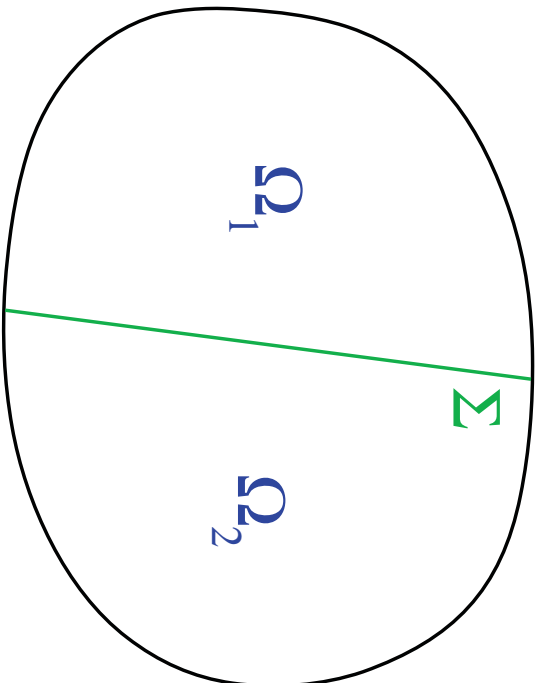
with, say,  $\beta \cdot \mathbf{n}u = 0$  on  $\Gamma_-$ . Then we have



$$\operatorname{div}(\beta u) + \gamma u = f \text{ in } \Omega_i \quad (i = 1, 2)$$

$$[\beta u] = 0 \text{ on } \Sigma \text{ and on } \Gamma_-$$

## THE WEIGHTED RESIDUALS APPROACH - 2



$$\operatorname{div}(\beta u) + \gamma u = f \text{ in } \Omega_i \quad (i = 1, 2)$$

$$[\beta u] = 0 \text{ on } \Sigma \text{ and on } \Gamma_-$$

Accordingly you could choose two operators,  $B_0$  and  $B_1$  and write

$$\begin{aligned} & \sum_{i=1}^2 \int_{\Omega_i} (\operatorname{div}(\beta u_h) + \gamma u_h - f) B_0 v_h dx \\ & + \int_{\Sigma \cup \Gamma_-} [\beta u_h] B_1 v_h ds = 0 \quad \forall v_h \end{aligned}$$

## THE WEIGHTED RESIDUALS APPROACH -3

Similarly, if you want to solve the problem

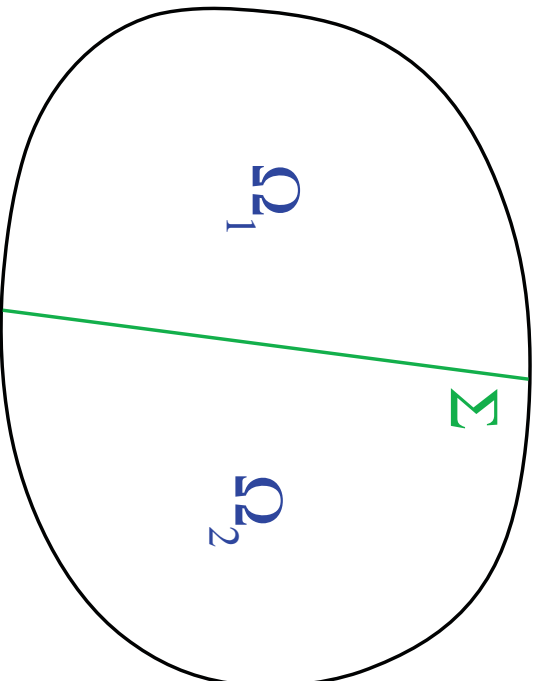
$$-\operatorname{div}(\kappa \nabla u) = f \text{ in } \Omega \equiv \Omega_1 \cup \Sigma \cup \Omega_2$$

with, say,  $u = 0$  on  $\Gamma$ , then you have instead

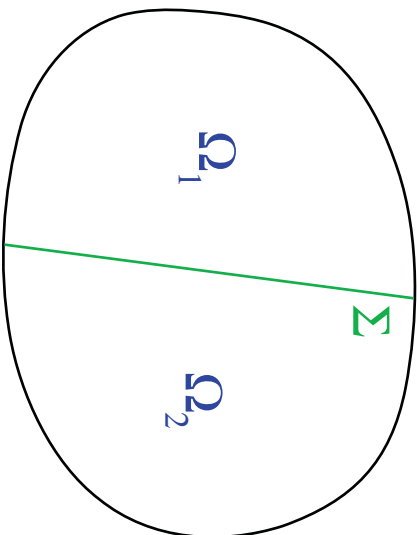
$$-\operatorname{div}(\kappa \nabla u) = f \text{ in } \Omega_i \quad (i = 1, 2)$$

$$[u] = 0 \text{ on } \Sigma \text{ and on } \Gamma$$

$$[\kappa \nabla u] = 0 \text{ on } \Sigma$$



## THE WEIGHTED RESIDUALS APPROACH - 4



$$-\operatorname{div}(\kappa \nabla u) = f \text{ in } \Omega_i \quad (i = 1, 2)$$

$$[u] = 0 \text{ on } \Sigma \text{ and on } \Gamma$$

$$[\kappa \nabla u] = 0 \text{ on } \Sigma$$

Then you could choose **three** operators,  $B_0$ ,  $B_1$  and  $B_2$ , and write

$$\begin{aligned} & \sum_{i=1}^2 \int_{\Omega_i} (-\operatorname{div}(\kappa \nabla u_h) - f) B_0 v_h dx \\ & + \int_{\Sigma_{\text{int}}} [[u_h]] \cdot B_1 v_h ds + \int_{\Sigma} [[\kappa \nabla u_h]] B_2 v_h ds = 0 \quad \forall v_h \end{aligned}$$

## CHOICE OF THE WEIGHTS -1

Starting from

$$((\operatorname{div}(\beta u_h) + \gamma u_h - f), B_0 v_h)_h + \langle \|\beta u_h\|, B_1 v_h \rangle_- = 0 \quad \forall v_h$$

you can choose  $B_0 v_h \equiv v_h$  and integrate by parts

$$\begin{aligned} (u_h, -\beta \cdot \nabla v_h + \gamma v_h)_h - (f, v_h)_h \\ + \langle \{\beta u_h\}, \|v_h\| \rangle + \langle \|\beta u_h\|, \{v_h\} \rangle - \\ + \langle \|\beta u_h\|, B_1 v_h \rangle_- = 0 \quad \forall v_h \end{aligned}$$

## CHOICE OF THE WEIGHTS - 2

Having

$$\begin{aligned} & (u_h, -\beta \cdot \nabla v_h + \gamma v_h)_h - (f, v_h)_h \\ & + \langle \{\beta u_h\}, \|v_h\| \rangle + \langle \|\beta u_h\|, \{v_h\} \rangle - \\ & + \langle \|\beta u_h\|, B_1 v_h \rangle - = 0 \quad \forall v_h \end{aligned}$$

you can choose  $B_1 v_h = -\{v_h\} + \frac{|\beta \cdot \mathbf{n}|}{2|\beta|} \mathbf{n} \cdot \|v_h\|$  and get

$$\begin{aligned} & (u_h, -\beta \cdot \nabla v_h + \gamma v_h)_h - (f, v_h)_h \\ & + \langle \{\beta u_h\}_{\text{upw}}, \|v_h\| \rangle - = 0 \quad \forall v_h \end{aligned}$$

### CHOICE OF THE WEIGHTS - 3

On the other hand from

$$(\operatorname{div}(\beta u_h) + \gamma u_h - f, B_0 v_h)_h + \langle \|\beta u_h\|, B_1 v_h \rangle_{-} = 0 \quad \forall v_h$$

you can (brutally) choose  $B_0 v_h \equiv \operatorname{div}(\beta v_h) + \gamma v_h$  and

$B_1 v_h = \mu(h) \|\beta v_h\|$  to get

$$\begin{aligned} (\operatorname{div}(\beta u_h) + \gamma u_h - f, \operatorname{div}(\beta v_h) + \gamma v_h)_h \\ + \mu(h) \langle \|\beta u_h\|, \|\beta v_h\| \rangle_{-} = 0 \quad \forall v_h \end{aligned}$$

## CHOICE OF THE WEIGHTS - 4

$$(\operatorname{div}(\beta u_h) + \gamma u_h - f, B_0 v_h)_h + \langle \|\beta u_h\|, B_1 v_h \rangle_{-} = 0 \quad \forall v_h$$

However, you can also take  $B_0 v_h \equiv v_h$  and  $B_1 v_h = \mu(h) \|\beta v_h\|$  for  $\mu(h)$  big enough to get

$$(\operatorname{div}(\beta u_h) + \gamma u_h - f, v_h)_h + \mu(h) \langle \|\beta u_h\|, \|\beta v_h\| \rangle_{-} = 0 \quad \forall v_h$$

that surely works for  $\gamma + \nabla \cdot \beta > 0$ .



## CHOICE OF THE WEIGHTS FOR DARCY-1

Coming back to the Darcy problem  $-\operatorname{div}(\kappa \nabla u) = f$ , with zero Dirichlet boundary conditions, our residual equations are now:

- $\operatorname{div} \kappa \nabla u + f = 0$  in each element
- $[[u]] = 0$  on each edge
- $[[\kappa \nabla u]] = 0$  on each internal edge

## CHOICE OF THE WEIGHTS FOR DARCY-2

Then we have to choose **three** operators  $B_0$ ,  $B_1$ , and  $B_2$ , and to write

$$\begin{aligned} & (A u_h - f, B_0(v_h))_{h^+} \\ & < \llbracket u_h \rrbracket, B_1(v_h) \rangle_h + < \llbracket \kappa \nabla u_h \rrbracket, B_2(v_h) \rangle_h^0 = 0 \quad \forall v_h \end{aligned}$$

where again

$$(u, v)_h = \sum_{K \in \mathcal{T}_h} \int_K u v \, dx \quad < u, v \rangle_h = \sum_{e \in \mathcal{E}_h} \int_e u v \, ds$$

and  $< u, v \rangle_h^0$  runs only on internal edges

## A POSSIBLE CHOICE FOR $B_0$

Choosing  $B_0(v) \equiv v$  and using the magic formula, we can write:

$$\begin{aligned}
 (Au, B_0v)_h &\equiv (-\operatorname{div}(\kappa \nabla u_h), v_h)_h \\
 &= (\kappa \nabla u_h, \nabla v_h)_h - \sum_K \int_{\partial K} \kappa \nabla u_h \cdot \mathbf{n} v_h \, ds \\
 &= (\kappa \nabla u_h, \nabla v_h)_h - \langle \{\kappa \nabla u_h\}, \llbracket v_h \rrbracket \rangle_h - \langle \llbracket \kappa \nabla u_h \rrbracket, \{v_h\} \rangle_h.
 \end{aligned}$$

## A POSSIBLE CHOICE FOR $B_0$

With the previous choice  $B_0(v) \equiv v$  our method becomes then

$$\begin{aligned} & (\kappa \nabla u_h, \nabla v_h)_h - (f, v_h) \\ & \quad - \langle \{\kappa \nabla u_h\}, \llbracket v_h \rrbracket \rangle_h - \langle \llbracket \kappa \nabla u_h \rrbracket, \{v_h\} \rangle_h^0 \\ & \quad + \langle \llbracket u_h \rrbracket, B_1(v_h) \rangle_h + \langle \llbracket \kappa \nabla u_h \rrbracket, B_2(v_h) \rangle_h^0 = 0 \end{aligned}$$

for all  $v_h$  in the discrete space.

## A POSSIBLE CHOICE FOR $B_2$

With the previous choice  $B_0(v) \equiv v$  our method becomes then

$$\begin{aligned} & (\kappa \nabla u_h, \nabla v_h)_h - (f, v_h) \\ & \quad - \langle \{\kappa \nabla u_h\}, \llbracket v_h \rrbracket \rangle_h - \langle \llbracket \kappa \nabla u_h \rrbracket, \{v_h\} \rangle_h^0 \\ & \quad + \langle \llbracket u_h \rrbracket, B_1(v_h) \rangle_h + \langle \llbracket \kappa \nabla u_h \rrbracket, B_2(v_h) \rangle_h^0 = 0 \end{aligned}$$

for all  $v_h$  in the discrete space. The **strong** temptation is to use

$$B_2(v_h) = \{v_h\} \text{ (in order to kill the second purple term)}$$

.

## A POSSIBLE CHOICE FOR $B_1$

With the previous choice  $B_0(v) \equiv v$  our method becomes then

$$\begin{aligned} & (\kappa \nabla u_h, \nabla v_h)_h - (f, v_h) \\ & \quad - \langle \{\kappa \nabla u_h\}, \llbracket v_h \rrbracket \rangle_{>h} \\ & \quad + \langle \llbracket u_h \rrbracket, B_1(v_h) \rangle_{>h} \\ & \quad = 0 \end{aligned}$$

for all  $v_h$  in the discrete space. The **strong** temptation is to use

$B_2(v_h) = \{v_h\}$  (in order to kill the second purple term) and

$B_1(v_h) = -\{\kappa \nabla u_h\}$  in order to symmetrize the first purple term.

## A POSSIBLE CHOICE FOR $B_1$

With the previous choice  $B_0(v) \equiv v$  our method becomes then

$$\begin{aligned} & (\kappa \nabla u_h, \nabla v_h)_h - (f, v_h) \\ & \quad - \langle \{\kappa \nabla u_h\}, \llbracket v_h \rrbracket \rangle_{>h} \\ & \quad - \langle \llbracket u_h \rrbracket, \{\kappa \nabla u_h\} \rangle_{>h} \\ & \quad = 0 \end{aligned}$$

for all  $v_h$  in the discrete space. The **strong** temptation is to use

$B_2(v_h) = \{v_h\}$  (in order to kill the second purple term) and

$B_1(v_h) = -\{\kappa \nabla u_h\}$  in order to symmetrize the first purple term. But

you could also use  $B_1(v_h) = +\{\kappa \nabla u_h\}$  to get B-O

## A POSSIBLE CHOICE FOR $B_1$

Surely, in all cases, you would need to add some stabilizing term to  $B_1$ . Hence, for instance, with  $B_0(v) \equiv v$ ,  $B_2(v_h) = \{v_h\}$ , and  $B_1(v_h) = -\{\kappa \nabla u_h\} + C_1(h)[[v_h]]$  the method becomes

$$\begin{aligned}
 (\kappa \nabla u_h, \nabla v_h)_h - (f, v_h) & \\
 & - \langle \{\kappa \nabla u_h\}, [[v_h]] \rangle_h \\
 & - \langle [[u_h]], \{\kappa \nabla u_h\} \rangle_h + C_1(h) \langle [[u_h]], [[u_h]] \rangle_h = 0 \quad \forall v_h
 \end{aligned}$$



## OTHER CHOICES OF THE WEIGHTS FOR DARCY

We had to choose **three** operators  $B_0$ ,  $B_1$ , and  $B_2$  in

$$\begin{aligned} (A u_h - f, B_0(v_h))_{h^+} \\ < \llbracket u_h \rrbracket, B_1(v_h) \rangle_h + \langle \llbracket \kappa \nabla u_h \rrbracket, B_2(v_h) \rangle_h^0 = 0 \quad \forall v_h \end{aligned}$$

A simple minded but viable choice would be to take  $B_0(v_h) = A v_h$ ,

$B_1(v_h) = C_1(h) \llbracket v_h \rrbracket$ , and  $B_2(v_h) = C_2(h) \llbracket \kappa \nabla u_h \rrbracket$  to reach

$$\begin{aligned} (A u_h - f, A v_h)_{h^+} \\ C_1(h) \langle \llbracket u_h \rrbracket, \llbracket v_h \rrbracket \rangle_h >_h + C_2(h) \langle \llbracket \kappa \nabla u_h \rrbracket, \llbracket \kappa \nabla u_h \rrbracket \rangle_h^0 >_h^0 = 0 \quad \forall v_h \end{aligned}$$

## OTHER CHOICES OF THE WEIGHTS FOR DARCY

We had to choose **three** operators  $B_0$ ,  $B_1$ , and  $B_2$  in

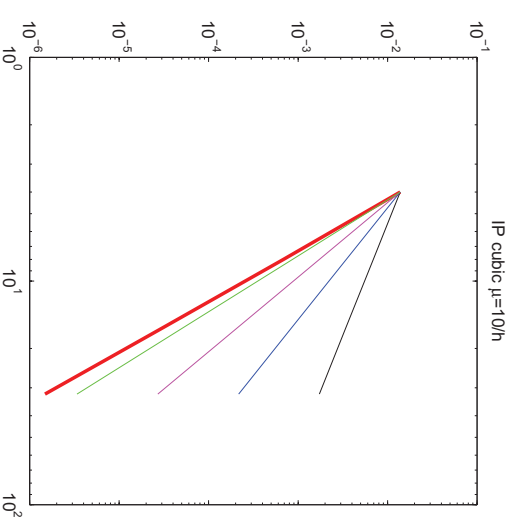
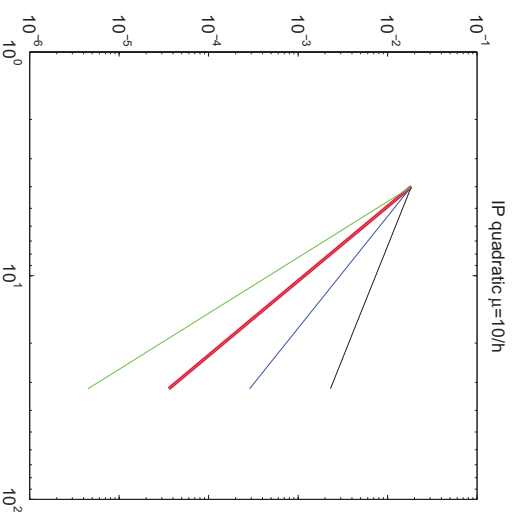
$$\begin{aligned} (A u_h - f, B_0(v_h))_{h^+} \\ < \llbracket u_h \rrbracket, B_1(v_h) \rangle_h + \langle \llbracket \kappa \nabla u_h \rrbracket, B_2(v_h) \rangle_h^0 = 0 \quad \forall v_h \end{aligned}$$

Now you could “play dumb” and take  $B_0(v_h) = v_h$ ,

$B_1(v_h) = C_1(h) \llbracket v_h \rrbracket$ , and  $B_2(v_h) = C_2(h) \llbracket \kappa \nabla u_h \rrbracket$  to reach

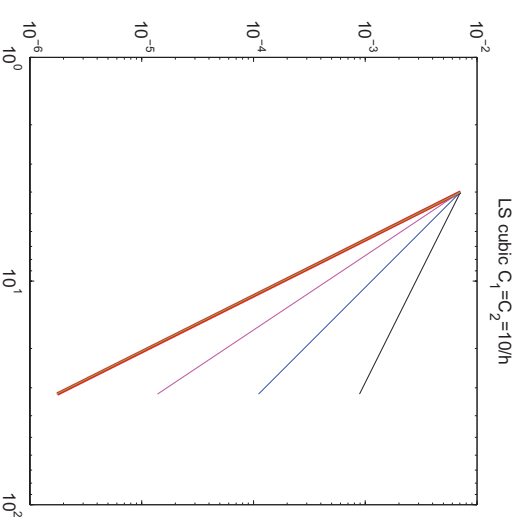
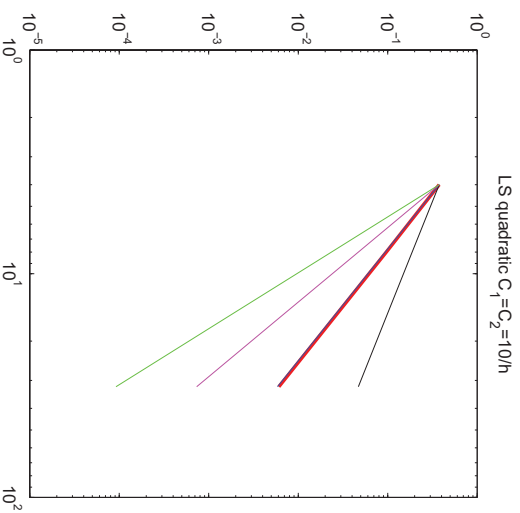
$$\begin{aligned} (A u_h - f, v_h)_{h^+} \\ C_1(h) \langle \llbracket u_h \rrbracket, \llbracket v_h \rrbracket \rangle_h >_h + C_2(h) \langle \llbracket \kappa \nabla u_h \rrbracket, \llbracket \kappa \nabla u_h \rrbracket \rangle_h^0 = 0 \quad \forall v_h \end{aligned}$$

## THE CLASSICAL CHOICE (IP)



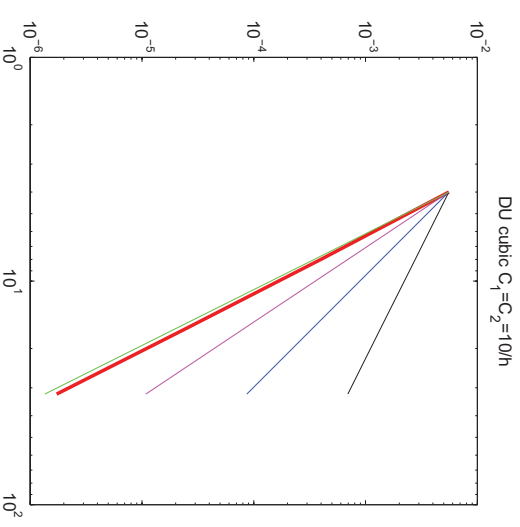
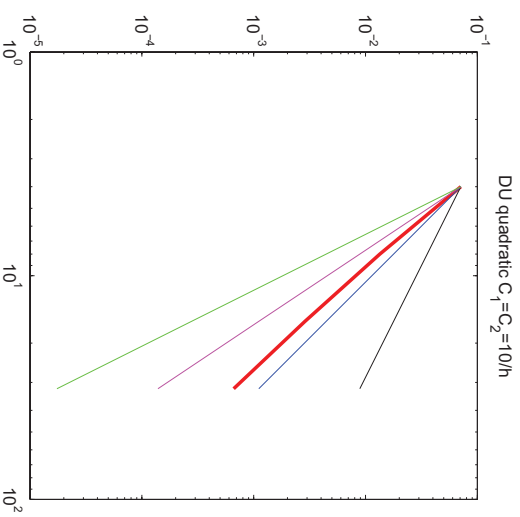
Left: Quadratic elements,  $C_1 = 10/h$ . Right: Cubic elements,  
 $C_1 = 10/h$ .

## THE LEAST SQUARES CHOICE



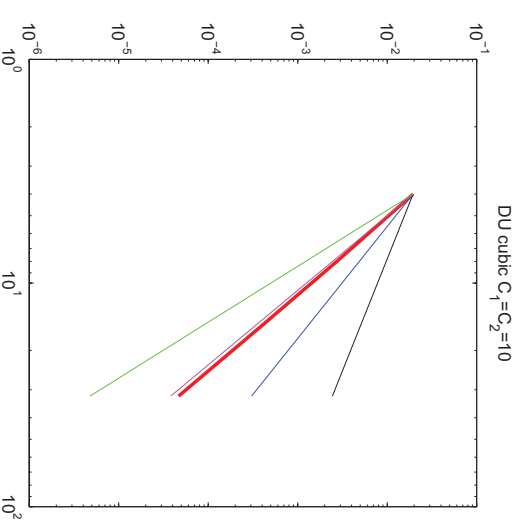
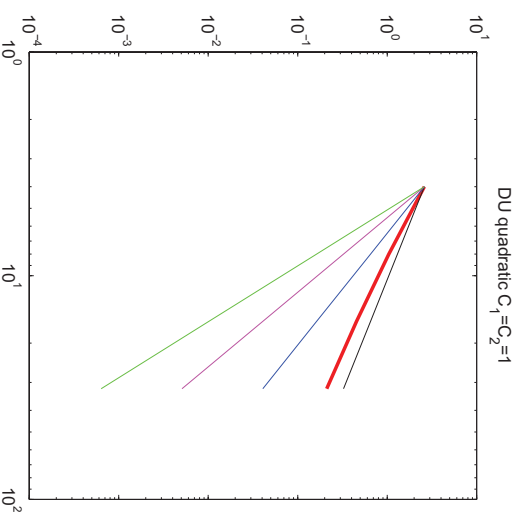
Left: Quadratic elements,  $C_1 = C_2 = 10/h$ . Right: Cubic elements,  $C_1 = C_2 = 10/h$ .

## THE DUMB CHOICE



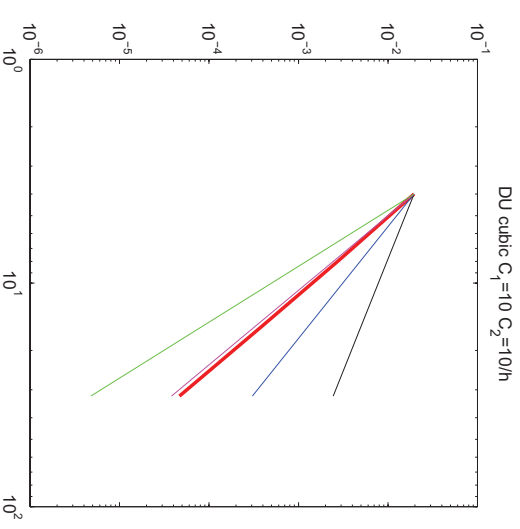
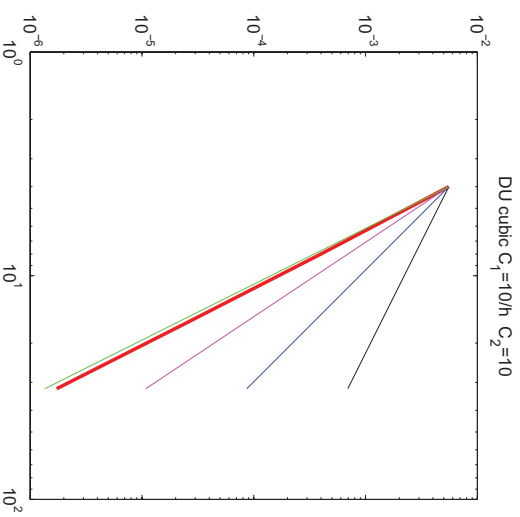
Left: Quadratic elements,  $C_1 = C_2 = 10/h$ . Right: Cubic elements,  $C_1 = C_2 = 10/h$ .

## THE DUMB CHOICE: SENSITIVITY



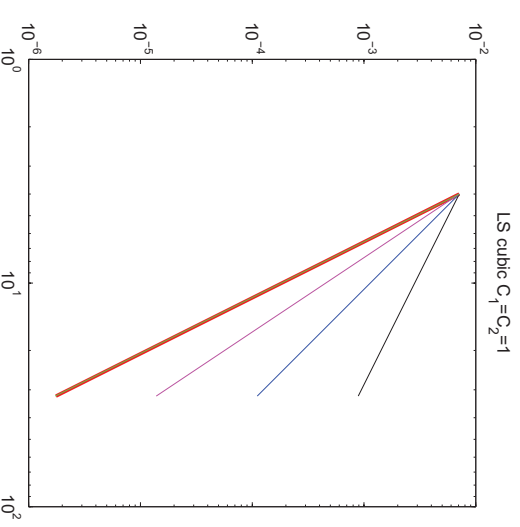
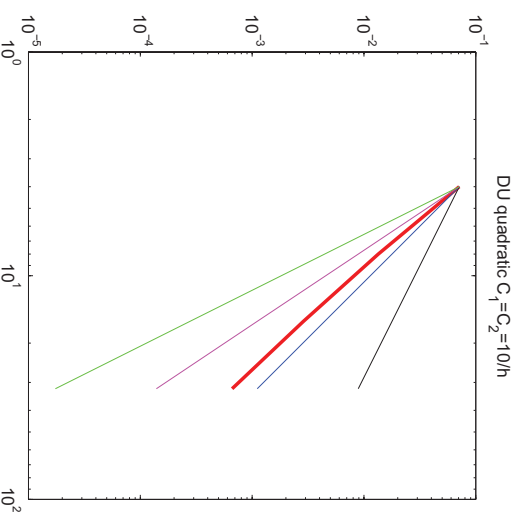
Left: Quadratic elements,  $C_1 = C_2 = 1$ . Right: Cubic elements,  $C_1 = C_2 = 10$ .

## THE DUMB CHOICE: SENSITIVITY



Left: Cubic elements,  $C_1 = 10/h$   $C_2 = 10$ . Right: Cubic elements,  
 $C_1 = 10$   $C_2 = 10/h$ .

## OTHER RESULTS



Left: Dumb, quadratic elements,  $C_1 = C_2 = 10/h$ . Right: Least Squares, cubic elements,  $C_1 = 1$   $C_2 = 1$ .



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- You could use WRDg because **finally you know what you are doing**