# On hitting times of bounded sets by random walks 

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## 1. The exit problem for random walks

Let $S_{n}:=x+X_{1}+\cdots+X_{n}$ be a random walk with i.i.d. increments $X_{1}, X_{2}, \ldots$
Use $\mathbb{P}_{x}(\cdot)$ for the law of walk starting at $x$ and $\mathbb{E}_{x} f:=\int f d \mathbb{P}_{x}$. Denote $\tau_{B}:=\inf \left\{n \geq 1: S_{n} \in B\right\}$ the hitting time of a set $B$. A huge number of works is devoted to the asymptotic of $\mathbb{P}_{x}\left(\tau_{B}>n\right)$ under different assumptions of $S_{n}$ and $B$.

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- Unbounded $B$ : a rather complete theory have been developed for $B=(-\infty, 0) \subset \mathbb{R}$ (from Sparre-Andersen '50s to Rogozin '72). In higher dimensions, there are many result on exit times from cones (resent most by Denisov and Wachtel '14).
- Bounded B: much less was known (Kesten and Spitzer '63, Port and Stone '67).

Kesten-Spitzer: For any aperiodic RW in $\mathbb{Z}^{1,2}$ and any finite $B \subset \mathbb{Z}^{1,2}$, there exists

$$
\lim _{n \rightarrow \infty} \frac{\mathbb{P}_{x}\left(\tau_{B}>n\right)}{\mathbb{P}_{0}\left(\tau_{\{0\}}>n\right)}:=g_{B}(x), \quad x \notin B
$$

The hard case is that of recurrent random walks.

- For $\mathbb{Z}^{1}$, if $S_{n}$ is centred and asymptotically $\alpha$-stable with $1<\alpha \leq 2$, then $\mathbb{P}_{0}\left(\tau_{\{0\}}>n\right) \sim c n^{1 / \alpha-1} L(n)$.
Moreover, if $\operatorname{Var}\left(X_{1}\right)<\infty$, then $\alpha=2$ and $L(n)=$ const.

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Moreover, if $\operatorname{Var}\left(X_{1}\right)<\infty$, then $\alpha=2$ and $L(n)=$ const.
- $g_{B}(x)$ is harmonic for the walk killed at hitting $B$, that is

$$
g_{B}(x)=\mathbb{E}_{x} g_{B}\left(S_{1}\right) \text { for } x \in B^{c} \text { and } g(x):=0 \text { on } B .
$$

Why:

$$
\begin{aligned}
\mathbb{P}_{x}\left(\tau_{B}>n+1\right) & =\int_{B} \mathbb{P}_{y}\left(\tau_{B}>n\right) \mathbb{P}_{x}\left(S_{1} \in d y\right) \\
& \sim \mathbb{P}_{0}\left(\tau_{\{0\}}>n\right) \mathbb{E}_{x} g_{B}\left(S_{1}\right) \mathbb{1}_{\left\{\tau_{B}>1\right\}}
\end{aligned}
$$

Physical interpretation: $g_{B}(x)$ is the potential energy of the field due to the unit equilibrium charge on $B$.
Spitzer made this rigorous: for any aperiodic recurrent walk in $\mathbb{Z}^{1,2}$, the potential kernel

$$
a(x):=\lim _{n \rightarrow \infty} \sum_{k=0}^{n}\left(\mathbb{P}_{0}\left(S_{k}=0\right)-\mathbb{P}_{x}\left(S_{k}=0\right)\right)
$$

exists and solves $\Delta a=\delta_{0}$, where $\Delta=P-I$. For any finite $B \subset \mathbb{Z}^{1,2}$, the equilibrium charge on $B$ is
$\mu^{*}(y)=\left\{\begin{array}{l}\lim _{|x| \rightarrow \infty} \mathbb{E}_{z}\left(S_{T_{-B}}=-y\right), \quad d=2 \text { or } d=1, \sigma^{2}=\infty, \\ \frac{1}{2} \lim _{x \rightarrow+\infty} \mathbb{E}_{x}\left(S_{T_{-B}}=-y\right)+\frac{1}{2} \lim _{x \rightarrow-\infty} \mathbb{E}_{x}\left(S_{T_{-B}}=-y\right), \quad o / w .\end{array}\right.$

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The potential $h_{B}(x):=\sum_{y \in B} a(x-y) \mu^{*}(y)$ solves $\Delta h_{B}=\mu^{*}$ and is constant on $B$, called the capacity. Then

$$
g_{B}(x)=h_{B}(x)-\text { Cap }_{B} .
$$

This is a very implicit representation.

## 2. Our assumptions and a lower bound

 Assume that the walk is in $\mathbb{R}, \mathbb{E} X_{1}=0, \operatorname{Var}\left(X_{1}\right):=\sigma^{2} \in(0, \infty)$. Let $M$ be the state space of the random walk, that is $M:=\lambda \mathbb{Z}$ if the walk is $\lambda$-arithmetic for some $\lambda>0$ and $M:=\mathbb{R}$ if otherwise. Consider the basic case that $B=(-d, d)$ for some $d>0$. Put$$
p_{n}(x):=\mathbb{P}_{x}\left(\tau_{(-d, d)}>n\right), \quad x \notin B, x \in M .
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Hitting times for half-lines: for any $x \geq 0$,

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\mathbb{P}_{x}\left(\tau_{(-\infty, 0)}>n\right) \sim \sqrt{\frac{2}{\pi}} \frac{U \geqslant(x)}{\sigma \sqrt{n}}
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where $U \geqslant(x)$ is the renewal function. It is harmonic for the walk killed as it enters $(-\infty, 0)$ and satisfies $U_{\geqslant}(x)=\mathbb{E}_{x}\left(x-S_{\tau_{(-\infty, 0)}}\right)$.

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where $U \geqslant(x)$ is the renewal function. It is harmonic for the walk killed as it enters $(-\infty, 0)$ and satisfies $U_{\geqslant}(x)=\mathbb{E}_{x}\left(x-S_{\tau_{(-\infty, 0)}}\right)$. Lower bound: for $|x| \geq d$, staying to one side of $B$ gives

$$
p_{n}(x) \geq \mathbb{P}_{x}\left(T_{1}>n\right) \sim \sqrt{\frac{2}{\pi}} \frac{U_{d}(x)}{\sigma \sqrt{n}}, \quad U_{d}(x):=\mathbb{E}_{x}\left|x-S_{T_{1}}\right|
$$

where $T_{1}$ is the first moment of jump over either $-d$ or $d$.

## 3. Results for the basic case

Let $T_{k}$ be the moment of the $k$ th jump over $\{-d, d\}$ from the outside; let $H_{k}:=S_{T_{k}}, k \geq 0$ be the overshoots; denote the $\#$ of jumps over $(-d, d)$ before it is hit as $\kappa:=\min \left(k \geq 1:\left|H_{k}\right|<d\right)$.

## Theorem 1

Let $S_{n}$ be a random walk with $\mathbb{E} X_{1}=0, \mathbb{E} X_{1}^{2}:=\sigma^{2} \in(0, \infty)$. Then for any $d>0$ and any $x$ from the state space $M$,

$$
p_{n}(x) \sim \sqrt{\frac{2}{\pi}} \frac{V_{d}(x)}{\sigma \sqrt{n}}, \quad V_{d}(x):=\mathbb{E}_{x}\left[\sum_{i=1}^{\kappa}\left|H_{i}-H_{i-1}\right|\right] .
$$

Moreover, this holds uniformly for $x=o(\sqrt{n})$. Further,

- $V_{d}(x)$ is harmonic for the walk killed as it enters $(-d, d)$;
- $0<U_{d}(x) \leq V_{d}(x)<\infty$ for $|x| \geq d$;
- $V_{d}(x) \sim|x|$ as $x \rightarrow \infty$.


## 4. Ideas of the proof

1. It costs to jump over:

There exists a $\gamma \in(0,1)$ such that

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\mathbb{P}_{x}\left(\left|H_{1}\right| \geq d\right) \leq \gamma
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2. Regularity of $p_{n}(x)$ in both $x$ and $n$ is needed.

Lemma: For any $x \in \mathbb{R}$ and $n \geq 1, p_{n}(x) \leq C|x| n^{-1 / 2}$.
Roughly, $\mathbb{E}_{x} p_{n-T_{1}}\left(H_{1}\right) \mathbb{1}_{\left\{\left|H_{1}\right| \geq d, T_{1} \leq n\right\}}$ is controlled by $\mathbb{E}_{x}\left|H_{1}\right|$.

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3. The mechanism of stabilisation:

For any $\alpha \in(0,1)$ it holds that

$$
\mathbb{E}_{x}\left|H_{1}\right| \leq \alpha|x|+K(\alpha), \quad|x| \geq d
$$

This follows from the known $\mathbb{E}_{x}\left|H_{1}\right|=o(|x|)$ as $|x| \rightarrow \infty$,

## 5. General sets

Denote $T_{k}^{\prime}$ the moments of jumps over $\{\inf B, \sup B\} ; H_{k}^{\prime}:=S_{T_{k}}^{\prime}$ the overshoots; and put $\kappa^{\prime}:=\min \left\{k \geq 1: T_{k}^{\prime} \geq \tau_{B}\right\}$.

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## Theorem 2

Assume that $\mathbb{E} X_{1}=0, \mathbb{E} X_{1}^{2}:=\sigma^{2} \in(0, \infty)$, and $B$ is a bounded Borel set with the non-empty $\operatorname{Int}_{M}(B)$. Then for any $x \in M$,
$p_{n}^{\prime}(x) \sim \frac{\sqrt{2} V_{B}(x)}{\sigma \sqrt{\pi n}}, \quad V_{B}(x):=\mathbb{E}_{x}\left[\sum_{i=1}^{\kappa^{\prime}}\left|H_{i}^{\prime}-H_{i-1}^{\prime}\right| \mathbb{1}_{\left\{H_{i-1}^{\prime} \notin \operatorname{Conv}(B)\right\}}\right]$.
Moreover, this holds uniformly for $x=o(\sqrt{n})$. It is true that $0<V_{B}(x)<\infty$ for $x \notin \operatorname{Conv}(B)$ and clearly, $V_{(-d, d)}(x)=V_{d}(x)$.

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Heuristics

1. It costs exponentially in time to stay within $\operatorname{Conv}(B) \backslash B$.
2. Each return from $B^{c}$ to $\operatorname{Conv}(B) \backslash B$ costs multiplicatively.
3. The rest is as in the basic case.

## 6. Conditional functional limit theorem

Define $\hat{S}_{n}(t)$ : for $t=k / n$ with a $k \in \mathbb{N}$ put $\hat{S}_{n}(k / n):=S_{k} /(\sigma \sqrt{n})$, and define the other values by linear interpolation.

Theorem 3
Under assumptions of Thm 2, for any $x \in M$ such that $V_{B}(x)>0$,

$$
\operatorname{Law}_{x}\left(\hat{S}_{n}(\cdot) \mid \tau_{B}>n\right) \xrightarrow{\mathcal{D}} \operatorname{Law}\left(\rho W_{+}\right) \quad \text { in } C[0,1]
$$

where $W_{+}$is a Brownian meander, $\rho$ is a r.v. independent of $W_{+}$ with the distribution given by $\mathbb{P}(\rho= \pm 1)=\frac{1}{2} \pm \frac{x-\mathbb{E}_{x} S_{\tau_{B}}}{2 V_{B}(x)}$.
For integer-valued asymptotically $\alpha$-stable walks $(1 \leq \alpha \leq 2)$ the weak convergence was proved by Belkin '72.

## 7. Applications to the largest problem

Define the largest gap (maximal spacing) within the range of $S_{n}$ :

$$
\operatorname{Gap}\left(\left\{S_{k}\right\}_{k \geq 1}^{n}\right):=G_{n}:=\max _{1 \leq k \leq n-1}\left(S_{(k+1, n)}-S_{(k, n)}\right)
$$

where $m_{n}:=S_{(1, n)} \leq S_{(2, n)} \leq \cdots \leq S_{(n, n)}=: M_{n}$ denote the elements of $S_{1}, \ldots, S_{n}$ arranged in the weakly ascending order.

Theorem 4
If $\mathbb{E} X_{1}=0, \operatorname{Var}\left(X_{1}\right)<\infty$, then

$$
G_{n} \xrightarrow{\mathcal{D}} G,
$$

where $G$ is a non-degenerate proper random variable.

