

STOCHASTIC PROCESSES:
A REVIEW OF PROBABILITY THEORY
CIS002-2 COMPUTATIONAL ALGEBRA AND NUMBER
THEORY

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10:00, Friday 09th March 2012

OUTLINE

- 1 RANDOM VARIABLES AND MUTUALLY EXCLUSIVE EVENTS
- 2 INDEPENDENCE
- 3 DEPENDENT RANDOM VARIABLES
- 4 CORRELATIONS AND CORRELATION COEFFICIENTS
- 5 ADDING RANDOM VARIABLES TOGETHER
- 6 TRANSFORMATION OF A RANDOM VARIABLE
- 7 THE DISTRIBUTION FUNCTION
- 8 THE CHARACTERISTIC FUNCTION
- 9 THE MULTIVARIATE GAUSSIAN

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RANDOM VARIABLES AND MUTUALLY EXCLUSIVE EVENTS

- Probability theory is used to describe a situation in which we do not know the precise value of a variable, but may have an idea of the likelihood that it will have one of a number of possible values.
- let us call the unknown quantity X , referred to as a random variable.
- We describe the likelihood X will have one of all the possible values as the probability, $0 < X < 1$.
- The various values of X , and of any random variable, are an example of mutually exclusive events.
- The total probability that one of two or more mutually exclusive events occurs is the sum of the probabilities for each event

RANDOM VARIABLES: ROLL OF DICE.

- The sum of the probabilities for all the mutually exclusive possible values must always be unity.
- If a die is fair, then all the possible values are equally likely, therefore the probability for each event is $1/6$.
- in this example, x is a discrete random variable.

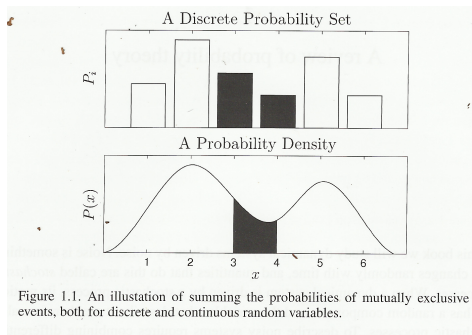


Figure 1.1. An illustration of summing the probabilities of mutually exclusive events, both for discrete and continuous random variables.

If we want to know the probability for X , being the roll of a die, being in the range from 4 to 6, we sum all the probabilities for the values from 4 to 6, illustrated in the figure 1.1 above.

CONTINUOUS RANDOM VARIABLES

- If X could take the value of any real number, then we say X is a continuous random variable.
- If X is a continuous random variable, the probability is now a function of x , where x ranges over the values of X .
- This type of probability is called a probability density, denoted $P(x)$.
- The probability for X to be in the range $x = a$ to $x = b$ is now the area under $P(x)$ from $x = a$ to $x = b$

$$\text{Prob}(a < X < b) = \int_a^b P(x)dx$$

- Thus, the integration (area under the curve) of $P(x)$ over the whole real number line (from $-\infty$ to ∞) must be unity, since X must take on one of these values.

$$\int_{-\infty}^{\infty} P(x)dx = 1$$

STATISTICAL DEFINITIONS

- The average of X , also known as the mean, or expectation value, of X is defined by

$$\langle X \rangle \equiv \int_{-\infty}^{\infty} P(x)x dx$$

- If $P(x)$ is symmetric about $x = 0$, then it is not difficult to see that the mean of X is zero.
- If the density is symmetric about any other point then the mean is the value at this point.
- The variance of X is defined as

$$V_X \equiv \int_{-\infty}^{\infty} P(x)(x - \langle X \rangle)^2 dx = \langle X^2 \rangle - \langle X \rangle^2$$

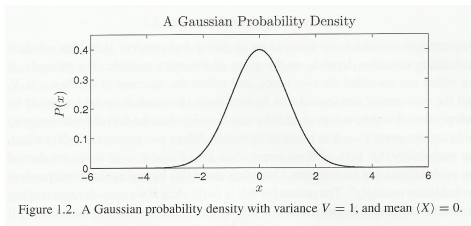
- The standard deviation of X , denoted by σ_X and defined as the square root of the variance, is a measure of how broad the probability density for X is - that is, how much we expect X to deviate from the mean value.

THE GAUSSIAN

- An important example of a probability density is the Gaussian, given by

$$P(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

- The mean of this Gaussian is $\langle X \rangle = \mu$ and the variance is $V(x) = \sigma^2$.
- A plot of this probability density is shown in the figure 1.2 below.



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INDEPENDENCE

- Two random variables are referred to as independent if neither of their probability densities depends on the value of the other variable.
- The probability that two independent random events occur is the product of their probabilities.
- This is true for discrete and continuous independent random variables.
- In the case of continuous independent random variables we speak of the joint probability density.

$$P(x, y) = P_X(x)P_Y(y)$$

- We can take this further and ask what the probability that X falls within the interval $[a, b]$ and Y falls in the interval $[c, d]$. This is

$$\int_a^b \int_c^d P(x, y) dy dx = \int_a^b P_X(x) dx \int_c^d P_Y(y) dy$$

- It is also worth noting that when two variables are independent, then the expectation value of their product is simply the product of their expectation values

$$\langle XY \rangle = \langle X \rangle \langle Y \rangle$$

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DEPENDENT RANDOM VARIABLES

- Two random variables are referred to as dependent if their joint probability density, $P(x, y)$, does not factor into the product of their respective probability densities.
- To obtain the probability density for one variable alone (say X), we integrate the joint probability density over all values of the other variable (in this case Y).
- For each value of X , we want to know the total probability summed over all the mutually exclusive values that Y can take.
- In this context, the probability densities for a single variable are referred to as the marginals of the joint density.
- If we know nothing about Y , then our probability density for X is just the marginal

$$P_X(x) = \int_{-\infty}^{\infty} P(x, y) dy$$

- If X and Y are dependent, and we learn the value of Y , then in general this will change our probability density for X (and vice versa). The probability density for X given that we know that $Y = y$, is written $P(x | y)$ and is referred to as the conditional probability density for X given Y .

DEPENDENT RANDOM VARIABLES

- To see how to calculate this conditional probability, we note first that $P(x, y)$ with $y = a$ gives a relative probability for different values of x given that $Y = a$.
- To obtain the conditional probability density for X given that $Y = a$, all we have to do is divide $P(x, a)$ by its integral over all values of x . This ensures that the integral of the conditional probability is unity

$$P(x | y) = \frac{P(x, y)}{\int_{-\infty}^{\infty} P(x, y) dx}$$

- If we substitute

$$P_Y(y) = \int_{-\infty}^{\infty} P(x, y) dx$$

into this equation for the conditional probability we have

$$P(x | y) = \frac{P(x, y)}{P_Y(y)}$$

- Further than this, we also see

$$P(x, y) = P(x | y)P_Y(y)$$

- Generally when two random variables are dependent $\langle XY \rangle \neq \langle X \rangle \langle Y \rangle$

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CORRELATIONS AND CORRELATION COEFFICIENTS

- The expectation value of the product of two random variables is called the correlation of the two variables.
- Item the correlation is a measure of how correlated two variables are.
- For a measure of how mutually dependent two variables are we divide the correlation by the square root of the product of the variances

$$C_{XY} \equiv \frac{\langle XY \rangle}{\sqrt{V(X)V(Y)}}$$

where C_{XY} is called the correlation coefficient of X and Y .

- If the means of X and Y are not zero, we can remove these when calculating the correlation coefficient and preserve its properties, we can find in general the correlation coefficient as

$$C_{XY} \equiv \frac{\langle (X - \langle X \rangle)(Y - \langle Y \rangle) \rangle}{\sqrt{V(X)V(Y)}} = \frac{\langle XY \rangle - \langle X \rangle \langle Y \rangle}{\sqrt{V(X)V(Y)}}$$

CORRELATIONS AND CORRELATION COEFFICIENTS

- The quantity $\langle XY \rangle - \langle X \rangle \langle Y \rangle$ is called the covariance of X and Y and is zero if X and Y are independent.
- The correlation coefficient is zero if X and Y are independent.
- The correlation coefficient is unity if $X = cY$ (c being some positive constant).
- If $X = -cY$, then the correlation coefficient is -1 , and we say that the two variables are perfectly anti-correlated.
- The correlation coefficient provides a rough measure of the mutual dependence of two random variables, and is one that is relatively easy to calculate.

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ADDING RANDOM VARIABLES TOGETHER

- The probability density for $Z = X + Y$ is given by

$$P_Z(z) = \int_{-\infty}^{\infty} P_X(s - z)P_Y(s)ds \equiv P_X * P_Y$$

which is called the convolution of P_X and P_Y , and is denoted by another function “*”.

- The mean and the variance are defined as follows, for $X = X_1 + X_2$

$$\begin{aligned}\langle X \rangle &= \langle X_1 \rangle + \langle X_2 \rangle \\ V_X &= V_1 + V_2\end{aligned}$$

where the two events are independent.

- The notion that averaging the results of a number of independent measurements producing a more accurate results is an important one here. If we sum the averages of a number of experiments, N , the mean will not change, however, because we are dividing each of the variable by N , the variance goes down by $1/N^2$.
- Because it is the variances that add together, the variance of the sum is V/N . Thus the variance gets smaller as we add more results together.
- The uncertainty of the results is the standard deviation, and the standard deviation of the average is σ/\sqrt{N}

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TRANSFORMATION OF A RANDOM VARIABLE

- If we know the probability density for a random variable X , then it can be useful to know how to calculate the probability density for some random variable Y , that is a function of X . This is referred to as a transformation of a random variable.
- Consider the case where $Y = aX + b$ for constants a and b .
 - ① The probability density will be stretched by a factor a .
 - ② The probability density will be shifted a distance of b .

TRANSFORMATION OF A RANDOM VARIABLE

- More generally, if $Y = g(X)$, then we determine the probability density for Y by changing the variables as shown below.
- We begin by writing the expectation value of a function Y , $f(Y)$, in terms of $P(x)$.

$$\langle f(Y) \rangle = \int_{x=a}^{x=b} P(x) f(g(x)) dx$$

where a and b are the upper and lower limits on the values X can take.

- Now we transform this into an integral over the values of Y

$$\begin{aligned} \langle f(Y) \rangle &= \int_{y=g(a)}^{y=g(b)} P(g^{-1}(y)) \left(\frac{dx}{dy} \right) f(y) dy \\ &= \int_{y=g(a)}^{y=g(b)} \frac{P(g^{-1}(y))}{g'(g^{-1}(y))} f(y) dy \end{aligned}$$

TRANSFORMATION OF A RANDOM VARIABLE

- We now identify the function that multiplies $f(y)$ inside the integral over y as the probability density.
- The probability density for y is therefore

$$Q(y) = \frac{P(g^{-1}(y))}{|g'(g^{-1}(y))|}$$

- One must realise that this expression for $Q(y)$ only works for functions that map a single value of x to a single value of y (invertable functions), because in the change of variables we assumed that g was invertable.

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THE DISTRIBUTION FUNCTION

- The probability distribution function, which we call $D(x)$, of a random variable X is defined as the probability that X is less than or equal to x

$$D(x) = \text{Prob}(X \leq x) = \int_{-\infty}^x P(z) dz$$

- In addition, the fundamental theorem of calculus tells us that

$$P(x) = \frac{dD(x)}{dx}$$

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THE CHARACTERISTIC FUNCTION

- Another useful definition is that of the characteristic function, $\chi(s)$.
- The function is defined as the fourier transform of the probability density.
- The Fourier transform of a function $P(x)$ is another function given by

$$\chi(s) = \int_{-\infty}^{\infty} P(x)e^{isx} dx$$

- One use of the Fourier transform is that it has a simple inverse, allowing one to perform a transformation on $\chi(s)$ to get back $P(x)$. This inverse transform is

$$P(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \chi(s)e^{-isx} ds$$

- If we have two functions $F(x)$ and $G(x)$, then the fourier transform of their convolution is simple the product of their respective fourier transforms.
- We now have an alternative way to find the probability density of the sum of two random variables:

- ① Convolve their two densities.
- ② Calculate the characteristic functions for each, multiply these together, and then take the inverse Fourier transform.

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THE MULTIVARIATE GAUSSIAN

- It is possible to have a probability density for N variables, in which the marginal densities for each of the variables are all Gaussian, and where all the variables may be correlated.
- Defining a column vector of N random variables, $\mathbf{x} = (x_1, x_2, \dots, x_N)^T$, the general form of the multivariate Gaussian is

$$P(\mathbf{x}) = \frac{1}{\sqrt{(2\pi)^N \det[\Gamma]}} \exp\left[-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \Gamma^{-1}(\mathbf{x} - \boldsymbol{\mu})\right]$$

where $\boldsymbol{\mu}$ is the vector of the means of the random variables, and Γ is the matrix of covariances of the variables,

$$\Gamma = \langle \mathbf{X}\mathbf{X}^T \rangle - \langle \mathbf{X} \rangle \langle \mathbf{X} \rangle^T = \langle \mathbf{X}\mathbf{X}^T \rangle - \boldsymbol{\mu}\boldsymbol{\mu}^T$$

- Note that the diagonal elements of Γ are the variances of the individual variables.