<u>Twice iterated tent map</u> : find corresponding map  $M^{2}(x)$ 

1) Note there are points where the map M(x) goes to zero or 1.

$$M(x) M(\frac{1}{2}) = 1 M(0) = 0 M(1) = 0$$
$$M(\frac{1}{4}) = \frac{1}{2} M(\frac{3}{4}) = \frac{1}{2}.$$

also,

2) There are points where 
$$M^2(x)$$
 goes to zero or 1.

Clearly,

$$M^{2}\left(\frac{1}{4}\right) = M\left(M\left(\frac{1}{4}\right)\right) = M\left(\frac{1}{2}\right) = 1$$
$$M^{2}\left(\frac{3}{4}\right) = M\left(M\left(\frac{3}{4}\right)\right) = M\left(\frac{1}{2}\right) = 1$$

and

$$M^{2}\left(\frac{1}{2}\right) = M\left(M\left(\frac{1}{2}\right)\right) = M(1) = 0$$
$$M^{2}(0) = M(M(0)) = M(0) = 0$$

Folding points – another method.





$$\frac{1}{4} \text{ iterates as } M\left(\frac{1}{4}\right) = \frac{1}{2} \quad M^2\left(\frac{1}{4}\right) = 1 \quad M^3\left(\frac{1}{4}\right) = 0$$
  
$$\frac{1}{8} \text{ iterates as } M\left(\frac{1}{8}\right) = \frac{1}{4} \quad \text{and } M\left(\frac{1}{4}\right) = \frac{1}{2} \quad M^2\left(\frac{1}{4}\right) = 1 \quad \text{so } M^4\left(\frac{1}{8}\right) = 0$$
  
$$\frac{1}{16} \text{ iterates as } M\left(\frac{1}{16}\right) = \frac{1}{4} \quad \text{so similarly} \quad M^5\left(\frac{1}{16}\right) = 0$$

Now consider all the segments between, ie

$$0 - \frac{1}{4}, \quad \frac{1}{4} - \frac{1}{2}, \quad \frac{1}{2} - \frac{3}{4}, \quad \frac{3}{4} - 1.$$

## Notation



Write M(x) as  $M_{<}(x) = 2x$  "left half"  $M_{>}(x) = 2(1-x)$  "right half"

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Clearly,  $\begin{bmatrix} 0 - \frac{1}{4} \end{bmatrix} \rightarrow \begin{bmatrix} 0 - \frac{1}{2} \end{bmatrix}$   $M_{<}(x)$ and  $\begin{bmatrix} 0 - \frac{1}{2} \end{bmatrix} \rightarrow \begin{bmatrix} 0 - 1 \end{bmatrix}$   $M_{<}(x)$ 

only need  $M_{<}(x)$  here

$$0 \le x \le \frac{1}{4} \quad M^2(x) = M_{<}^2(x)$$

Now

$$\begin{bmatrix} \frac{1}{4} - \frac{1}{2} \end{bmatrix} \rightarrow \begin{bmatrix} \frac{1}{2} - 1 \end{bmatrix} \qquad M_{<}(x)$$
$$\begin{bmatrix} \frac{1}{2} - 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 - 0 \end{bmatrix} \qquad M_{>}(x)$$

so,

$$\frac{1}{4} \le x \le \frac{1}{2} \quad M^2(x) = M_{>}(M_{<}(x))$$

similarly

$$\frac{1}{2} \le x \le \frac{3}{4} \quad M^2(x) = M_{>}^2(x)$$
$$\frac{3}{4} \le x \le 1 \quad M^2(x) = M_{<}(M_{>}(x))$$

Then plug in  $M_{<}$ ,  $M_{>}$  to get the result.

$$0 \le x \le \frac{1}{4} \quad M^{2}(x) = 2[2x] = 4x$$

$$\frac{1}{4} \le x \le \frac{1}{2} \quad M^{2}(x) = 2(1 - [2x]) = 2 - 4x$$

$$\frac{1}{2} \le x \le \frac{3}{4} \quad M^{2}(x) = 2(1 - [2(1 - x)])$$

$$= 2(1 - 2 + 2x)$$

$$= 4x - 2$$

$$\frac{3}{4} \le x \le 1 \quad M^{2}(x) = 2[2(1 - x)]$$

$$= 4 - 4x$$

Sketch



Note – neighbouring points on x move apart as length of M(x) line increases as we iterate – stretch/fold.



 $p^{th}$  iterate of map



Therefore, any points in x separated by more than  $2^{-p}$  can be <u>anywhere</u> in [0,1] after p iterates.

- chaos
  - follows from inevitability of map.

Note, gradient is always  $2^p > 1$ 

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therefore, always globally unstable.

## local gradient and stability

Note that this shows if a fixed point is <u>unstable</u>.

eg: tent map

$$x_{n+1} = 2x_n, \ x_{n+1} = 2(1-x_n)$$



1x

Mathematically, for some map M(x) consider small displacement  $\delta x_n$  from fixed point  $\overline{x}$  and Taylor expand  $x_{n+1} = M(x_n)$  at  $x_n = \overline{x} + \delta x_n$ .

$$x_{n+1} = M(\overline{x} + \delta x_n) \simeq M(\overline{x}) + \delta x_n \frac{dM}{dx}(\overline{x}) + 0(\delta x^2) \simeq \overline{x} + \delta x_n \frac{dM}{dx}(\overline{x})$$
$$x_{n+1} = \overline{x} + \delta x_{n+1}$$

but  $x_n$ 

so 
$$\overline{x} + \delta x_{n+1} = \overline{x} + \delta x_n \frac{dM}{dx}(\overline{x})$$
 ie:  $\frac{\delta x_{n+1}}{\delta x_n} = \frac{dM}{dx}(\overline{x})$ .

So, for stability  $\left| \frac{dM}{dx}(\bar{x}) \right| < 1$ .

Must hold for all iterates.. Lyapunov exponents

## Measure of divergence of trajectories.

Lyapunov exponents (or Lyapunov number)

Consider a general map

$$x_{n+1} = f(x_n)$$

how fast are two initially neighbouring points converging/diverging?

Have initial condition  $x_0$ .

This then has iterates 
$$x_1, x_2...x_n$$
  
 $x_1 = f(x_0), \quad x_2 = f(x_1), \text{ etc.}$ 

Consider an initially neighbouring point  $\tilde{x}_0 = x_0 + \varepsilon_0$  separated from  $x_0$  by  $\varepsilon_0 \ll 1$ .

After we iterate  $\tilde{x}_1 = f(\tilde{x}_0) = f(x_0 + \varepsilon_0) = f(x_0) + \varepsilon_0 \frac{df}{dx}(x_0) + \dots$ , by Taylor expansion.

But, after one iterate  $\tilde{x}_1 = x_1 + \varepsilon_1$  Now two points are separated by  $\varepsilon_1$ 

then 
$$\tilde{x}_1 = x_1 + \varepsilon_1 = f(x_0 + \varepsilon_0) = f(x_0) + \varepsilon_0 \frac{df}{dx}(x_0) + \dots$$
  
ie:  $\varepsilon_1 = \varepsilon_0 f'(x_0)$  to first order in  $\varepsilon_0$ .

So, generally for  $j^{th}$  iterate have

$$\tilde{x}_j = x_j + \varepsilon_j$$
  $\varepsilon_j = \varepsilon_{j-1} f'(x_{j-1})$ 

provided  $\varepsilon_j \ll 1 \quad 0 < j < n$ .

Then

$$\tilde{x}_{n} = x_{n} + \varepsilon_{n} = x_{n} + \varepsilon_{n-1} f'(x_{n-1})$$

$$= x_{n} + \varepsilon_{n-2} f'(x_{n-2}) f'(x_{n-1})$$

$$= x_{n} + \varepsilon_{0} f'(x_{0}) f'(x_{1}) \dots f'(x_{n-1})$$

$$\tilde{x}_{n+1} = x_{n+1} + \varepsilon_{0} f'(x_{0}) \dots f'(x_{n})$$

$$\tilde{x}_{n+1} = x_{n+1} + \varepsilon_{0} \prod_{j=0}^{n} f'(x_{j})$$

Now use a trick (handy to turn a product into a sum)

$$f'(x_j) = e^{\ln f'(n_j)}.$$

In addition, we do not know the signs of all  $f'(x_j)$  (and we don't need to know – just interested in whether the product is getting bigger or not in <u>magnitude</u>).

So, write

$$\tilde{x}_n = x_n + \varepsilon_0 \exp\left(\sum_{j=0}^{n-1} \ln\left|f'(x_j)\right|\right),$$

and hence, define Lyapunov number (exponent)

$$\lambda = \lim_{n \to \infty} \frac{1}{n} \sum_{j=0}^{n-1} \ln \left| f'(x_j) \right|$$

NB: after written with  $n-1 \simeq n$  $n \rightarrow \infty$ 

which is a measure of exponential divergence of trajectories

$$\tilde{x}_n - x_n = \varepsilon_0 e^{n\lambda}$$

What about approximation  $\varepsilon_i \ll 1$ ?

Can always take  $\varepsilon_0$  (and thus  $\varepsilon_j$ ) infinitesimally small – still same dynamics.

So  $\lambda < 0$  - x is at an attractor - trajectories converge.  $\lambda > 0$  - x is at a repellor  $\rightarrow$  chaos trajectories diverge.

Note, there is a  $\lambda$  for each degree of freedom (coordinate) here one (*x*).

Note that generally if all 
$$|f'(x_j)| > 1$$
 all iterates

then al	1		$\ln \left  f'(x_j) \right  $	> 0		
then		$\sum \ln j$	$f'(x_j) > 0$ chaotic		and $\lambda > 0$	
Simila	rly, if <u>al</u>	$\frac{1}{f'}$	$_{j}\left)\right  < 1$			
	then al	1	$\ln \left  f'(x_j) \right  \cdot$	< 0		
and			$\lambda < 0$	-	stable attractor	
	-	if our g	raphical resu	lt that fo	r each iterate if $ gradient  > 1$ unstable	
*	-	now ge	eneralised this	s for all i	terates of the map – characterised the dynamics.	*
Tent m	ap after	<i>p</i> iterat	tes:			



\* Therefore, tent map globally chaotic \*

Next, consider polynomial maps. More complicated f'(x)