### OPERATING SYSTEMS Lecture #9: Concurrent Processes

Written by David Goodwin based on the lecture series of Dr. Dayou Li and the book *Understanding Operating Systems* 4<sup>th</sup> ed. by *I.M.Flynn and A.McIver McHoes* (2006)

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Outline

#### Lecture #9 Concurrent Processes

- David Goodwin University of Bedfordshire
- Introduction
- Configurations
- Programming
- Threads





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#### Introduction

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## INTRODUCTION



### What is parallel processing?

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### Parallel processing (also called multiprocessing)

- situation in which two or more procesors operate in unison
- i.e. two or more CPUs are executing instructions simultaneously
- each CPU can have a RUNNING process at the same time
- Process manager must coordinate each processor
  - Process manager must synchronise the interaction among CPUs
- enhance throughput and increase computing power

### What is parallel processing?

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### • Example: Information Retrieval System

- Processor 1
  - accepts a query
  - checks for errors
  - passes request to Processor 2
- Processor 2
  - searches database for required information
- Processor 3
  - retrieves data from database (if kept off-line in secondary storage)
  - data placed where Processor 2 can get it
- Processor 2
  - passes information to Processor 4
- Processor 4
  - routes the response back to the originator of the request

### **Benefits**

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### Increased reliability

- more than one CPU
  - if one fails, others can absorb the load
    - failing processor must inform other processors
    - OS must re-structure its resource allocation strategies
- faster processing
  - instructions processed two or more at a time
    - allocate CPU to each job
    - allocate CPU to each working set
    - subdivide individual instructions, called concurrent programming
- Challenges:
  - How to connect the processors in configurations?
  - How to orchestrate their interaction?



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## CONFIGURATIONS



### Master/Slave configuration

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Master/Slave configuration is asymmetric

• Essentially a single processor with additional "slaves"

- Master processor responsible for managing entire system
  - maintains status of processes, storage management, schedules work for slave processors, executes all control programs.
- suited for environments with front-end interactive users, and back-end batch job mode





### Master/Slave configuration

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- Advantage:
  - Simplicity
- Disadvantage:
  - Reliability no higher than for single processor (if master fails the whole system fails)
  - Poor use of resources (if matser is busy, slave must wait until master becomes free until it can be assigned more work)
    - Increases the number of interrupts (slaves must interrupt the master every time they need OS intervention e.g. IO requests), creating long queues at the master processor

### Loosely Coupled configuration

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Loosely Coupled system features several complete computing systems

- each has its own memory, IO devices, CPU, and OS
- each processor controls its own resources
- each processor can communicate and cooperate with others
  - job assigned to one processor, and will remain there until finished
  - job scheduling based on several requiremenyts and policies (new jobs may be assigned to the processor with lightest load)



### Loosely Coupled configuration

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Advantage:

- Isn't prone to catastrophic system failures (when a processor fails, others can continue work independently)
- Disadvantage:
  - · Difficult to detect when a processor has failed

### Symmetric configuration

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• Symmetric configuration best implimented if processors are the same type

- Processor scheduling is decentralised
- Single copy of OS and a globqal table listing each process and its status (stored in a common area of memory)
- Each processor uses the same scheduling algorithm
- If interrupted, processor updates process list and finds another to run (processors are kept busy)
- Any given job can be executed on several processors
- Presents a need for process synchronisation





### Symmetric configuration

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### Advantage:

Reliable

• Uses resources effectively

- Balance loads well
- Can degrade gracefully in the event of a failure
- Disadvantage:
  - Processors must be well synchronised to avoid problems of races and deadlocks



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## PROGRAMMING



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 Multiprocessing can refer to one job using several processors
This requires a programming language and computer system that can support it, called concurrent processing system

 Most programming languages are serial - instructions executed one at a time

> To resolve and arithmetic expression, every operation is done in sequence

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### • Example:

• 
$$A = 3 * B * C + 4/(D + E) * *(F - G)$$

| step | Operation         | Result                    |  |
|------|-------------------|---------------------------|--|
| 1    | (F-G)             | Store difference in $T_1$ |  |
| 2    | (D+E)             | Store sum in $T_2$        |  |
| 3    | $(T_1) * * (T_2)$ | Store power in $T_1$      |  |
| 4    | $4/(T_1)$         | Store quotient in $T_2$   |  |
| 5    | 3 * B             | Store product in $T_1$    |  |
| 6    | $(T_1) * C$       | Store product in $T_1$    |  |
| 7    | $(T_1) + (T_2)$   | Store sum in $A$          |  |
| (11) |                   |                           |  |

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• Arithmetic expressions can be processed differently if we use a language that allows concurrent processing

• Define COBEGIN and COEND to indicate to the compiler which instructions can be processed concurrently

| • COBEGIN<br>T1 = 3 * B      | step | proc. | Operation         | Result                    |
|------------------------------|------|-------|-------------------|---------------------------|
| T2 = D + E                   | 1    | 1     | 3 * B             | Store difference in $T_1$ |
| T3 = F - G                   |      | 2     | (D+E)             | Store sum in $T_2$        |
| COEND                        |      | 3     | (F-G)             | Store difference in $T_3$ |
|                              | 2    | 1     | $(T_1) * C$       | Store product in $T_4$    |
| $T_{4} = T_{1} + C$          |      | 2     | $(T_2) * * (T_3)$ | Store power in $T_5$      |
| 14 = 11 * C<br>T5 = T2 * *T3 | 3    | 1     | $4/(T_5)$         | Store quotient in $T_1$   |
| COEND                        | 4    | 1     | $(T_4) + (T_1)$   | Store sum in A            |
| • $A = T4 + 4/T5$            |      |       |                   |                           |
|                              |      |       | 333               |                           |
|                              |      |       |                   |                           |

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### Increased computational speed

- increased complexity of programming language
- increased complexity of hardware (machinary and communication among machines)
- programmer must explicitly state which instructions are to be executed in parallel, called **explicit parallelism** 
  - solution: automatic detection by the compiler of instructions that can be performed in parallel, called implicit parallelism

## Case 1: Array Operations

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• To perform an array operation within a loop in three steps, the instruction might say:

• for(j=1;j<=3;j++) a(j)=b(j)+c(j);

 If we use three processors, the instruction can be performed in a single step:

 processor#1 performs: a(1)=b(1)+c(1) processor#2 performs: a(2)=b(2)+c(2) processor#3 performs: a(3)=b(3)+c(3)

### Case 2: Matrix Multiplication

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- To perform C = A \* B where A and B represent two matricies:
  - $A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$ ,  $B = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$ 
    - Several elements of a row of A are multiplied by the corresponding elements of the column in B.
- Serially, the answer can be computed in 45 steps (5 imes9)
- With three processors the answer takes only 27 steps, multiplying in parallel  $(3 \times 9)$



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### **Threads & Concurrent Programming**

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- We have considered cooperation and synchronisation of traditional processes (known as heavyweight processes):
  - require space in main memory where they reside during execution
  - may require other resources such as data files or IO devices
  - pass through several states: ready, running, waiting, delayed, blocked
- this requires an overhead from swapping between main memory and secondary storage

• To minimise overhead time, impliment the use of threads

• defined as a smaller unit within a process, that can be scheduled and executed (uses CPU)

 each has its own processor registers, program counter, stack and staus, but shares the data area and resources allocated to its process

### **Threads States**

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• The same operations are performed on both traditional processes and threads.

- The OS must be able to support:
  - Creating new threads
  - Setting up a thread so it is ready to execute
  - Delaying, or putting to sleep, threads for a specific amount of time
  - Blocking, or suspending, threads that are waiting for IO to complete
  - Setting threads to wait state until specific event
  - Scheduling threads for execution
  - Synchronising thread execution using semaphores, events, or conditional variables
  - Terminating a thread and releasing its resources

• This is done by the OS tracking critical information for each thread

### **Thread Control Block**

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- Just as processes are represented by Process Contol Blocks (PCBs), threads are represented by **Thread Contol Blocks (TCBs)**:
  - Thread ID: unique identifier assigned by OS
  - Thread State: changes as the thread progresses though execution
  - CPU information: how far the thread has executed, which instruction is being performed, what data is begin used
  - Thread Priority: used by Thread Scheduler to determine which thread should be selected for the ready queue
  - Pointer: to the process that created the thread
  - Pointers: to other threads created by this thread