# Second class particles and random Young tableaux joint work with Dan Romik 

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## infinite Young tableau


$\Omega$ — set of infinite Young tableaux

Young tableau as a growth process


Young tableau as a growth process


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Young tableau as a growth process


Young tableau and dynamics of particles


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## jeu de taquin and second class particles


jeu de taquin trajectory - rouge path of the gap

## jeu de taquin and second class particles


jeu de taquin trajectory - rouge path of the gap
jeu de taquin and second class particles

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## second class particle


second class particle $=$ jeu de taquin
jeu de taquin - overview

original tableau $T$
jeu de taquin - overview

outcome of slidings
jeu de taquin - overview

new tableau $J(T)$

## jeu de taquin - overview


jeu de taquin applied to $T$ gives two pieces of information:

- trajectory $\mathbf{p}(T)$ of jeu de taquin,
- the new tableau $J(T)$,


## infinite Robinson-Schensted-Knuth (RSK) map

infinite word $\stackrel{\text { RSK }}{\mapsto}$ recording tableau $\in \Omega$

insertion tableau

recording tableau

FONDPXBZULGEATWRSMYVCJHQIK

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| F | L | P | W |
| :---: | :---: | :---: | :---: |
| D | G | M | R |
| B | E | J | Q |
| A | C | H | I |

insertion tableau

| 7 | 11 | 22 | 24 |
| :---: | :---: | :---: | :---: |
| 4 | 10 | 16 | 17 |
| 3 | 9 | 14 | 15 |
| 1 | 2 | 5 | 6 |

recording tableau

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infinite word $\xrightarrow{\text { RSK }}$ recording tableau $\in \Omega$

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FONDPXBZULGEATWRSMYVCJHQIK
if $X_{0}, X_{1}, \ldots$ are i.i.d. $U(0,1)$ random variables then
$\operatorname{RSK}\left(X_{0}, X_{1}, \ldots\right) \stackrel{\text { distribution }}{=}$ Plancherel measure

## trajectories



## trajectories


jeu de taquin
$\Theta(T)$ - asymptotic angle of jeu de taquin

second class particle asymptotic speed of second class particle

$$
\begin{gathered}
T_{0} \\
T_{\theta_{0}}
\end{gathered}
$$



jeu de taquin dynamical system ( $\Omega$, Plancherel, $J$ )

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jeu de taquin dynamical system ( $\Omega$, Plancherel, $J$ )
i.i.d. shift dynamical system $\left([0,1]^{\mathbb{N}}, \prod\right.$ Lebesgue, $\left.s\right)$

$$
\left(x_{0}, x_{1}, \ldots\right) \stackrel{s}{\longmapsto}\left(x_{1}, x_{2}, \ldots\right) \stackrel{s}{\longmapsto}
$$


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$\theta_{0}=f\left(x_{0}\right)$
$\theta_{1}=f\left(x_{1}\right)$
jeu de taquin dynamical system ( $\Omega$, Plancherel, $J$ )
the jeu de taquin dynamical system is isomorphic to i.i.d. shift the inverse map is given by $x_{i}=f^{-1}\left(\theta_{i}\right)$

## main results

- slope angles $\theta_{0}, \theta_{1}, \ldots$
(and hence asymptotic speeds of second class particles!) exist almost surely,
- they are independent random variables with explicit distribution,
- RSK is an isomorphism between the dynamical system of shift and jeu de taquin,
- jeu de taquin is an ergodic transformation,


## open problems



睩 Dan Romik, Piotr Śniady
Jeu de taquin dynamics on infinite Young tableaux and second class particles arXiv:1111.0575

