## Arnold Diffusion in Fictitious Play Dynamics

Georg Ostrovski

University of Warwick

May 9, 2012

G.Ostrovski (University of Warwick) Arnold Diffusion in Fictitious Play Dynamics

May 9, 2012 1 / 30

G.Ostrovski (University of Warwick) Arnold Diffusion in Fictitious Play Dynamics

< ロ > < 回 > < 回 > < 回 > < 回 >

• The dynamical systems in this talk are mainly motivated by processes in Game Theory, modelling the learning behaviour of players when repeatedly playing a game.

- The dynamical systems in this talk are mainly motivated by processes in Game Theory, modelling the learning behaviour of players when repeatedly playing a game.
- Mathematically, the systems of interest are nonsmooth flows on S<sup>3</sup>, with global sections whose first return maps are
  - continuous,
  - piecewise affine,
  - area-preserving.

- The dynamical systems in this talk are mainly motivated by processes in Game Theory, modelling the learning behaviour of players when repeatedly playing a game.
- Mathematically, the systems of interest are nonsmooth flows on S<sup>3</sup>, with global sections whose first return maps are
  - continuous,
  - piecewise affine,
  - area-preserving.
- Among other interesting features of this class of nonsmooth dynamics we are particularly interested in different forms of coexistence of quasi-periodic and stochastic behaviour.

### Static Games

- 2 Dynamics in Games: Fictitious Play
- Fictitious Play in Zero-Sum Games
- 4 The Induced Flow on S<sup>3</sup>
- 5 Numerical Experiments
- 6 Model Maps

### Static Games

- 2 Dynamics in Games: Fictitious Play
- 3 Fictitious Play in Zero-Sum Games
- 4 The Induced Flow on S<sup>3</sup>
- 5 Numerical Experiments
- 6 Model Maps

G.Ostrovski (University of Warwick) Arnold Diffusion in Fictitious Play Dynamics

#### Definition

### Definition

A two-player normal form game consists of:

• two players, say player 1 and player 2

### Definition

- two players, say player 1 and player 2
- for each player k = 1, 2, a space of **pure strategies**,  $S_k = \{1, ..., n_k\}$

### Definition

- two players, say player 1 and player 2
- for each player k = 1, 2, a space of **pure strategies**,  $S_k = \{1, ..., n_k\}$
- for each player k = 1, 2, a **payoff-function**

$$u_k: S_1 \times S_2 \to \mathbb{R}.$$

### Definition

A two-player normal form game consists of:

- two players, say player 1 and player 2
- for each player k = 1, 2, a space of **pure strategies**,  $S_k = \{1, ..., n_k\}$
- for each player k = 1, 2, a **payoff-function**

$$u_k: S_1 \times S_2 \to \mathbb{R}.$$

• Player k chooses strategy  $s_k$  without knowing his opponent's choice.

### Definition

- two players, say player 1 and player 2
- for each player k = 1, 2, a space of **pure strategies**,  $S_k = \{1, ..., n_k\}$
- for each player k = 1, 2, a payoff-function

$$u_k: S_1 \times S_2 \to \mathbb{R}.$$

- Player k chooses strategy  $s_k$  without knowing his opponent's choice.
- Then he receives his payoff  $u_k(s_1, s_2)$ .

### Definition

- two players, say player 1 and player 2
- for each player k = 1, 2, a space of **pure strategies**,  $S_k = \{1, ..., n_k\}$
- for each player k = 1, 2, a **payoff-function**

$$u_k: S_1 \times S_2 \to \mathbb{R}.$$

- Player k chooses strategy  $s_k$  without knowing his opponent's choice.
- Then he receives his payoff  $u_k(s_1, s_2)$ .
- Each player's aim is to maximize his own payoff.

### Definition

- two players, say player 1 and player 2
- for each player k = 1, 2, a space of **pure strategies**,  $S_k = \{1, ..., n_k\}$
- for each player k = 1, 2, a **payoff-function**

$$u_k: S_1 \times S_2 \to \mathbb{R}.$$

- Player k chooses strategy  $s_k$  without knowing his opponent's choice.
- Then he receives his payoff  $u_k(s_1, s_2)$ .
- Each player's aim is to maximize his own payoff.
- Today we assume  $n = n_1 = n_2$ .

### Definition

A two-player normal form game consists of:

- two players, say player 1 and player 2
- for each player k = 1, 2, a space of **pure strategies**,  $S_k = \{1, ..., n_k\}$
- for each player k = 1, 2, a **payoff-function**

$$u_k: S_1 \times S_2 \to \mathbb{R}.$$

- Player k chooses strategy  $s_k$  without knowing his opponent's choice.
- Then he receives his payoff  $u_k(s_1, s_2)$ .
- Each player's aim is to maximize his own payoff.
- Today we assume  $n = n_1 = n_2$ .

The payoff functions can be represented by a bimatrix  $(A, B), A, B \in \mathbb{R}^{n \times n}$ :

$$u_1(i,j) = A_{ij} = e_i^T A e_j$$
 and  $u_2(i,j) = B_{ij} = e_i^T B e_j$ .

G.Ostrovski (University of Warwick) Arnold Diffusion in Fictitious Play Dynamics

• Idea: randomization instead of fixed strategy choice.

• Idea: randomization instead of fixed strategy choice.

#### Definition

Space of player *k*'s **mixed strategies** is set of probability distributions over his pure strategies:

$$\Sigma_k = \Delta(S_k) = \{x \in \mathbb{R}^n_{\geq 0} \colon \sum x_i = 1\}$$

(pure strategy *i* implicitly identified with  $e_i$ , the *i*th unit vector in  $\mathbb{R}^n$ )

• Idea: randomization instead of fixed strategy choice.

#### Definition

Space of player *k*'s **mixed strategies** is set of probability distributions over his pure strategies:

$$\Sigma_k = \Delta(S_k) = \{x \in \mathbb{R}^n_{\geq 0} \colon \sum x_i = 1\}$$

(pure strategy *i* implicitly identified with  $e_i$ , the *i*th unit vector in  $\mathbb{R}^n$ )

• Geometrically: simplex spanned by *n* vertices *e*<sub>1</sub>,..., *e<sub>n</sub>* 

• Idea: randomization instead of fixed strategy choice.

#### Definition

Space of player *k*'s **mixed strategies** is set of probability distributions over his pure strategies:

$$\Sigma_k = \Delta(S_k) = \{x \in \mathbb{R}^n_{\geq 0} \colon \sum x_i = 1\}$$

(pure strategy *i* implicitly identified with  $e_i$ , the *i*th unit vector in  $\mathbb{R}^n$ )

- Geometrically: simplex spanned by *n* vertices *e*<sub>1</sub>,..., *e<sub>n</sub>*
- Convention: row vectors for player 1 and column vectors for player 2

• Idea: randomization instead of fixed strategy choice.

#### Definition

Space of player *k*'s **mixed strategies** is set of probability distributions over his pure strategies:

$$\Sigma_k = \Delta(S_k) = \{x \in \mathbb{R}^n_{\geq 0} \colon \sum x_i = 1\}$$

(pure strategy *i* implicitly identified with  $e_i$ , the *i*th unit vector in  $\mathbb{R}^n$ )

- Geometrically: simplex spanned by *n* vertices *e*<sub>1</sub>,..., *e<sub>n</sub>*
- Convention: row vectors for player 1 and column vectors for player 2

Extended payoff functions  $u_i: \Sigma_1 \times \Sigma_2 \to \mathbb{R}$ 

$$u_1(x,y) = xAy$$
 and  $u_2(x,y) = xBy$ 

• Idea: randomization instead of fixed strategy choice.

#### Definition

Space of player *k*'s **mixed strategies** is set of probability distributions over his pure strategies:

$$\Sigma_k = \Delta(S_k) = \{x \in \mathbb{R}^n_{\geq 0} \colon \sum x_i = 1\}$$

(pure strategy *i* implicitly identified with  $e_i$ , the *i*th unit vector in  $\mathbb{R}^n$ )

- Geometrically: simplex spanned by *n* vertices *e*<sub>1</sub>,...,*e*<sub>n</sub>
- Convention: row vectors for player 1 and column vectors for player 2

Extended payoff functions  $u_i \colon \Sigma_1 \times \Sigma_2 \to \mathbb{R}$ 

$$u_1(x,y) = xAy$$
 and  $u_2(x,y) = xBy$ 

• Expected payoff from randomizing with probability distributions x, y

#### **Best Response Correspondences**

Let  $\mathcal{BR}_1: \Sigma_2 \to \Sigma_1$  and  $\mathcal{BR}_2: \Sigma_1 \to \Sigma_2$  be given by

$$\mathcal{BR}_1(y) = \{ x \in \Sigma_1 : u_1(x, y) \ge u_1(x', y) \ \forall x' \in \Sigma_1 \},$$
  
$$\mathcal{BR}_2(x) = \{ y \in \Sigma_2 : u_2(x, y) \ge u_2(x, y') \ \forall y' \in \Sigma_2 \}.$$

#### Best Response Correspondences

Let  $\mathcal{BR}_1: \Sigma_2 \to \Sigma_1$  and  $\mathcal{BR}_2: \Sigma_1 \to \Sigma_2$  be given by

$$\mathcal{B}\mathcal{R}_1(y) = \{ x \in \Sigma_1 : u_1(x, y) \ge u_1(x', y) \ \forall x' \in \Sigma_1 \},$$
  
$$\mathcal{B}\mathcal{R}_2(x) = \{ y \in \Sigma_2 : u_2(x, y) \ge u_2(x, y') \ \forall y' \in \Sigma_2 \}.$$

Generically single-valued except on a finite set of hyperplanes

#### **Best Response Correspondences**

Let  $\mathcal{BR}_1: \Sigma_2 \to \Sigma_1$  and  $\mathcal{BR}_2: \Sigma_1 \to \Sigma_2$  be given by

$$\mathcal{BR}_1(y) = \{x \in \Sigma_1 : u_1(x, y) \ge u_1(x', y) \ \forall x' \in \Sigma_1\},$$
  
$$\mathcal{BR}_2(x) = \{y \in \Sigma_2 : u_2(x, y) \ge u_2(x, y') \ \forall y' \in \Sigma_2\}.$$

Generically single-valued except on a finite set of hyperplanes

#### Definition

A **Nash Equilibrium** of a two-player game is a mixed strategy profile  $(x, y) \in \Sigma_1 \times \Sigma_2$ , such that

$$x \in \mathcal{BR}_1(y)$$
 and  $y \in \mathcal{BR}_2(x)$ .

#### Best Response Correspondences

Let  $\mathcal{BR}_1 : \Sigma_2 \to \Sigma_1$  and  $\mathcal{BR}_2 : \Sigma_1 \to \Sigma_2$  be given by

$$\mathcal{BR}_1(y) = \{x \in \Sigma_1 : u_1(x, y) \ge u_1(x', y) \ \forall x' \in \Sigma_1\},$$
  
$$\mathcal{BR}_2(x) = \{y \in \Sigma_2 : u_2(x, y) \ge u_2(x, y') \ \forall y' \in \Sigma_2\}.$$

Generically single-valued except on a finite set of hyperplanes

#### Definition

A **Nash Equilibrium** of a two-player game is a mixed strategy profile  $(x, y) \in \Sigma_1 \times \Sigma_2$ , such that

$$x \in \mathcal{BR}_1(y)$$
 and  $y \in \mathcal{BR}_2(x)$ .

• Interpretation: neither player benefits from *unilateral* deviation.

#### **Best Response Correspondences**

Let  $\mathcal{BR}_1 : \Sigma_2 \to \Sigma_1$  and  $\mathcal{BR}_2 : \Sigma_1 \to \Sigma_2$  be given by

$$\mathcal{BR}_1(y) = \{x \in \Sigma_1 : u_1(x, y) \ge u_1(x', y) \ \forall x' \in \Sigma_1\},$$
  
$$\mathcal{BR}_2(x) = \{y \in \Sigma_2 : u_2(x, y) \ge u_2(x, y') \ \forall y' \in \Sigma_2\}.$$

Generically single-valued except on a finite set of hyperplanes

#### Definition

A **Nash Equilibrium** of a two-player game is a mixed strategy profile  $(x, y) \in \Sigma_1 \times \Sigma_2$ , such that

$$x \in \mathcal{BR}_1(y)$$
 and  $y \in \mathcal{BR}_2(x)$ .

- Interpretation: neither player benefits from *unilateral* deviation.
- Nash (1950): Every game has at least one Nash Equilibrium.

### An Example: Rock-Paper-Scissors

G.Ostrovski (University of Warwick) Arnold Diffusion in Fictitious Play Dynamics

### An Example: Rock-Paper-Scissors

Let 1 = 'rock', 2 = 'paper', 3 = 'scissors'. The game is given by (A, B):

$$A = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} , \quad B = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}.$$

- ∢ ≣ ▶

### An Example: Rock-Paper-Scissors

Let 1 = 'rock', 2 = 'paper', 3 = 'scissors'. The game is given by (A, B):

$$A = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \quad , \quad B = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

The space of mixed strategies can be visualized like this:



### Static Games

2 Dynamics in Games: Fictitious Play

3 Fictitious Play in Zero-Sum Games

- 4 The Induced Flow on S<sup>3</sup>
- 5 Numerical Experiments
- 6 Model Maps

## **Fictitious Play**

Instead of playing a game once ('one-shot game'), the players can play it repeatedly (discrete time) or continuously (continuous time).

## **Fictitious Play**

Instead of playing a game once ('one-shot game'), the players can play it repeatedly (discrete time) or continuously (continuous time).

• **Question**: How can players *learn* from past play to improve their future play?
Instead of playing a game once ('one-shot game'), the players can play it repeatedly (discrete time) or continuously (continuous time).

- **Question**: How can players *learn* from past play to improve their future play?
- **Possible Answer**: Always play a best response to the average past play of your opponent.

Instead of playing a game once ('one-shot game'), the players can play it repeatedly (discrete time) or continuously (continuous time).

- **Question**: How can players *learn* from past play to improve their future play?
- **Possible Answer**: Always play a best response to the average past play of your opponent.

#### Definition

Let  $(x_n, y_n)$  denote the (pure) strategies played at time  $n \in \mathbb{N}$ . Then **discrete-time Fictitious Play** is given by the rule

$$x_{n+1} \in \mathcal{BR}_1\left(\frac{1}{n}\sum_{i=1}^n y_i\right)$$
,  $y_{n+1} \in \mathcal{BR}_2\left(\frac{1}{n}\sum_{i=1}^n x_i\right)$ .

We are more interested in a continuous-time process:

We are more interested in a continuous-time process:

• Let x(t) and y(t) be the strategies played at time t > 0.

We are more interested in a continuous-time process:

- Let x(t) and y(t) be the strategies played at time t > 0.
- Denote the average play through time t by

$$p(t) = rac{1}{t} \int_0^t x(\tau) \, d\tau$$
 and  $q(t) = rac{1}{t} \int_0^t y(\tau) \, d\tau.$ 

We are more interested in a continuous-time process:

- Let x(t) and y(t) be the strategies played at time t > 0.
- Denote the average play through time t by

$$p(t) = \frac{1}{t} \int_0^t x(\tau) d\tau$$
 and  $q(t) = \frac{1}{t} \int_0^t y(\tau) d\tau$ .

• Assume  $x(t) \in \mathcal{B}R_1(q(t))$  and  $y(t) \in \mathcal{B}R_2(p(t))$  for all t > 0.

We are more interested in a continuous-time process:

- Let x(t) and y(t) be the strategies played at time t > 0.
- Denote the average play through time t by

$$p(t) = rac{1}{t} \int_0^t x(\tau) \, d au$$
 and  $q(t) = rac{1}{t} \int_0^t y(\tau) \, d au.$ 

• Assume  $x(t) \in \mathcal{B}_{R_1}(q(t))$  and  $y(t) \in \mathcal{B}_{R_2}(p(t))$  for all t > 0. A short calculation shows:

We are more interested in a continuous-time process:

- Let x(t) and y(t) be the strategies played at time t > 0.
- Denote the average play through time t by

$$p(t) = rac{1}{t} \int_0^t x(\tau) \, d au$$
 and  $q(t) = rac{1}{t} \int_0^t y(\tau) \, d au.$ 

• Assume  $x(t) \in \mathcal{BR}_1(q(t))$  and  $y(t) \in \mathcal{BR}_2(p(t))$  for all t > 0. A short calculation shows:

(Continuous-time) Fictitious Play Dynamics (FP)

$$\dot{p} \in \frac{1}{t} \left( \mathcal{B}\mathcal{R}_1(q) - p \right) \quad , \quad \dot{q} \in \frac{1}{t} \left( \mathcal{B}\mathcal{R}_2(p) - q \right)$$

$$\dot{p} \in \frac{1}{t} (\mathcal{B}\mathcal{R}_1(q) - p) \quad , \quad \dot{q} \in \frac{1}{t} (\mathcal{B}\mathcal{R}_2(p) - q)$$
 (FP)

#### **Fictitious Play Dynamics**

$$\dot{p} \in \frac{1}{t} (\mathcal{B}\mathcal{R}_1(q) - p) \quad , \quad \dot{q} \in \frac{1}{t} (\mathcal{B}\mathcal{R}_2(p) - q)$$
 (FP)

 Solutions for any initial conditions exist for all times t ≥ 0 (by general theory: BRupper semi-continuous, has closed convex sets as values).

$$\dot{p} \in \frac{1}{t} (\mathcal{B}\mathcal{R}_{1}(q) - p) \quad , \quad \dot{q} \in \frac{1}{t} (\mathcal{B}\mathcal{R}_{2}(p) - q)$$
 (FP)

- Solutions for any initial conditions exist for all times t ≥ 0 (by general theory: BRupper semi-continuous, has closed convex sets as values).
- Under genericity assumptions on (A, B), (FP) defines a *unique*, continuous flow for all t ≥ 0 for a set of initial conditions which has full Lebesgue measure, is open and dense (van Strien et al., 2008).

$$\dot{p} \in \frac{1}{t} (\mathcal{B}\mathcal{R}_1(q) - p) \quad , \quad \dot{q} \in \frac{1}{t} (\mathcal{B}\mathcal{R}_2(p) - q)$$
 (FP)

#### **Fictitious Play Dynamics**

$$\dot{p} \in \frac{1}{t} (\mathcal{B}\mathcal{R}_{1}(q) - p) \quad , \quad \dot{q} \in \frac{1}{t} (\mathcal{B}\mathcal{R}_{2}(p) - q)$$
 (FP)

 Nash Equilibria are equilibrium solutions for (FP). If a (FP)-orbit converges to a point, this point is a Nash Equilibrium.

$$\dot{p} \in \frac{1}{t} (\mathcal{B}\mathcal{R}_1(q) - p) \quad , \quad \dot{q} \in \frac{1}{t} (\mathcal{B}\mathcal{R}_2(p) - q)$$
 (FP)

- Nash Equilibria are equilibrium solutions for (FP). If a (FP)-orbit converges to a point, this point is a Nash Equilibrium.
- (FP)-orbits converge to the set of Nash Equilibria in various specific classes of games, but generally this is not the case (example of (3 × 3)-game with a stable limit cycle due to Shapley, 1964).

$$\dot{p} \in \frac{1}{t} (\mathcal{B}\mathcal{R}_1(q) - p) \quad , \quad \dot{q} \in \frac{1}{t} (\mathcal{B}\mathcal{R}_2(p) - q)$$
 (FP)

- Nash Equilibria are equilibrium solutions for (FP). If a (FP)-orbit converges to a point, this point is a Nash Equilibrium.
- (FP)-orbits converge to the set of Nash Equilibria in various specific classes of games, but generally this is not the case (example of (3 × 3)-game with a stable limit cycle due to Shapley, 1964).
- In a zero-sum game (A + B = 0), (FP)-orbits converge to the set of Nash Equilibria (Brown, 1951). The converse statement is an open conjecture (Hofbauer, 1995).

$$\dot{p} \in \frac{1}{t} (\mathcal{B}\mathcal{R}_1(q) - p) \quad , \quad \dot{q} \in \frac{1}{t} (\mathcal{B}\mathcal{R}_2(p) - q)$$
 (FP)

#### **Fictitious Play Dynamics**

$$\dot{p} \in \frac{1}{t} (\mathcal{B}\mathcal{R}_1(q) - p) \quad , \quad \dot{q} \in \frac{1}{t} (\mathcal{B}\mathcal{R}_2(p) - q)$$
 (FP)

Example piece of orbit:



Non-equilibrium solution trajectories consist of straight line segments.

## Overview

Static Games



Fictitious Play in Zero-Sum Games

- 4 The Induced Flow on S<sup>3</sup>
- 5 Numerical Experiments
- 6 Model Maps

From now on we assume that

From now on we assume that

• (A, B) is a 3 × 3 zero-sum game, i.e. A + B = 0  $(A, B \in \mathbb{R}^{3\times 3})$ ,

From now on we assume that

- (A, B) is a 3 × 3 zero-sum game, i.e. A + B = 0  $(A, B \in \mathbb{R}^{3 \times 3})$ ,
- with *unique* Nash Equilibrium  $(E^A, E^B) \in int(\Sigma_1 \times \Sigma_2)$ .

From now on we assume that

- (A, B) is a 3 × 3 zero-sum game, i.e. A + B = 0  $(A, B \in \mathbb{R}^{3\times 3})$ ,
- with *unique* Nash Equilibrium  $(E^A, E^B) \in int(\Sigma_1 \times \Sigma_2)$ .

#### Theorem (van Strien, 2011)

In this setting (FP) induces a unique continuous flow on all of  $\Sigma_1 \times \Sigma_2$ .

G.Ostrovski (University of Warwick) Arnold Diffusion in Fictitious Play Dynamics

< A >

There exists a special function  $H: \Sigma_1 \times \Sigma_2 \to \mathbb{R}$ , such that

There exists a special function  $H: \Sigma_1 \times \Sigma_2 \to \mathbb{R}$ , such that

• *H* is continuous and piecewise affine (pieces = best response regions)

There exists a special function  $H: \Sigma_1 \times \Sigma_2 \to \mathbb{R}$ , such that

- *H* is continuous and piecewise affine (pieces = best response regions)
- $H^{-1}(c)$  is a topological 3-sphere centred at the Nash Equilibrium

There exists a special function  $H: \Sigma_1 \times \Sigma_2 \to \mathbb{R}$ , such that

- H is continuous and piecewise affine (pieces = best response regions)
- $H^{-1}(c)$  is a topological 3-sphere centred at the Nash Equilibrium



There exists a special function  $H: \Sigma_1 \times \Sigma_2 \to \mathbb{R}$ , such that

- *H* is continuous and piecewise affine (pieces = best response regions)
- $H^{-1}(c)$  is a topological 3-sphere centred at the Nash Equilibrium

# *H* is a Lyapunov function for (FP) (Brown, 1951) Let (A, B) be zero-sum with unique Nash Equilibrium $(E^A, E^B)$ . Then 1 $H(p, q) \ge 0$ and H(p, q) = 0 if and only if $(p, q) = (E^A, E^B)$ ; 2 $\dot{H} = -\frac{H}{t}$ along solutions (p(t), q(t)) of (FP).

 For A + B = 0, the motion defined by (FP) is a product of radial motion towards the Nash Equilibrium and motion on H-level sets.

There exists a special function  $H: \Sigma_1 \times \Sigma_2 \to \mathbb{R}$ , such that

- *H* is continuous and piecewise affine (pieces = best response regions)
- $H^{-1}(c)$  is a topological 3-sphere centred at the Nash Equilibrium

#### *H* is a Lyapunov function for (FP) (Brown, 1951)

Let (A, B) be zero-sum with unique Nash Equilibrium  $(E^A, E^B)$ . Then

● 
$$H(p,q) \ge 0$$
 and  $H(p,q) = 0$  if and only if  $(p,q) = (E^A, E^B)$ ;

2 
$$\dot{H} = -\frac{H}{t}$$
 along solutions  $(p(t), q(t))$  of (FP).

- For A + B = 0, the motion defined by (FP) is a product of radial motion towards the Nash Equilibrium and motion on H-level sets.
- This induced flow on  $H^{-1}(1) \approx S^3$  is subject of our further interest.

# Overview

Static Games

- 2 Dynamics in Games: Fictitious Play
- 3 Fictitious Play in Zero-Sum Games
- 4 The Induced Flow on S<sup>3</sup>
- 5 Numerical Experiments
- 6 Model Maps

G.Ostrovski (University of Warwick) Arnold Diffusion in Fictitious Play Dynamics

Image: A matching of the second se

•  $\phi_t$  flow of (FP) on  $\Sigma_1 \times \Sigma_2$ 

- ₹ 3 →

Image: A matching of the second se

 $\Psi_t$  the induced flow on  $H^{-1}(1) \approx S^3$ , i.e.  $\pi$  maps orbits of  $\phi_t$  to orbits of  $\Psi_t$ 

φ<sub>t</sub> flow of (FP) on Σ<sub>1</sub> × Σ<sub>2</sub>
π: (Σ<sub>1</sub> × Σ<sub>2</sub>) \ {(E<sup>A</sup>, E<sup>B</sup>)} → H<sup>-1</sup>(1) radial projection along rays from (E<sup>A</sup>, E<sup>B</sup>)

 $\Psi_t$  the induced flow on  $H^{-1}(1) \approx S^3$ , i.e.  $\pi$  maps orbits of  $\phi_t$  to orbits of  $\Psi_t$ 

Theorem (van Strien, 2011)

•  $\Psi_t$  is a piecewise translation flow.

•  $\phi_t$  flow of (FP) on  $\Sigma_1 \times \Sigma_2$ 

•  $\pi: (\Sigma_1 \times \Sigma_2) \setminus \{(E^A, E^B)\} \to H^{-1}(1) \text{ radial projection along rays from } (E^A, E^B)$ 

 $\Psi_t$  the induced flow on  $H^{-1}(1) \approx S^3$ , i.e.  $\pi$  maps orbits of  $\phi_t$  to orbits of  $\Psi_t$ 

#### Theorem (van Strien, 2011)

- $\Psi_t$  is a piecewise translation flow.
- Ψ<sub>t</sub> has no stationary points. In particular, no orbit of (FP) approaches Nash Equilibrium along a well-defined direction.
## The Induced Flow on $S^3$

•  $\phi_t$  flow of (FP) on  $\Sigma_1 \times \Sigma_2$ 

•  $\pi: (\Sigma_1 \times \Sigma_2) \setminus \{(E^A, E^B)\} \to H^{-1}(1) \text{ radial projection along rays from } (E^A, E^B)$ 

 $\Psi_t$  the induced flow on  $H^{-1}(1) \approx S^3$ , i.e.  $\pi$  maps orbits of  $\phi_t$  to orbits of  $\Psi_t$ 

#### Theorem (van Strien, 2011)

- $\Psi_t$  is a piecewise translation flow.
- Ψ<sub>t</sub> has no stationary points. In particular, no orbit of (FP) approaches Nash Equilibrium along a well-defined direction.
- $\Psi_t$  is volume-preserving w.r.t. an appropriate volume form.

G.Ostrovski (University of Warwick)

$$A = -B = \begin{pmatrix} 1 & 0 & \beta \\ \beta & 1 & 0 \\ 0 & \beta & 1 \end{pmatrix}, \quad \beta = \frac{\sqrt{5} - 1}{2} \approx 0.618 \text{ (golden mean)}$$

$$A = -B = \begin{pmatrix} 1 & 0 & \beta \\ \beta & 1 & 0 \\ 0 & \beta & 1 \end{pmatrix}, \quad \beta = \frac{\sqrt{5} - 1}{2} \approx 0.618 \text{ (golden mean)}$$

The induced flow  $\Psi_t$  on  $H^{-1}(1) \approx S^3$  has a periodic orbit  $\Gamma$  (a hexagon), and there exists a topological disc  $S \subset H^{-1}(1)$  with  $\partial S = \Gamma$ , such that:

$$A = -B = \begin{pmatrix} 1 & 0 & \beta \\ \beta & 1 & 0 \\ 0 & \beta & 1 \end{pmatrix}, \quad \beta = \frac{\sqrt{5} - 1}{2} \approx 0.618 \text{ (golden mean)}$$

The induced flow  $\Psi_t$  on  $H^{-1}(1) \approx S^3$  has a periodic orbit  $\Gamma$  (a hexagon), and there exists a topological disc  $S \subset H^{-1}(1)$  with  $\partial S = \Gamma$ , such that:

• Every orbit intersects *S* infinitely many times (transversally); i.e., *S* is a global section with well-defined first return map *R*<sub>S</sub>.

$$A = -B = \begin{pmatrix} 1 & 0 & \beta \\ \beta & 1 & 0 \\ 0 & \beta & 1 \end{pmatrix}, \quad \beta = \frac{\sqrt{5} - 1}{2} \approx 0.618 \text{ (golden mean)}$$

The induced flow  $\Psi_t$  on  $H^{-1}(1) \approx S^3$  has a periodic orbit  $\Gamma$  (a hexagon), and there exists a topological disc  $S \subset H^{-1}(1)$  with  $\partial S = \Gamma$ , such that:

- Every orbit intersects *S* infinitely many times (transversally); i.e., *S* is a global section with well-defined first return map *R*<sub>S</sub>.
- The first return time of z ∈ S tends to zero as z tends to ∂S = Γ.
  R<sub>S</sub> can be extended continuously to ∂S by R<sub>S</sub>|<sub>∂S</sub> = id.

$$A = -B = \begin{pmatrix} 1 & 0 & \beta \\ \beta & 1 & 0 \\ 0 & \beta & 1 \end{pmatrix}, \quad \beta = \frac{\sqrt{5} - 1}{2} \approx 0.618 \text{ (golden mean)}$$

The induced flow  $\Psi_t$  on  $H^{-1}(1) \approx S^3$  has a periodic orbit  $\Gamma$  (a hexagon), and there exists a topological disc  $S \subset H^{-1}(1)$  with  $\partial S = \Gamma$ , such that:

- Every orbit intersects *S* infinitely many times (transversally); i.e., *S* is a global section with well-defined first return map *R*<sub>S</sub>.
- The first return time of z ∈ S tends to zero as z tends to ∂S = Γ.
  R<sub>S</sub> can be extended continuously to ∂S by R<sub>S</sub>|<sub>∂S</sub> = id.
- *R<sub>S</sub>* is piecewise affine and area-preserving.

## Overview

Static Games

- 2 Dynamics in Games: Fictitious Play
- 3 Fictitious Play in Zero-Sum Games
- 4 The Induced Flow on S<sup>3</sup>
- 5 Numerical Experiments
- 6 Model Maps

For different zero-sum games, numerical experiments seem to suggest several possible types of induced dynamics on  $S^3$ . The following types were (numerically) observed in (O., van Strien, 2011):

For different zero-sum games, numerical experiments seem to suggest several possible types of induced dynamics on  $S^3$ . The following types were (numerically) observed in (O., van Strien, 2011):

#### Completely ergodic type



Space decomposed into elliptic islands and ergodic regions



Space decomposed into elliptic islands and ergodic regions



#### Remark (O., van Strien, 2011)

Quasi-periodic orbits in the elliptic regions exactly correspond to orbits with periodic itinerary (players switch strategies in a cyclic way).

 More complicated situation with coexistence of different quasi-periodic islands and stochastic motion





G.Ostrovski (University of Warwick)

rnold Diffusion in Fictitious Play Dynamics

May 9, 2012 23 / 30





• The images indicate the occurence of 'Arnold Diffusion'; coexistence of various families of islands of (quasi-)periodic motion (filled with invariant circles), contained in regions of stochastic (space-filling) motion.

## Overview

Static Games

- 2 Dynamics in Games: Fictitious Play
- 3 Fictitious Play in Zero-Sum Games
- [4] The Induced Flow on  $S^3$
- 5 Numerical Experiments



G.Ostrovski (University of Warwick)

As we have seen (in an example), the induced flow  $\Psi_t$  on  $H^{-1}(1) \approx S^3$  has a global section *S*, which is a two dimensional topological disc. Its first return map  $R_S$  has rather special properties:

piecewise affine

- piecewise affine
- continuous

- piecewise affine
- continuous
- area-preserving

- piecewise affine
- continuous
- area-preserving
- $R_S|_{\partial S} = \mathsf{id}$

As we have seen (in an example), the induced flow  $\Psi_t$  on  $H^{-1}(1) \approx S^3$  has a global section *S*, which is a two dimensional topological disc. Its first return map  $R_S$  has rather special properties:

- piecewise affine
- continuous
- area-preserving
- $R_S|_{\partial S} = \mathsf{id}$

Trying to construct simple (non-trivial) examples of maps with these properties shows that the properties are quite restrictive.

G.Ostrovski (University of Warwick) Arnold Diffusion in Fictitious Play Dynamics

\*ロ \* \* 御 \* \* 注 \*



< ロト < 部 ト < 注 ト < 注</p>



The map  $F_{\theta}$  for  $\theta \in (0, \frac{\pi}{4}]$  is defined by declaring:

- $F_{\theta} = id$  on the boundary of the square
- 2  $F_{\theta}(P_i) = Q_i$  for i = 1, ..., 4
- $F_{\theta}$  affine on each of the shown pieces



The map  $F_{\theta}$  for  $\theta \in (0, \frac{\pi}{4}]$  is defined by declaring:

- $F_{\theta} = id$  on the boundary of the square
- 2  $F_{\theta}(P_i) = Q_i$  for i = 1, ..., 4
- 3  $F_{\theta}$  affine on each of the shown pieces
- The map acts similar to a twist map. Intuitively, all points approximately rotate counterclockwise with rotation number decreasing to zero as points approach the boundary.

#### Invariant curves



• For many parameter values of  $\theta$ , families of invariant circles consisting of straight line segments and accumulating on the boundary can be constructed explicitly. On these invariant circles,  $F_{\theta}$  has rational rotation number.

#### **Stochastic Regions**









G.Ostrovski (University of Warwick)

Arnold Diffusion in Fictitious Play Dynamics

▲ E ► E つへの May 9, 2012 29 / 30



▶ ◀ 볼 ▶ 볼 ∽ ९ ୯ May 9, 2012 30 / 30



**Open questions:** 

May 9, 2012 30 / 30



#### **Open questions:**

 Do invariant circles near the boundary exist for all θ? What is their geometry? Can they have irrational rotation number?



#### **Open questions:**

- Do invariant circles near the boundary exist for all θ? What is their geometry? Can they have irrational rotation number?
- What are the ergodic properties of *F<sub>θ</sub>* restricted to 'stochastic regions'? Are there dense orbits?



#### **Open questions:**

- Do invariant circles near the boundary exist for all θ? What is their geometry? Can they have irrational rotation number?
- What are the ergodic properties of *F<sub>θ</sub>* restricted to 'stochastic regions'? Are there dense orbits?
- What are the possible itineraries for quasi-periodic orbits?