

# Generalized pCN Metropolis algorithms for Bayesian inference in Hilbert spaces

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Data Assimilation and Inverse Problems (U Warwick)

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1. Problem setting and Metropolis-Hastings algorithms in Hilbert spaces
2. The gpCN-Metropolis algorithm
3. Convergence

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## Groundwater flow modelling:

- ▶ PDE model for groundwater pressure head  $p$ , e.g.,

$$-\nabla \cdot (e^{\kappa(x)} \nabla p(x)) = 0$$

- ▶ Noisy observations of  $\kappa$  and  $p$  at locations  $x_j$ ,  $j = 1, \dots, J$
- ▶ Interested in functional  $f$  of flux  $\mathbf{u}(x) = -e^{\kappa(x)} \nabla p(x)$  (e.g., breakthrough time of pollutants)

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- ▶ Random function in Hilbert space  $\mathcal{H}$  with CONS  $\{\phi_m\}_{m \in \mathbb{N}}$

$$\kappa(x, \omega) = \sum_{m \geq 1} \xi_m(\omega) \phi_m(x),$$

where  $\xi = (\xi_m)_{m \in \mathbb{N}}$  random vector in  $\ell^2$

- ▶ Employ measurements of  $\kappa$  to fit Gaussian prior  $\mu_0$  for  $\kappa$  resp.  $\xi$ :

$$\xi \sim \mu_0 = N(0, C_0) \quad \text{on } \ell^2$$

- ▶ Conditioning prior  $\mu_0$  on noisy observations  $p \in \mathbb{R}^J$  of  $p$

$$p = G(\xi) + \varepsilon, \quad (\xi, \varepsilon) \sim \mu_0 \otimes N(0, \Sigma)$$

results in posterior via Bayes' rule [Stuart, 2010]

$$\mu(d\xi) \propto \exp(-\Phi(\xi)) \mu_0(d\xi), \quad \Phi(\xi) = \frac{1}{2} \|p - G(\xi)\|_{\Sigma^{-1}}^2.$$

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- ▶ Employ MCMC sampling to compute  $\mathbb{E}_\mu[f] = \int_{\mathcal{H}} f(\boldsymbol{\xi}) \mu(d\boldsymbol{\xi})$ .

- ▶ Construct Markov chain  $(\boldsymbol{\xi}_k)_{k \in \mathbb{N}}$  in  $\mathcal{H} = \ell^2$  with **transition kernel**

$$M(\boldsymbol{\eta}, A) := \mathbb{P}(\boldsymbol{\xi}_{k+1} \in A | \boldsymbol{\xi}_k = \boldsymbol{\eta})$$

which is  **$\mu$ -reversible**:

$$M(\boldsymbol{\xi}, d\boldsymbol{\eta}) \mu(d\boldsymbol{\xi}) = M(\boldsymbol{\eta}, d\boldsymbol{\xi}) \mu(d\boldsymbol{\eta})$$

- ▶ Then  $\mu$  **stationary measure** of chain and (under suitable conditions)

$$\frac{1}{n} \sum_{k=1}^n f(\boldsymbol{\xi}_k) \xrightarrow{n \rightarrow \infty} \mathbb{E}_\mu[f] \quad \text{a.s.}$$

- ▶  $\mu$ -reversible Markov chain geometrically ergodic and  $\xi_1 \sim \mu$ , then

$$\sqrt{n} \left( \frac{1}{n} \sum_{k=1}^n f(\xi_k) - \mathbb{E}_\mu[f] \right) \xrightarrow{d} N(0, \sigma_f^2),$$

see [Roberts & Rosenthal, 1997], where

$$\sigma_f^2 = \sum_{k=-\infty}^{\infty} \gamma_f(k), \quad \gamma_f(k) = \text{Cov}(f(\xi_1), f(\xi_{1+k}))$$

- ▶ Rapid decay of autocovariance function  $\gamma_f$  yields high **statistical efficiency**.
- ▶ Common measure of efficiency is **effective sample size**:

$$\text{ESS}_f(n) = n \frac{\sigma_f^2}{\text{Var}_\mu(f)}.$$

## Metropolis-Hastings algorithm for generating state $\xi_{k+1}$ of Markov chain

1. Draw a new state  $\eta$  from **proposal kernel**  $P(\xi_k, d\eta)$ :

$$\eta \sim P(\xi_k).$$

2. Accept proposal  $\eta$  with **acceptance probability**  $\alpha(\xi_k, \eta)$ , i.e., draw  $a \sim \text{Uni}[0, 1]$  and set

$$\xi_{k+1} = \begin{cases} \eta, & a \leq \alpha(\xi_k, \eta), \\ \xi_k, & \text{otherwise.} \end{cases}$$

Transition kernel of resulting chain is called **Metropolis kernel** and reads

$$M(\xi, d\eta) = \alpha(\xi, \eta)P(\xi, d\eta) + \left[ 1 - \int \alpha(\xi, \zeta) P(\xi, d\zeta) \right] \delta_{\xi}(d\eta).$$

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To ensure  $\mu$ -reversibility of Metropolis kernel we need to choose

$$\alpha(\boldsymbol{\xi}_k, \boldsymbol{\eta}) = \min \left\{ 1, \frac{d\nu^\top}{d\nu}(\boldsymbol{\xi}_k, \boldsymbol{\eta}) \right\},$$

where  $\nu(d\boldsymbol{\xi}, d\boldsymbol{\eta}) := P(\boldsymbol{\xi}, d\boldsymbol{\eta}) \mu(d\boldsymbol{\xi})$  and  $\nu^\top(d\boldsymbol{\xi}, d\boldsymbol{\eta}) := \nu(d\boldsymbol{\eta}, d\boldsymbol{\xi})$ .

Since  $\mu$  and  $\mu_0$  are equivalent (Bayes' rule), a  $\mu_0$ -reversible proposal  $P$ ,

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**Gaussian random walk-proposal:**  $P(\xi) = N(\xi, s^2 C_0)$

- ▶  $s \in \mathbb{R}_+$  is a stepsize parameter typically tuned such that acceptance rate

$$\bar{\alpha} := \int_{\mathcal{H}} \int_{\mathcal{H}} \alpha(\xi, \eta) P(\xi, d\eta) \mu(d\xi) \approx 0.234.$$

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**Preconditioned Crank-Nicolson-proposal:**  $P(\xi) = N(\sqrt{1-s^2}\xi, s^2 C_0)$

- ▶ Derived from a CN-scheme for (the drift of) the SDE

$$d\xi_t = (0 - \xi_t) dt + \sqrt{2} dB_t$$

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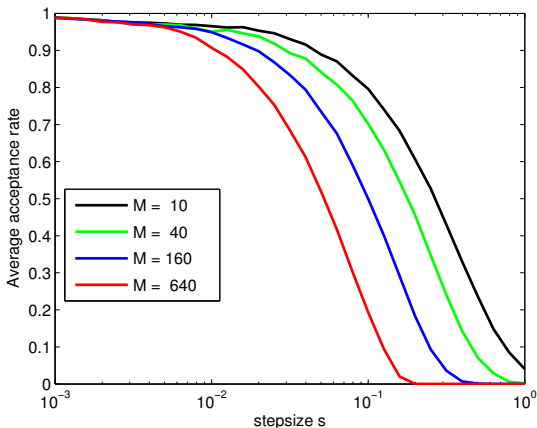
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**Problem:** Bayesian inference in 2D groundwater flow model.

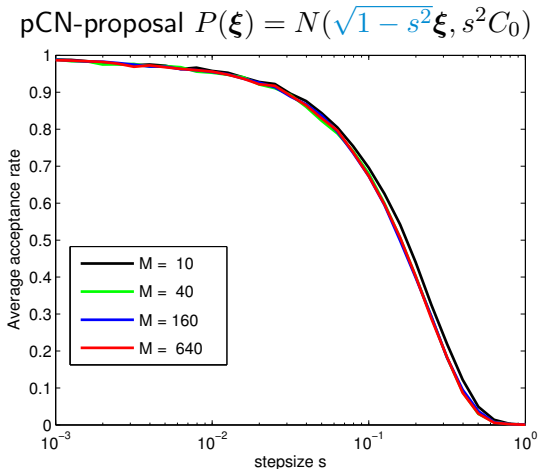
Acceptance rate vs. stepsize  $s$  for different dimensions  $M$  of  $\xi \in \mathbb{R}^M$ .

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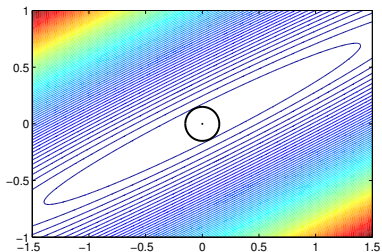


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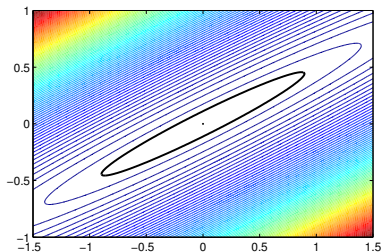
## Observation:

Higher statistical efficiency when proposal employs same covariance as target measure  $\mu$ , see [Tierney, 1994], [Roberts & Rosenthal, 2001], ...

Example:  $\mu = N(\mathbf{0}, \mathbf{C})$  in 2D, MH with different proposal covariances



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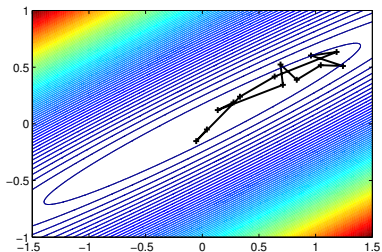


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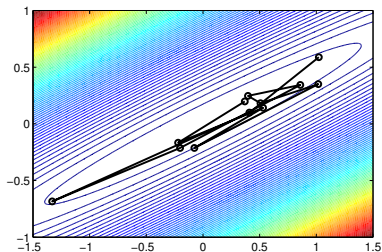
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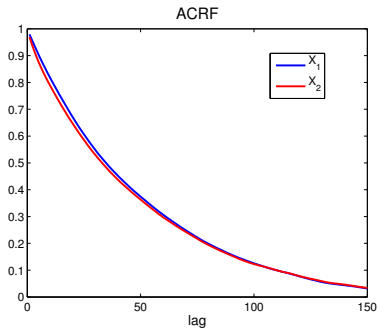


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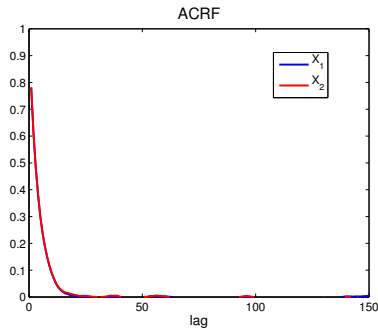
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- ▶ If forward map  $G$  were linear, then

$$\mu = N(m, C), \quad C = (C_0^{-1} + G^* \Sigma^{-1} G)^{-1}.$$

- ▶ **Idea:** Linearization of nonlinear  $G$  at  $\xi_0$

$$G(\xi) \approx \tilde{G}(\xi) := G(\xi_0) + J\xi, \quad J = \nabla G(\xi_0)$$

yields approximation to posterior covariance

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- ▶ Class of admissible proposal covariances:

$$C_{\Gamma} = (C_0^{-1} + \Gamma)^{-1}, \quad \Gamma \text{ positive, self-adjoint and bounded}$$

- ▶ Define **generalized pCN**-proposal kernel as

$$P_{\Gamma}(\boldsymbol{\xi}) = N(A_{\Gamma}\boldsymbol{\xi}, s^2 C_{\Gamma}),$$

cf. operator weighted proposals [Law, 2013] and [Cui et al., 2014]

- ▶ Enforcing  $\mu_0$ -reversibility of  $P_{\Gamma}$  – as for pCN-proposal  $P_0$  – yields

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## gpCN Metropolis

The Metropolis algorithm with the gpCN-proposal kernel

$$P_{\Gamma}(\boldsymbol{\xi}) = N(A_{\Gamma}\boldsymbol{\xi}, s^2 C_{\Gamma}),$$

where  $s \in (0, 1)$ , and the acceptance probability

$$\alpha(\boldsymbol{\xi}, \boldsymbol{\eta}) = \min \{1, \exp(\Phi(\boldsymbol{\xi}) - \Phi(\boldsymbol{\eta}))\}$$

is well-defined and yields a  $\mu$ -reversible Markov chain in  $\mathcal{H}$ .

It is called **gpCN Metropolis** and its Metropolis kernel denoted by  $M_{\Gamma}$ .

Note, for  $\Gamma = 0$  we recover the pCN Metropolis algorithm with kernel  $M_0$ .

## ► Setting

- 1D model:  $\frac{d}{dx} \left( e^{\kappa(x)} \frac{dp}{dx}(x) \right) = 0, \quad p(0) = 0, \quad p(1) = 2$
- Observations:  $\mathbf{p} = [p(0.2j)]_{j=1}^4 + \boldsymbol{\varepsilon}, \quad \boldsymbol{\varepsilon} \sim N(0, \sigma_{\boldsymbol{\varepsilon}}^2 I)$
- Prior:  $\kappa$  Brownian bridge on  $[0, 1]$ , i.e.,

$$\kappa(x, \boldsymbol{\xi}(\omega)) \approx \frac{\sqrt{2}}{\pi} \sum_{m=1}^M \xi_m(\omega) \sin(m\pi x), \quad \xi_m \sim N(0, m^{-2})$$

- Quantity of interest:  $f(\boldsymbol{\xi}) = \int_0^1 \exp(\kappa(x, \boldsymbol{\xi})) dx$

## ► Proposals for MH-MCMC

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### ► Proposals for MH-MCMC

Gaussian random walk (RW):  $P_1(\boldsymbol{\xi}) = N(\boldsymbol{\xi}, s^2 C_0)$

pCN:  $P_2(\boldsymbol{\xi}) = N(\sqrt{1 - s^2} \boldsymbol{\xi}, s^2 C_0)$

Gauss-Newton RW (GN-RW):  $P_3(\boldsymbol{\xi}) = N(\boldsymbol{\xi}, s^2 C_\Gamma)$

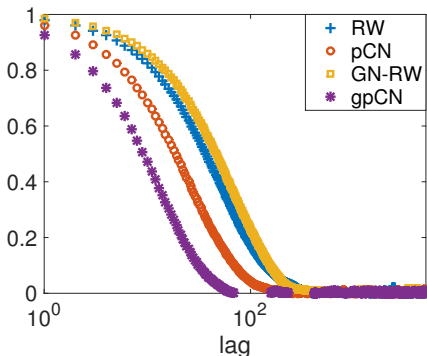
gpCN:  $P_4(\boldsymbol{\xi}) = N(A_\Gamma \boldsymbol{\xi}, s^2 C_\Gamma)$

$$\Gamma = \sigma_\varepsilon^{-2} J J^\top, \quad J = \nabla G(\boldsymbol{\xi}_{\text{MAP}})$$

### ► Results

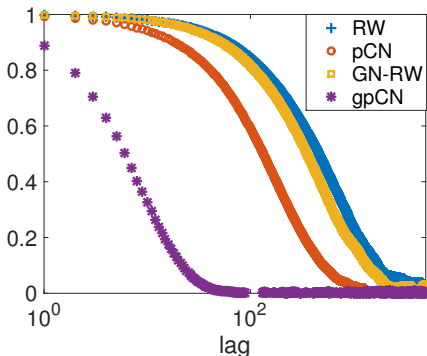
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Autocorrelation for  $M = 50$ ,  $\sigma_\varepsilon = 0.1$



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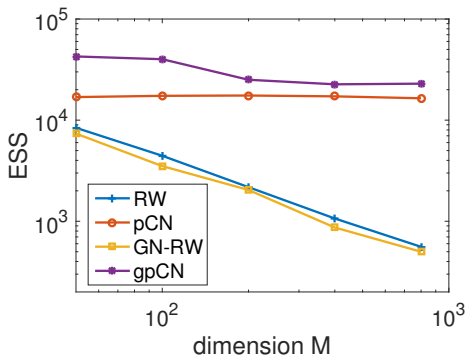
Autocorrelation for  $M = 400$ ,  $\sigma_\varepsilon = 0.01$





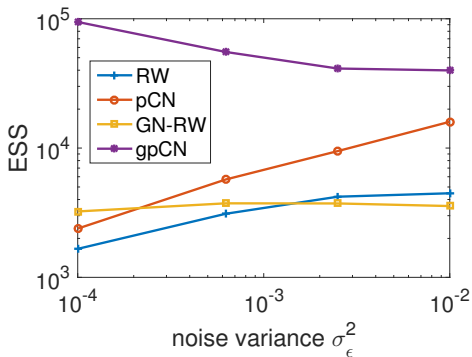
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Effective sample size vs. dimension



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Effective sample size vs. noise variance



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Consider Markov chain  $\{\xi_k\}_{k \in \mathbb{N}_0}$  with  $\mu$ -reversible transition kernel  $M$ .

- ▶ Kernel  $M$  is  $L^2_\mu$ -geometrically ergodic if  $r > 0$  exists such that

$$\|\mu - \nu M^k\|_{\text{TV}} \leq C_\nu \exp(-r k) \quad \forall \nu : \frac{d\nu}{d\mu} \in L^2_\mu(\mathcal{H}).$$

- ▶ Define associated Markov operator  $M : L^2_\mu \rightarrow L^2_\mu$  by

$$Mf(\xi) := \int_{\mathcal{H}} f(\eta) M(\xi, d\eta).$$

- ▶  $L^2_\mu$ -spectral gap of operator  $M$ :  $\text{gap}_\mu(M) := 1 - \|M - \mathbb{E}_\mu\|_{L^2_\mu \rightarrow L^2_\mu}$
- ▶  $M$  is  $L^2_\mu$ -geometrically ergodic iff  $\text{gap}_\mu(M) > 0$ .

- ▶ For pCN-Metropolis kernel  $M_0$  an  $L^2_\mu$ -spectral gap was proven in [Hairer et al., 2014] under certain conditions on  $\frac{d\mu}{d\mu_0}$ .

- ▶ **Our Strategy:**

Take a **comparative approach** and relate  $\text{gap}_\mu(M_\Gamma)$  to  $\text{gap}_\mu(M_0)$  in order to prove

$$0 < \text{gap}_\mu(M_0) \implies 0 < \text{gap}_\mu(M_\Gamma).$$

- ▶ **Idea behind:**

If kernels  $M_0$  and  $M_\Gamma$  do not “differ” too much, then (maybe) they inherit convergence properties from each other.

## Theorem (Comparison of spectral gaps)

For  $i = 1, 2$  let  $M_i$  be  $\mu$ -reversible Metropolis kernels with proposals  $P_i$  and acceptance probability  $\alpha$ .

Assume that

1. the associated Markov operators  $M_i$  are positive,
2. the Radon-Nikodym derivative  $\rho(\xi; \eta) := \frac{dP_1(\xi)}{dP_2(\xi)}(\eta)$  exists,
3. and for a  $\beta > 1$  we have

$$\sup_{\mu(A) \in (0, \frac{1}{2}]} \frac{\int_A \int_{A^c} \rho^\beta(\xi; \eta) P_2(\xi, d\eta) \mu(d\xi)}{\mu(A)} < \infty,$$

Then

$$\text{gap}_\mu(M_1)^{2\beta} \leq K_\beta \text{gap}_\mu(M_2)^{\beta-1}.$$

## Lemma (Positivity of Markov operators)

*The Markov operator  $M_\Gamma$  associated to gpCN-Metropolis is positive for any admissible  $\Gamma$ .*

## Lemma (Absolute continuity, integrability of density)

*There exists a density between the pCN- and gpCN-proposal*

$$\rho_\Gamma(\boldsymbol{\xi}; \boldsymbol{\eta}) := \frac{dP_0(\boldsymbol{\xi})}{dP_\Gamma(\boldsymbol{\xi})}(\boldsymbol{\eta})$$

*and constants  $b, K < \infty$  such that for  $\beta < 1 + \frac{1}{2\|H_\Gamma\|}$*

$$\int_{\mathcal{H}} \rho_\Gamma^\beta(\boldsymbol{\xi}; \boldsymbol{\eta}) P_\Gamma(\boldsymbol{\xi}, d\boldsymbol{\eta}) \leq K \exp\left(\frac{b^2}{2}\|\boldsymbol{\xi}\|^2\right).$$

- For  $R > 0$  set  $B_R := \{\xi \in \mathcal{H} : \|\xi\| < R\}$  and define

$$\mu_R(d\xi) := \frac{1}{\mu(B_R)} \mathbf{1}_{B_R}(\xi) \mu(d\xi).$$

- For Metropolis kernel  $M$  with proposal  $P$  and acceptance probability  $\alpha$  set

$$M_R(\xi, d\eta) := \alpha_R(\xi, \eta) P(\xi, d\eta) + \left[ 1 - \int_{\mathcal{H}} \alpha_R(\xi, \zeta) P(\xi, d\zeta) \right] \delta_\xi(d\eta)$$

where  $\alpha_R(\xi, \eta) := \mathbf{1}_{B_R}(\eta) \alpha(\xi, \eta)$ .

### Lemma

If  $M$  is self-adjoint and positive on  $L^2_\mu(\mathcal{H})$ , then so is  $M_R$  on  $L^2_{\mu_R}(\mathcal{H})$  and

$$\text{gap}_{\mu_R}(M_R) \geq \text{gap}_\mu(M) - \sup_{\xi \in B_R} M(\xi, B_R^c).$$



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## Theorem (Spectral gap of gpCN-Metropolis for restricted measure)

If

$$\text{gap}_\mu(M_0) > 0,$$

then for any admissible  $\Gamma$  and any  $\epsilon > 0$  there exists a number  $R < \infty$  such that

$$\|\mu - \mu_R\|_{TV} < \epsilon \quad \text{and} \quad \text{gap}_{\mu_R}(M_{\Gamma,R}) > 0.$$

Proof employs previous lemmas and comparison theorem to show

$$\text{gap}_\mu(M_0) > 0 \quad \implies \quad \text{gap}_{\mu_R}(M_{0,R}) > 0 \quad \implies \quad \text{gap}_{\mu_R}(M_{\Gamma,R}) > 0.$$

Density  $\rho_{\Gamma}(\boldsymbol{\xi}) = \frac{dP_0(\boldsymbol{\xi})}{dP_{\Gamma}(\boldsymbol{\xi})}$  allows for **state-dependent proposal covariances**:

- ▶ Let  $\boldsymbol{\xi} \mapsto \Gamma(\boldsymbol{\xi})$  be measurable and define proposal kernel

$$P_{\text{loc}}(\boldsymbol{\xi}) := N(A_{\Gamma(\boldsymbol{\xi})}\boldsymbol{\xi}, s^2 C_{\Gamma(\boldsymbol{\xi})}).$$

- ▶ Following an approach as in [Beskos et al., 2008] we get

$$P_{\text{loc}}(\boldsymbol{\xi}, d\boldsymbol{\eta}) \mu_0(d\boldsymbol{\xi}) = \frac{\rho_{\Gamma(\boldsymbol{\eta})}(\boldsymbol{\eta}, \boldsymbol{\xi})}{\rho_{\Gamma(\boldsymbol{\xi})}(\boldsymbol{\xi}, \boldsymbol{\eta})} P_{\text{loc}}(\boldsymbol{\eta}, d\boldsymbol{\xi}) \mu_0(d\boldsymbol{\eta}).$$

- ▶ Obtain  $\mu$ -reversible MH algorithm with proposal  $P_{\text{loc}}$  and

$$\alpha_{\text{loc}}(\boldsymbol{\xi}, \boldsymbol{\eta}) := \min \left\{ 1, \exp(\Phi(\boldsymbol{\eta}) - \Phi(\boldsymbol{\xi})) \frac{\rho_{\Gamma(\boldsymbol{\xi})}(\boldsymbol{\xi}, \boldsymbol{\eta})}{\rho_{\Gamma(\boldsymbol{\eta})}(\boldsymbol{\eta}, \boldsymbol{\xi})} \right\}$$

- ▶ Same approach works for  $P'_{\text{loc}}(\boldsymbol{\xi}) := N(\sqrt{1-s^2}\boldsymbol{\xi}, s^2 C_{\Gamma(\boldsymbol{\xi})})$ .

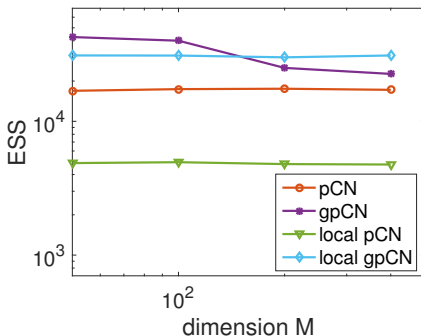
Same problem setting as before, but now also consider “local” proposals

$$\text{local pCN: } P_5(\boldsymbol{\xi}) = N(\sqrt{1 - s^2}\boldsymbol{\xi}, s^2 C_{\Gamma(\boldsymbol{\xi})})$$

$$\text{local gpCN: } P_6(\boldsymbol{\xi}) = N(A_{\Gamma(\boldsymbol{\xi})}\boldsymbol{\xi}, s^2 C_{\Gamma(\boldsymbol{\xi})})$$

with  $\Gamma(\boldsymbol{\xi}) = \nabla G(\boldsymbol{\xi})^\top \Sigma^{-1} \nabla G(\boldsymbol{\xi})$ .

Effective sample size vs. dimension



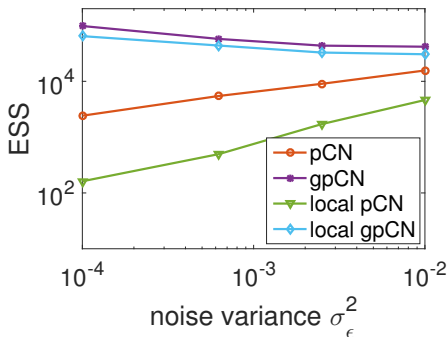
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Effective sample size vs. noise variance



- ▶ Generalized pCN-Metropolis allows to beneficially employ approximation of posterior covariance for proposal kernel
- ▶ gpCN seems to perform independent of dimension and noise variance
- ▶ Geometric ergodicity of gpCN-Metropolis proven by general framework for relating spectral gaps of Metropolis algorithms
- ▶ gpCN-Metropolis with state-dependent proposal covariance possible







### Some open issues:

- ▶ Proof of higher efficiency of gpCN-Metropolis
- ▶ Proof and theoretical understanding of variance-independence

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### **Some open issues:**

- ▶ Proof of higher efficiency of gpCN-Metropolis
- ▶ Proof and theoretical understanding of variance-independence

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