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Euler Day

Relaxation Routes to Steady Euler Flows
of Complex Topology

Keith Moffatt

DAMTP, Cambridge

The Euler equations :

$$\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} = -\frac{1}{\rho} \nabla p \quad (*)$$

Restrict attention to incompressible flow

$$\nabla \cdot \underline{u} = 0$$

and take $\rho = \text{const.} = 1$.

$$\underline{\omega} = \nabla \wedge \underline{u} \quad \text{Vorticity field}$$

Alternative form of (*)

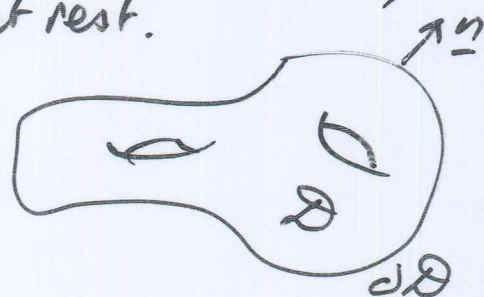
$$\frac{\partial \underline{u}}{\partial t} = \underline{u} \wedge \underline{\omega} - \nabla h$$

$$\text{where } h = p + \frac{1}{2} u^2$$

(2)

Consider flows in a finite domain \mathcal{D} ,
smooth bdy $\partial\mathcal{D}$, fixed & at rest.

but \mathcal{D} may have
non-trivial topology.



$$\underline{u} \cdot \underline{n} = 0 \text{ on } \partial\mathcal{D}$$

Under Euler evolution

$$\frac{\partial \underline{\omega}}{\partial t} = \nabla \wedge (\underline{u} \wedge \underline{\omega})$$

Vortex lines are frozen in the fluid.

- $\underline{\omega}$ -lines: ~~are~~ Helmholtz got this wrong (1858)
- i) closed curves in \mathcal{D}
 - or ii) lie on surfaces
 - or iii) are chaotic in subdomains of \mathcal{D} generic behaviour
 - or iv) may terminate on $\partial\mathcal{D}$

If $\underline{u} = 0$ on $\partial\mathcal{D}$ (i.e. no-slip)

then $\underline{\omega} \cdot \underline{n} = 0$ on $\partial\mathcal{D}$ also

(and there is no vortex sheet on $\partial\mathcal{D}$)

If $\underline{\omega} \cdot \underline{n} = 0$ on $\partial\mathcal{D}$ at $t=0$, then this holds
for $t > 0$ also ($\partial\mathcal{D}$ is a 'vorticity surface')

Invariants

Suppose $\underline{u}(\underline{x}, t)$ is smooth (regular, C^∞ , $n \geq 1$)

$$E = \frac{1}{2} \int_{\mathcal{D}} \underline{u}^2 dV = \text{const.} \quad \underline{\text{Energy}}$$

$$H = \int_{\mathcal{D}} \underline{u} \cdot \underline{\omega} dV \quad \underline{\text{Helicity}}$$

$H = \text{const.}$ only if $\underline{\omega} \cdot \underline{n} = 0$ on $\partial \mathcal{D}$ *

- a measure of the 'net' linkage of $\underline{\omega}$ -lines in \mathcal{D} .

There may be ^{Lograngian} subdomains $\mathcal{D}_L(t)$ s.t.

$$\underline{\omega} \cdot \underline{n} = 0 \text{ on } \partial \mathcal{D}_L$$

If so then $H_L = \int_{\mathcal{D}_L} \underline{u} \cdot \underline{\omega} dV = \text{const.}$

for each such subdomain.

* If $\underline{\omega} \cdot \underline{n} \neq 0$ on $\partial \mathcal{D}$, then any braid of $\underline{\omega}$ -lines can be untangled by tangential (slip) motion on $\partial \mathcal{D}$.

Momentum

$$\underline{P} = \int \underline{u} \, dV = 0$$

$$\left(\int_{\mathcal{D}} u_i \, dV = \int_{\mathcal{D}} \frac{\partial}{\partial x_j} (x_i u_j) \, dV = \int_{\partial \mathcal{D}} (\underline{n} \cdot \underline{u}) x_i \, dS = 0 \right)$$

Angular momentum ?

$$\underline{M} = \int \underline{x} \wedge \underline{u} \, dV \neq 0 \text{ in general}$$

but $\frac{d\underline{M}}{dt} \neq 0$ also in general

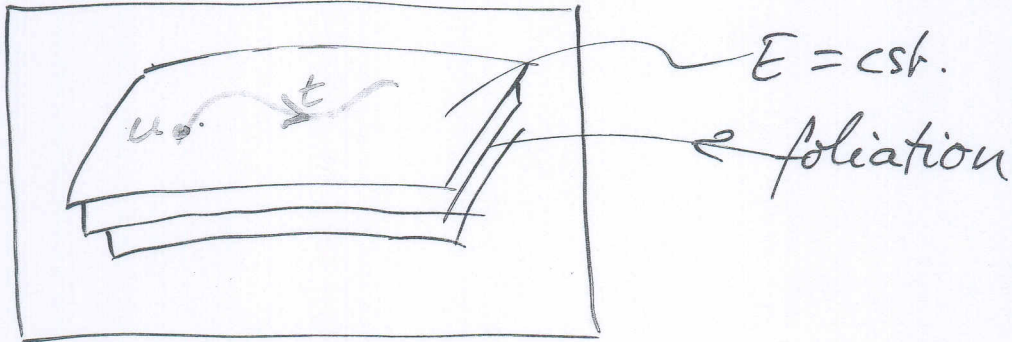
(the flow induces a pressure field which in general exerts a torque on the boundary; $\partial \mathcal{D}$ exerts an equal and opposite torque \underline{G} on the fluid

$$\text{and } \frac{d\underline{M}}{dt} = \underline{G}$$

Function space \mathcal{F}

$$\{ \underline{u} : \nabla \cdot \underline{u} = 0, E < \infty, \dots ? \}$$

allow vortex sheets,
but not concentrated
line vortices! (5)



A velocity field \underline{u} is represented by a point in \mathcal{F} .

Under Euler evolution, this point follows a trajectory on ~~the~~ 'folium' $E = \text{cst.}$

Dynamical systems point of view.

Fixed points of the Euler system are steady flows $\underline{u}(x)$ satisfying

$$\underline{u} \wedge \underline{\omega} = \nabla h$$

$$\underline{u} \cdot \nabla h = 0 \quad \underline{\omega} \cdot \nabla h = 0$$

so \underline{u} -lines and $\underline{\omega}$ -lines lie on surfaces $h = \text{cst.}$

(Only if $h \equiv \text{cst.}$ can $\underline{\omega}$ -lines be chaotic for a steady Euler flow.)

Kelvin: $\delta'E = 0$ for isovortical perturbations

Analogy with magnetostatics:

Steady Euler: $\mathbf{E}: \underline{u} \wedge \underline{\omega} = \nabla h$ $\underline{\omega} = \nabla \wedge \underline{u}, \nabla \cdot \underline{u} = 0$

Magnetostatics: $\mathbf{M}: \underline{j} \wedge \underline{B} = \nabla p, \underline{j} = \nabla \wedge \underline{B}, \nabla \cdot \underline{B} = 0$

$$\underline{u} \longleftrightarrow \underline{B}$$

$$\underline{\omega} \longleftrightarrow \underline{j}$$

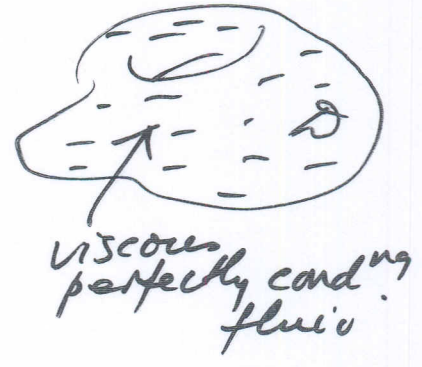
$$h \longleftrightarrow p_0 - p$$

So if, by any means, we can find a solution of the problem \mathbf{M} , we have, via this analogy, found a corresponding solution of the problem \mathbf{E} .

Note that current sheets in \mathbf{M} correspond to vortex sheets in \mathbf{E} .

Magnetic Relaxation

Let $\underline{B}_0(x)$ ($\nabla \cdot \underline{B}_0 = 0, \underline{n} \cdot \underline{B}_0 = 0$ on ∂D)
be a field of arbitrarily
complex topology in D .



This relaxes to equilibrium via MHD
evolution:

$$\left. \begin{aligned} \frac{\partial \underline{B}}{\partial t} &= \nabla \wedge (\underline{v} \wedge \underline{B}) \\ \frac{D \underline{v}}{Dt} &= -\nabla p + \underline{j} \wedge \underline{B} + \nu \nabla^2 \underline{v} \end{aligned} \right\} \text{N.S.}$$

$$\underline{v} = 0, \underline{n} \cdot \underline{B} = 0 \text{ on } \partial D$$

$$\nabla \cdot \underline{v} = 0, \nabla \cdot \underline{B} = 0$$

We are free to make whatever dynamical
model we like, provided it dissipates energy
e.g. ($Re \ll 1$: neglect $D \underline{v} / Dt$; 'Stokes')

Then we have a simple energy eqn:

$$\frac{dM}{dt} = \frac{d}{dt} \frac{1}{2} \int_D \underline{B}^2 dV = -\nu \int_D (\nabla \wedge \underline{v})^2 dV$$

Monotonic decrease of M

(8)

Lower Bound on E

Magnetic helicity $H_M = \int \underline{A} \cdot \underline{B} dV$

$$\underline{B} = \nabla \times \underline{A}$$
$$\nabla \cdot \underline{A} = 0$$

is conserved

$$(\underline{B} \cdot \underline{n} = 0 \text{ on } \partial \mathcal{D})$$

Schwarz $\int_{\mathcal{D}} B^2 dV \int_{\mathcal{D}} A^2 dV \geq \left(\int \underline{A} \cdot \underline{B} dV \right)^2$

Poincaré $\frac{\int B^2 dV}{\int A^2 dV} \geq \rho_0^2 \left(\sim \frac{1}{L_D^2} ? \right)$

So $\frac{1}{2} \int B^2 dV \geq \frac{1}{2} \rho_0 |H_M| = M_{\min}$

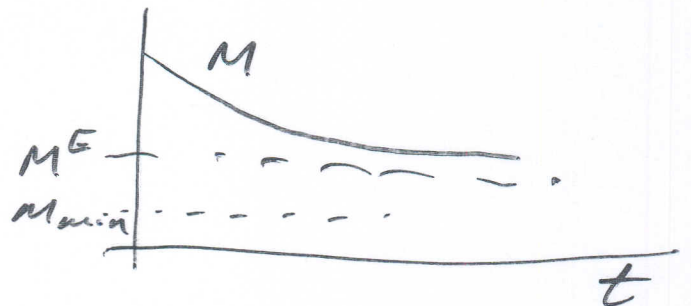
Positive lower bound on M if $H_M \neq 0$

(Actually there is a lower bound even if $H_M = 0$; it is sufficient that the topology of \underline{B} be non-trivial : Freedman ~1989?)

so $M \downarrow M^E$ as $t \rightarrow \infty$

$$\int (\nabla \cdot \underline{v})^2 dV \rightarrow 0$$

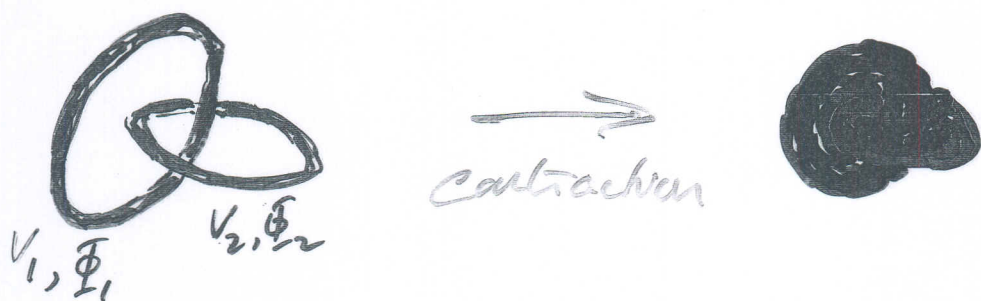
$$\therefore \int v^2 dV \rightarrow 0$$



$\therefore (?) \underline{v} \rightarrow 0$ uniformly in \underline{x}

(unproved, but extremely plausible!)

The Physical Mechanism of Relaxation is just contraction of \underline{B} -lines in response to Maxwell tension, e.g. for two linked flux tubes



Volumes and fluxes are conserved
 V_1, V_2 Φ_1, Φ_2

Linkage limits the relaxation process
Tangential discontinuity of \underline{B} (i.e. current sheet) appears in the limit

If (as seems inevitable!) $\nu \rightarrow 0$

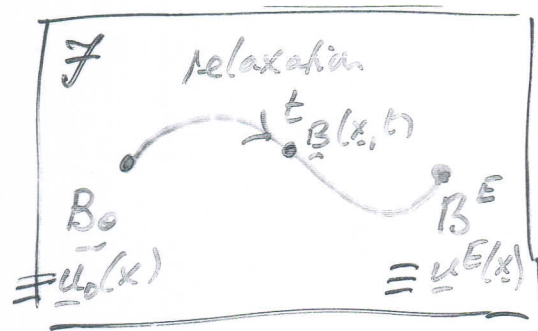
then in the limit $\underline{j} \wedge \underline{B} = \nabla p$

Magnetostatic eqn.

and the equilibrium field $\underline{B}(x)$ is

topologically accessible from the initial arbitrarily complex field $\underline{B}_0(x)$

Back to the function space \mathcal{F} :



So by this means, we have found a steady Euler flow $\underline{u}^E(x)$ whose streamline structure is 'topologically accessible' from that of the arbitrary flow $\underline{u}_0(x)$.

(not topologically equivalent, because tangential discontinuities can, and in general, do appear.)

Question: How 'bad' can the singularities of \underline{u}^E be? What is the 'natural' function space \mathcal{F} that includes all \underline{u}^E resulting from $C^\infty \underline{u}_0$'s?

Comments:

1. VCY relaxation (Vallis, Carnevalle, Young) JFM ~ 1990
- $$\underline{v} = \underline{u} + \alpha \partial \underline{u} / \partial t$$
- $$\frac{\partial \underline{u}}{\partial t} = \underline{v} \cdot \nabla \underline{u} - \nabla h \quad \underline{\omega} = \nabla \wedge \underline{u}$$
- $$\Rightarrow \frac{dE}{dt} = -\alpha \int \left(\frac{\partial \underline{u}}{\partial t} \right)^2 dV$$

But no bound on E for general 3D flows.

Upper bound on E for axisymm. flows; \therefore useful with $\alpha < 0$.

2. In 2D or axisymm. ~~to~~ magnetic relaxation, with no saddle points, current sheets can't form. But saddle-point collapse can lead to current sheets:



3. Presence of vortex sheets in analogous Euler flows \Rightarrow Kelvin-Helmholtz instability

3D Euler flows do not satisfy Arnold's (1966) sufficient condⁿ for stability

$$\delta^2 E > 0 \quad \text{or} \quad \delta^2 E < 0 \quad (\text{all } \textit{with} \text{ isovortical part})$$