#### BAYESIAN INVERSE PROBLEMS FOR BURGERS AND HAMILTON-JACOBI EQUATIONS WITH WHITE NOISE FORCING

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We consider Burgers equation with white noise forcing:

$$rac{\partial u}{\partial t} + (u \cdot \nabla)u = f(x)\dot{W}(t), \quad u \in \mathbb{R}^d, \ x \in \mathbb{R}^d.$$
  
Assume:  $f(x) = -\nabla F(x)$ , and  $u(t,x) = \nabla \phi(t,x)$ ;

 $\phi$  satisfies the Hamilton-Jacobi equation:

$$\frac{\partial \phi(x,t)}{\partial t} + \frac{1}{2} |\nabla \phi(x,t)|^2 + F(x) \dot{W}(t) = 0.$$

• Burgers equation is a model for studying turbulence. It also has applications in non-equilibrium mechanics.

• We are interested in long time behavior: we consider the equations on  $(-\infty, T]$ .

• Suppose at  $t_1, t_2, \ldots, t_m$ , observations are made for velocity u and velocity potential  $\phi$  (subject to Gaussian noise);

we make inference on the white noise forcing on  $(-\infty, T]$ .

• Bayesian inverse problem for Navier-Stokes equations with model errors (stochastic forcing) is considered by Cotter, Dashti, Robinson and Stuart (2009)

• Given an initial condition  $\phi(x, t_0) = \phi_0(x)$ ,  $\phi(\cdot, t)$  is determined by Lax operator:

$$\phi(\cdot,t)=\mathcal{K}_{t_0,t}^W\phi_0.$$

• Lax-Oleinik formula:

$$\phi(x,t) = \inf\left\{\phi_0(\gamma(t_0)) + \int_{t_0}^t \frac{1}{2}|\dot{\gamma}(\tau)|^2 - F(\gamma(\tau))\dot{W}(\tau)d\tau\right\},\$$

where inf is taken with respect to all absolutely continuous curves  $\gamma$  s.t.  $\gamma(t) = x$ .

• We are interested in solutions that exist for all time, i.e.

$$\phi(\cdot,t) = \mathcal{K}_{t_0,t}^W \phi(\cdot,t_0), \quad \forall t_0 < t.$$

• E, Khanin, Mazel and Sinai (2000) and Iturriaga and Khanin (2003):

there is a unique solution  $\phi$  (within an *additive constant*) that exists for all time, i.e.

$$\phi(\cdot,t) = \mathcal{K}_{t_0,t}^{W}\phi(\cdot,t_0), \quad \forall t_0 < t.$$

- For all t:  $\phi(\cdot, t)$  is continuous, and Lipschitz.
- There is a unique spatially periodic solution u(t, x) for the Burgers equation that exists for all time.

# NON-PERIODIC SETTING



- For potential F(x) with a "big" maximum and a "big" minimum, H. and Khanin (2003) show that there is a solution  $\phi$  and a solution u that exist for all time.
- They are limit of finite time solutions with zero initial conditions.

# BAYESIAN INVERSE PROBLEM FOR H-J EQUATION

 $\bullet$  Formulation: As  $\phi$  is uniquely determined within a constant, and is continuous

$$\mathcal{G}(W) = \{\phi^W(x_i, t_i) - \phi^W(x_0, t_0), i = 1, \dots, m\} \in \mathbb{R}^m,$$

is uniquely determined by W.

Let y be a noisy observation of  $\mathcal{G}(W)$ :

$$y = \mathcal{G}(W) + \sigma.$$

The prior probability  $\mu_0$  is the Wiener measure on  $C(-\infty, t_{\max}]$  $(t_{\max} = \max t_i)$ .

Determine  $\mu^{y}(W) = \mathbb{P}(W|y)$ .

### BAYESIAN INVERSE PROBLEM FOR H-J EQUATION

Assuming a Gaussian noise  $\sigma \sim \mathcal{N}(0, \Sigma)$ , we aim to show:

• Bayes' formula holds:

$$rac{d\mu^y}{d\mu_0} \propto \exp(-\Phi(W;y))$$

where

$$\Phi(W; y) = \frac{1}{2} |y - \mathcal{G}(W)|_{\Sigma}^2 = \frac{1}{2} \langle \Sigma^{-1/2}(y - \mathcal{G}(W)), \Sigma^{-1/2}(y - \mathcal{G}(W)) \rangle.$$

• The posterior  $\mu^{y}$  is well-posed; in particular

$$d_{\mathrm{Hell}}(\mu^y,\mu^{y'})\leq c(r)|y-y'|_{\mathbb{R}^m},$$

when  $|y|_{\mathbb{R}^m} \leq r$  and  $|y'|_{\mathbb{R}^m} \leq r$ .

For  $y = \mathcal{G}(x) + \sigma$ ,  $x \in X$  a Banach space:

Cotter, Dashti, Robinson and Stuart showed:

(I) If  $\mathcal{G} : X \to \mathbb{R}^m$  is measurable, e.g. when it is continuous with respect to x, the Bayes' formula holds.

(II) When  $\mu_0$  is Gaussian, when  $|y_1|_{\mathbb{R}^m} \leq r$ ,  $|y_2|_{\mathbb{R}^m} \leq r$ 

$$|\Phi(x;y_1) - \Phi(x;y_2)| \le K(r)(1 + ||x||_X^q)|y_1 - y_2|_{\mathbb{R}^m}$$

then the posterior measure  $\mu^{y}$  is well-posed, i.e.

$$d_{\operatorname{Hell}}(\mu^{y_1},\mu^{y_2}) \leq c(r)|y_1-y_2|_{\mathbb{R}^m}.$$

### METRIC SPACE SETTING

- Our space  $C(-\infty, t_{max}]$  is not Banach;
- It is a metric space with the metric:

$$D(W_1, W_2) = \sum_{n=1}^{\infty} \frac{1}{2^n} \frac{\sup_{-n \le t \le t_{\max}} |W_1(t) - W_2(t)|}{1 + \sup_{-n \le t \le t_{\max}} |W_1(t) - W_2(t)|}.$$

- We need to formulate Bayesian inverse problems for **metric** spaces.
- For a metric space X, condition (I) of Cotter et al. still holds: If  $\mathcal{G}$  is continuous, then the Bayes' formula holds.

#### METRIC SPACE SETTING

For well-posedness: Condition (II) needs to be generalized.

(III) i)  $\Phi$  is locally bounded: for r > 0, if  $|y|_{\mathbb{R}^m} \le r$ 

$$0\leq \Phi(x;y)\leq M(r),$$

for  $x \in X(r) \subset X$ ,  $\mu_0(X(r)) > 0$ . ii) There is a  $G : \mathbb{R} \times X \to \mathbb{R}$ :  $G(r, .) \in L^2(X, d\mu_0)$ , and

$$|\Phi(x;y)-\Phi(x;y')|\leq G(r,x)|y-y'|_{\mathbb{R}^m},$$

when  $|y|_{\mathbb{R}^m} \leq r$  and  $|y'|_{\mathbb{R}^m} \leq r$ .

Then

$$d_{\operatorname{Hell}}(\mu^y,\mu^{y'})\leq c(r)|y-y'|_{\mathbb{R}^m}.$$

• We consider the **periodic case** first:

the forcing function f(x) and forcing potential F(x) are periodic; problems are on  $\mathbb{T}^d$ .

 $\mathcal{G}(W) = \{\phi(x_i, t_i) - \phi(x_0, t_0) : i = 1, ..., m\}.$ 

- To show the validity of the Bayes' formula, we show that  $\mathcal{G}: C(-\infty, t_{\max}] \to \mathbb{R}^m$  is continuous.
- To show well-posedness, we show conditions (III)(i) and (III)(ii).

### PERIODIC H-J EQUATION

- $\bullet$  First we show that  ${\cal G}$  is continuous.
- From the Lax-Oleinik formula: when  $D(W_k, W) \rightarrow 0$ , there are  $c_k$  independent of  $x_i$  and  $t_i$  s.t.

$$\phi^{W_k}(x_i, t_i) - \phi^{W}(x_i, t_i) - c_k \to 0, \quad i = 0, 1, \dots, m.$$

• 
$$\mathcal{G}(W) = \{\phi^W(x_i, t_i) - \phi^W(x_0, t_0), i = 1, \dots, m\},\$$

- $\mathcal{G}: C(-\infty, t_{\max}] \to \mathbb{R}^m$  is continuous. • The Bayes' formula holds:
  - The Bayes formula holds:

$$rac{d\mu^y}{d\mu_0} \propto \exp(-\Phi(W;y)) = \exp(-rac{1}{2}|y - \mathcal{G}(W)|_{\Sigma}^2).$$

# PERIODIC H-J EQUATION

• For well-posedness, we show (III)(i) and (III)(ii):

(III)(i) 
$$0 \le \Phi(W; y) \le M(r)$$
 when  $|y|_{\mathbb{R}^m} \le r$ ;

 $W \in X(r) \subset C(-\infty, t_{\sf max}]$ , X(r) of positive  $\mu_0$  measure.

from the Lax operator

$$\begin{aligned} |\mathcal{G}(W)|_{\mathbb{R}^m} &= |\{\phi^W(x_i, t_i) - \phi^W(x_0, t_0)\}|_{\mathbb{R}^m} \\ &\leq c \left(1 + \sum_{i=1}^m \max_{t_0 - 1 \leq \tau \leq t_i} |W(\tau) - W(t_i)|^2\right). \end{aligned}$$

$$\Phi(W; y) = \frac{1}{2} |y - \mathcal{G}(W)|_{\Sigma}^2 \leq c(r + |\mathcal{G}(W)|_{\mathbb{R}^m})^2 \text{ when } |y|_{\mathbb{R}^m} \leq r.$$

Fixing M > 0, the set W s.t.  $|\mathcal{G}(W)|_{\mathbb{R}^m} < M$  has a positive Wiener measure. (III)(i) is thus shown.

# PERIODIC H-J EQN

(III)(ii)

$$|\Phi(W;y) - \Phi(W;y')| \leq G(r,W)|y-y'|_{\mathbb{R}^m}$$

when  $|y|_{\mathbb{R}^m} \leq r$ ,  $|y'|_{\mathbb{R}^m} \leq r$  and  $G(r, \cdot)$  is in  $L^2(C(-\infty, t_{\max}], d\mu_0)$ .

• With 
$$\Phi(W; y) = \frac{1}{2} |y - \mathcal{G}(W)|_{\Sigma}^{2}$$
:  
 $|\Phi(W; y) - \Phi(W; y')|$   
 $\leq \frac{1}{2} ||\Sigma^{-1/2}||_{\mathbb{R}^{m}, \mathbb{R}^{m}}^{2} (|y|_{\mathbb{R}^{m}} + |y'|_{\mathbb{R}^{m}} + 2|\mathcal{G}(W)|_{\mathbb{R}^{m}})|y - y'|_{\mathbb{R}^{m}}$   
 $\leq ||\Sigma^{-1/2}||_{\mathbb{R}^{m}, \mathbb{R}^{m}}^{2} (r + |\mathcal{G}(W)|_{\mathbb{R}^{m}})|y - y'|_{\mathbb{R}^{m}}.$ 

With the bound in the previous slice, this is square integrable.

- We consider the **non-periodic** case where the forcing potential F(x) has a "big" maximum and a "big" minimum.
- To show Bayes' formula, we show that

$$\mathcal{G}(W) = \{\phi^{W}(x_{i}, t_{i}) - \phi^{W}(x_{0}, t_{0}), i = 1, \dots, m\}$$

is continuous from  $C(-\infty, t_{\max}]$  to  $\mathbb{R}^m$ .

This is shown similarly as in the periodic case: there are constants  $c_k$  so that:

$$\lim_{k\to\infty}\phi^{W_k}(x_i,t_i)-\phi^W(x_i,t_i)-c_k=0.$$

• The Bayes' formula thus holds.

• The well-posedness of the posterior measure  $\mu^{y},$  we show conditions (III)(i) and (III)(ii).

• We show the bound:

 $|\mathcal{G}(W)|_{\mathbb{R}^m} \leq S(W),$ 

where

$$S(W) = c + c \sum_{i=1}^{m} \sum_{l=T_i(W)}^{t_{\max}} (1 + \max_{l \le \tau \le l+1} |W(\tau) - W(l+1)|^2).$$

• The constant  $T_i(W)$  depends on the Wiener path W.

### NONPERIODIC H-J EQN

• The Lax operator

$$\phi(\cdot,t) = \mathcal{K}_{s,t}^{W}\phi(\cdot,s);$$

$$\phi(x_i,t_i) = \inf_{\gamma, \gamma(t_i)=x_i} \left\{ \phi(\gamma(s),s) + \int_{t_0}^t \frac{1}{2} |\dot{\gamma}(\tau)|^2 - F(\gamma(\tau)) \dot{W}(\tau) d\tau \right\}.$$

 $\bullet$  We show that all the minimizers  $\gamma$  are inside a compact set at a time;

 $\gamma$  must be inside the compact set at a time larger than  $T_i(W)$ , which is independent of s.

### NONPERIODIC H-J EQN

• For the condition (III)(i): we show

$$\Phi(W;y) = \frac{1}{2}|y - \mathcal{G}(W)|_{\Sigma}^2 \leq c(r + |\mathcal{G}(W)|_{\mathbb{R}^m})^2 \leq c(r + S(W))^2$$

is less than M(r) for  $W \in X(r)$  of positive Wiener measure.

- There is a constant T such that the set of paths W with  $T_i(W) > T$  has a positive Wiener measure.
- We can choose a constant M s.t. out of these paths, the set of paths W such that S(W) < M has a positive Wiener measure.

# NONPERIODIC H-J EQN

• For the condition (III)(ii):

$$\begin{split} |\Phi(W;y) - \Phi(W;y')| &\leq \|\Sigma^{-1/2}\|_{\mathbb{R}^m,\mathbb{R}^m}^2(r+G(W))|y-y'|_{\mathbb{R}^m}.\\ &\leq \|\Sigma^{-1/2}\|_{\mathbb{R}^m,\mathbb{R}^m}^2(r+S(W))|y-y'|_{\mathbb{R}^m}. \end{split}$$

• To show that  $G(r, W) = \|\Sigma^{-1/2}\|_{\mathbb{R}^m, \mathbb{R}^m}^2(r + S(W))$  is in  $L^2(C(-\infty, t_{\max}], d\mu_0)$ 

we show  $S(W) \in L^2(C(-\infty, t_{\max}], d\mu_0)$ .

• This is achieved by using estimates for the convergence rates for the law of large numbers.

• There are shocks where the solution u is discontinuous; u is not defined everywhere, but  $u(\cdot, t) \in L^1_{loc}(\mathbb{R}^d)$  for all t.

• For i = 1, ..., m, let  $l_i : L^1_{loc}(\mathbb{R}^d) \to \mathbb{R}$  be continuous and bounded.

• Define

$$\mathcal{G}(W) = (l_1(u(\cdot, t_1)), \ldots, l_m(u(\cdot, t_m)) \in \mathbb{R}^m)$$

• Noisy observation

$$\mathbf{y} = \mathcal{G}(\mathbf{W}) + \sigma.$$

• Determine  $\mu^{y}(W) = \mathbb{P}(W|y)$ .