

Averaging Results

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WHEPPXI
Workshop on High Energy Physics Phenomenology

January 2010

Heavy Flavor Averaging Group

- Current chairs:
 - Alan Schwartz (Belle), Gianluca Cavoto (BaBar)
- HFAG operates as a set of quasi-autonomous subgroups:
 - Oscillations & lifetimes (Olivier Schneider)
 - Semileptonic (Christoph Schwanda)
 - Rare decays (Paoti Chang)
 - Unitarity Triangle (Tim Gershon)
 - B to Charm (Simon Blyth)
 - Charm (Alan Schwartz & Jon Coleman)
 - Tau (Swagato Banerjee)

Heavy Flavor Averaging Group

- History:
 - evolved from LEP B physics averaging group
 - **founded at first CKM workshop (CERN 2002)**
 - initial chairs:
 - David Kirkby (BaBar) & Yoshi Sakai (Belle) (2002-2005?)
 - succeeded by Soeren Prell (BaBar) & Simon Eidelman (Belle) (2006-2007?)
 - initially four subgroups; additional groups added according to demand
 - **manpower within subgroups evolves at a rate that differs significantly between subgroups**

Heavy Flavor Averaging Group

- Webpage:

<http://www.slac.stanford.edu/xorg/hfag/>

- Documentation:

- preprints updated irregularly

- end of 2007 update [arXiv:0808.1297 \[hep-ex\]](#)
- end of 2006 update [arXiv:0704.3575 \[hep-ex\]](#)
- end of 2005 update [hep-ex/0603003](#)
- winter 2005 update [hep-ex/0505100](#)
- summer 2004 update [hep-ex/0412073](#)

- end of 2009 update in preparation

Heavy Flavor Averaging Group

- Relations with other groups
 - PDG
 - Some HFAG members are also PDG members/contributors
 - HFAG provides some averages for PDG (at their request)
 - Experiments (BaBar, Belle, CDF, D0, LEP, CLEO, BES ...)
 - Subgroups contain representatives of relevant experiments
 - Close relations (heritage of LEP B physics WG)
 - CKMfitter & UTfit
 - Some HFAG members are CKMfitter/UTfit members
 - Aim for strict independence (but friendly relations)
 - Theorists
 - Discussions warmly encouraged
 - Care to avoid bias possible due to preferences for particular theoretical models

HFAG: Unitarity Triangle Parameters

• Mission

- Provide world averages for measurements **related to the angles of the Unitarity Triangle**. In particular, we provide world averages of measurements of **time-dependent CP violation**, and related parameters. We also prepare averages of time-independent measurements that have a clean relation to the UT angles (especially in the $B \rightarrow DK$ system).
- Identify common experimental and theoretical uncertainties and treat them coherently in the averages. Rescale the measurements if updated input parameters are available.
- In cases where effective UT angles are measured no attempts are made to derive the fundamental quantities, if this requires input from QCD calculations.
- If straightforward, an interpretation of the results is given.

• Members

Contact Persons	Experiment
Tim Gershon (*)	BABAR and LHCb
Gianluca Cavoto	BABAR
Owen Long	BABAR
Achille Stocchi	BABAR
Yoshi Sakai	Belle
Karim Trabelsi	Belle
Diego Tonelli	CDF
Hal Evans	D0
David Asner	CLEOc

HFAG: Unitarity Triangle Parameters

Φ_s ($B_s \rightarrow J/\psi\phi$) handled by **HFAG lifetimes & oscillations**
(actually handled directly by CDF & D0 at present)

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HFAG: Unitarity Triangle Parameters

- Averaging procedure
 - For measurements with Gaussian uncertainties
 - _ perform simultaneous average of all physics parameters that are determined in the fits taking (linear) correlations into account (NB. different to PDG)
 - _ encourage experiments to use parameters that have Gaussian uncertainties, and to report all physics parameters and correlations
 - For measurements with non-Gaussian uncertainties (ie. asymmetric errors)
 - _ perform uncorrelated averages using the PDG prescription
 - Correlations between measurements from different experiments are handled
 - _ can arise due to dependence on external nuisance parameters
 - _ rescaling of external parameters can be handled
 - If measurements do not agree, we discuss with the experiments and try to find the cause
 - _ we do NOT inflate the uncertainties (NB. the PDG does)

HFAG: Unitarity Triangle Parameters

- Averaging procedure

- Standard minimum χ^2 procedure

- i independent measurements of parameter x

- Values x_i and uncertainties σ_i

$$\sum_i (x_i - \bar{x})^2 / \sigma_i^2$$

- Generalisation to i sets of measurements of correlated parameters

- x_i is now a vector, C_i the covariance matrix ($\sigma_{ia} = \sqrt{(C_{i,aa})}$)

$$\sum_i (x_i - \bar{x})_a^T (C_i^{-1})_{ab} (x_i - \bar{x})_b$$

- Solved analytically

HFAG: Unitarity Triangle Parameters

- “The PDG prescription:”
 - See section 5.2 of the PDG RPP

When experimenters quote asymmetric errors $(\delta x)^+$ and $(\delta x)^-$ for a measurement x , the error that we use for that measurement in making an average or a fit with other measurements is a continuous function of these three quantities. When the resultant average or fit \bar{x} is less than $x - (\delta x)^-$, we use $(\delta x)^-$; when it is greater than $x + (\delta x)^+$, we use $(\delta x)^+$. In between, the error we use is a linear function of x . Since the errors we use are functions of the result, we iterate to get the final result. Asymmetric output errors are determined from the input errors assuming a linear relation between the input and output quantities.

HFAG: Unitarity Triangle Parameters

- Inclusion of results
 - We include all published and many preliminary results (NB. different to PDG)
 - We strongly encourage written documentation to accompany preliminary results
 - preferably collaboration authored (ie. not proceedings)
 - preferably available on arXiv (not hidden on web-pages)
 - We exclude preliminary results which remain unpublished for a long time (> 2 years) and/or for which no publication is planned

Example: $B^0 \rightarrow \pi^+ \pi^-$

- Statistically dominated
 - No need to worry about correlations of systematic uncertainties

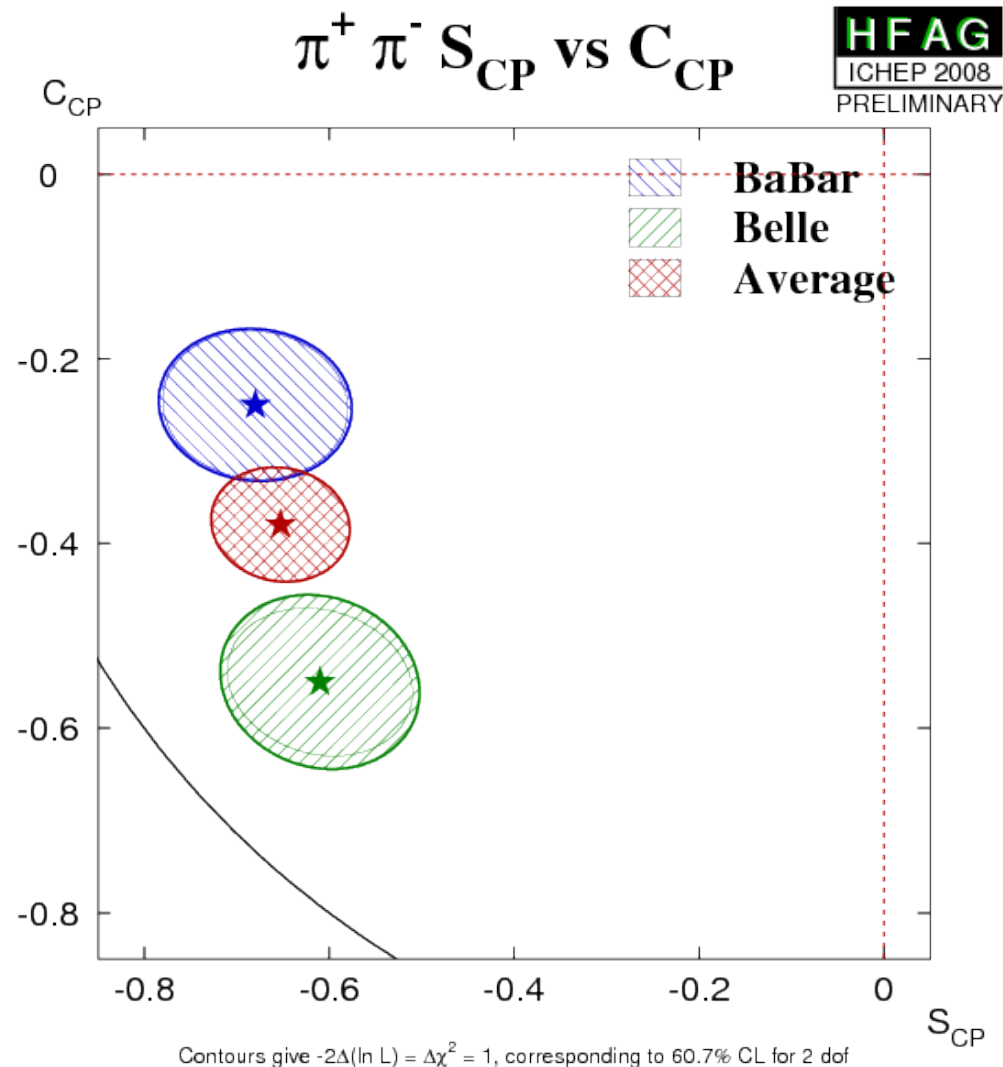
Experiment	$S_{CP}(\pi^+\pi^-)$	$C_{CP}(\pi^+\pi^-)$	Correlation	Reference
BaBar N(BB)=467M	$-0.68 \pm 0.10 \pm 0.03$	$-0.25 \pm 0.08 \pm 0.02$	-0.06 (stat)	arXiv:0807.4226
Belle N(BB)=535M	$-0.61 \pm 0.10 \pm 0.04$	$-0.55 \pm 0.08 \pm 0.05$	-0.15 (stat)	PRL 98 (2007) 211801
Average	-0.65 ± 0.07	-0.38 ± 0.06	-0.08	HFAG correlated average $\chi^2 = 5.8/2$ dof (CL=0.055 \Rightarrow 1.9 σ)

Figure	Figure	Figure
<p>$\pi^+ \pi^- S_{CP}$</p> <p>eps.gz png</p>	<p>$\pi^+ \pi^- C_{CP}$</p> <p>eps.gz png</p>	<p>S_{CP} vs C_{CP}</p> <p>eps.gz png</p>

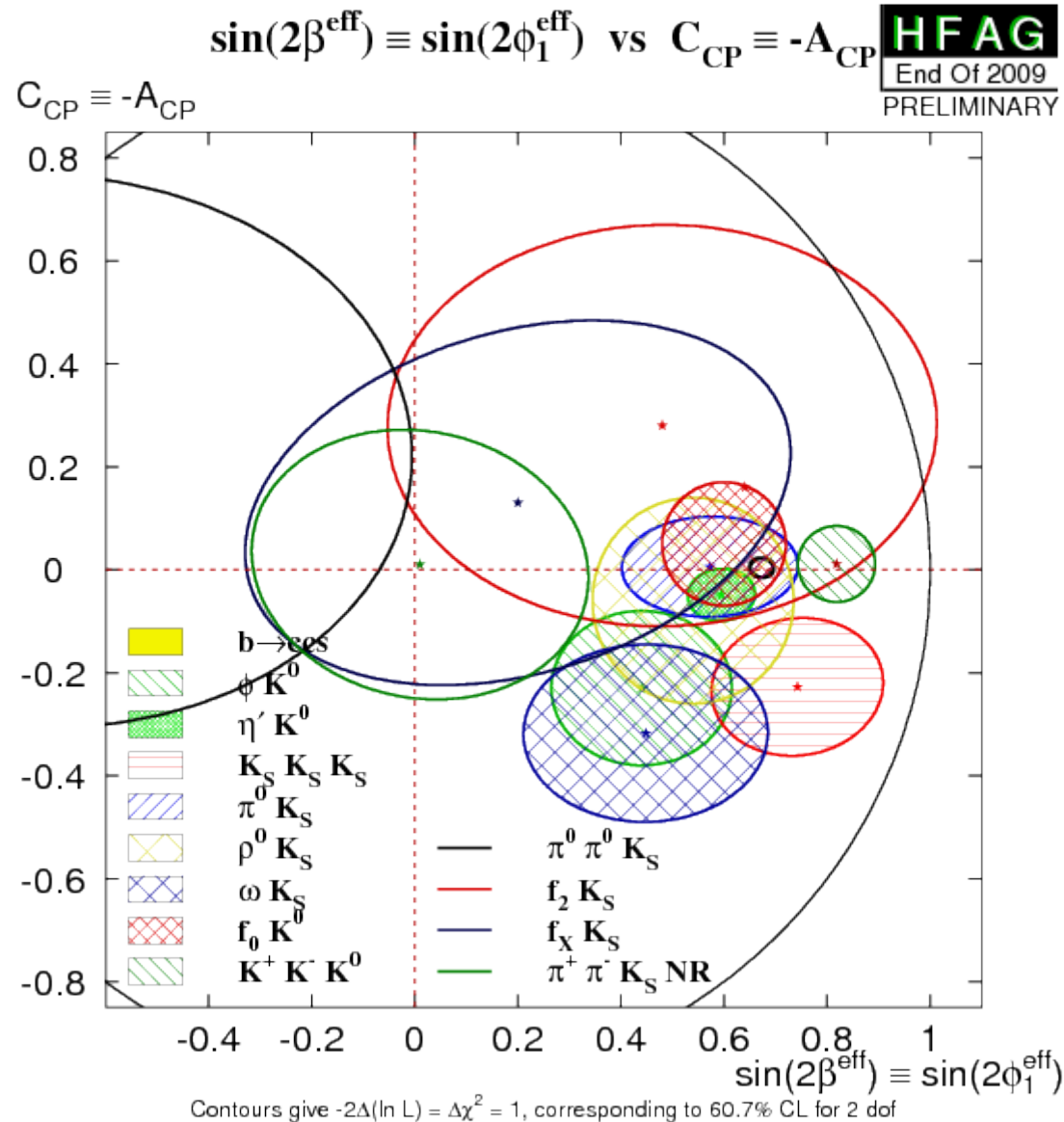
Figures:

Example: $B^0 \rightarrow \pi^+ \pi^-$

- Recall: we do NOT inflate uncertainties



Example: $b \rightarrow qqs$ penguins

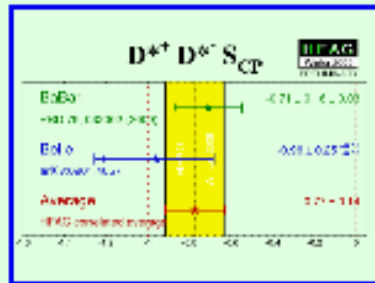


Example: $B^0 \rightarrow D^{*+} D^{*-}$

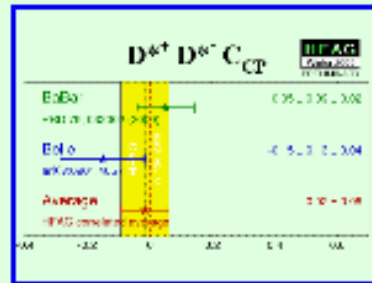
- Correlations with additional non-CP parameters

Experiment	$S_{CP} (D^{*+} D^{*-})$	$C_{CP} (D^{*+} D^{*-})$	$R_{\perp} (D^{*+} D^{*-})$	Correlation	Reference
BaBar N(BB)=467M	$-0.71 \pm 0.16 \pm 0.03$	$0.05 \pm 0.09 \pm 0.02$	0.17 ± 0.03	(stat)	PRD 79, 032002 (2009)
Belle N(BB)=657M	$-0.96 \pm 0.25^{+0.12}_{-0.16}$	$-0.15 \pm 0.13 \pm 0.04$	$0.12 \pm 0.04 \pm 0.02$	(stat)	arXiv:0901.4057
Average	-0.77 ± 0.14	-0.02 ± 0.08	0.16 ± 0.02	(stat)	HFAG correlated average $\chi^2 = 2.9/3$ dof (CL=0.41 \Rightarrow 0.8 σ)

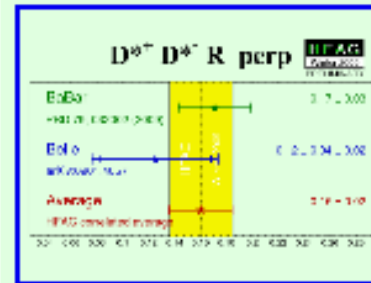
Figures:



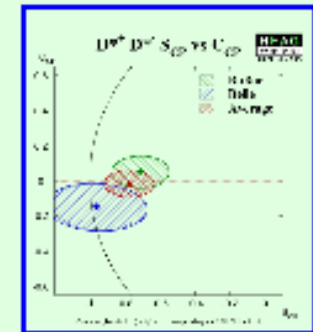
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Example: $B^0 \rightarrow J/\psi K_S$

- Systematic correlations (external nuisance parameters) taken into account

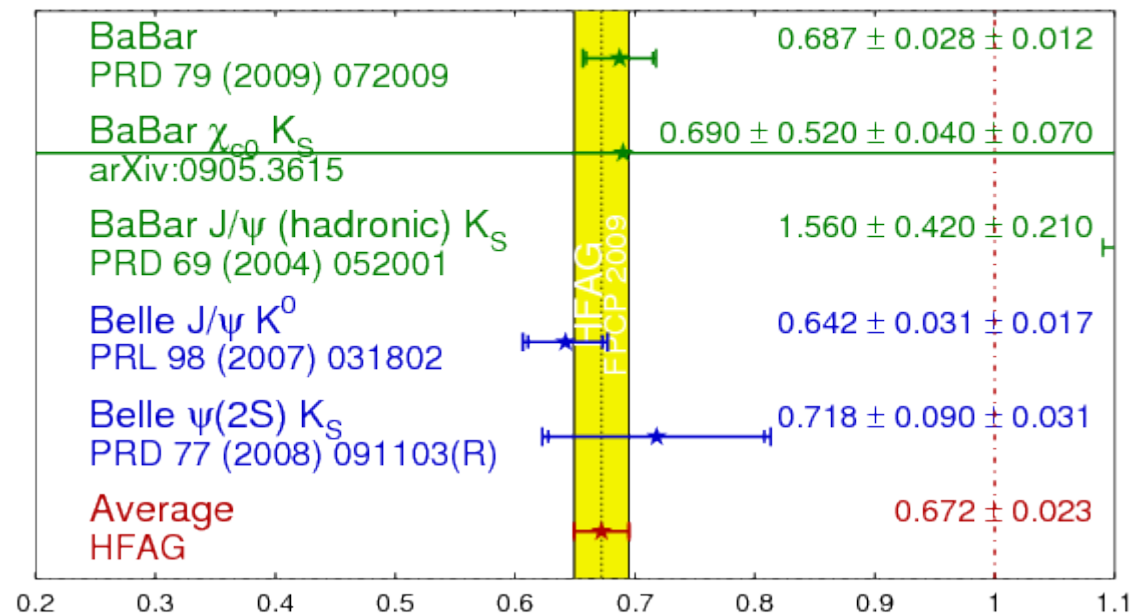
Parameter: $\sin(2\beta) \equiv \sin(2\phi_1)$				
Mode	BaBar	Belle	Average	Reference
Charmonium:	N(BB)=465M	N(BB)=535M		
$J/\psi K_S$ ($\eta_{CP}=-1$)	$0.657 \pm 0.036 \pm 0.012$	$0.643 \pm 0.038_{\text{stat}}$	-	BaBar (PRD 79 (2009) 072009) Belle (PRL 98 (2007) 031802)
$J/\psi K_L$ ($\eta_{CP}=+1$)	$0.694 \pm 0.061 \pm 0.031$	$0.641 \pm 0.057_{\text{stat}}$		
$J/\psi K^0$	$0.666 \pm 0.031 \pm 0.013$	$0.642 \pm 0.031 \pm 0.017$	0.655 ± 0.0244 (0.022 _{stat-only})	CL = 0.62
$\psi(2S)K_S$ ($\eta_{CP}=-1$)	$0.897 \pm 0.100 \pm 0.036$	$0.718 \pm 0.090 \pm 0.031$ N(BB)=657M	0.798 ± 0.071 (0.067 _{stat-only})	BaBar (PRD 79 (2009) 072009) Belle (PRD77 (2008) 091103(R))
$\chi_{c1}K_S$ ($\eta_{CP}=-1$)	$0.614 \pm 0.160 \pm 0.040$	-		
$\eta_c K_S$ ($\eta_{CP}=-1$)	$0.925 \pm 0.160 \pm 0.057$	-	-	BaBar (PRD 79 (2009) 072009)
$J/\psi K^{*0}$ ($K^{*0} \rightarrow K_S \pi^0$) ($\eta_{CP}=1-2 A_{\perp} ^2$)	$0.601 \pm 0.239 \pm 0.087$	-		
All charmonium	$0.687 \pm 0.028 \pm 0.012$	$0.650 \pm 0.029 \pm 0.018$	0.670 ± 0.023 (0.020 _{stat-only})	CL = 0.52
$\chi_{c0}K_S$ ($\eta_{CP}=+1$)	$0.69 \pm 0.52 \pm 0.04 \pm 0.07$ (*) N(BB)=383M	-	-	BaBar (PRD 80 (2009) 112001)
$J/\psi K_S, J/\psi \rightarrow \text{hadrons}$ ($\eta_{CP}=+1$)	$1.56 \pm 0.42 \pm 0.21$ (**) N(BB)=88M	-	-	BaBar (PRD 69 (2004) 052001)
All charmonium (incl. $\chi_{c0}K_S$ etc.)	0.691 ± 0.031 (0.028 _{stat-only})	$0.650 \pm 0.029 \pm 0.018$	0.672 ± 0.023 (0.020 _{stat-only})	CL = 0.30

Example: $B^0 \rightarrow J/\psi K_S$

- Systematic correlations (external nuisance parameters) taken into account

$$\sin(2\beta) \equiv \sin(2\phi_1)$$

HFAG
FPCP 2009
PRELIMINARY



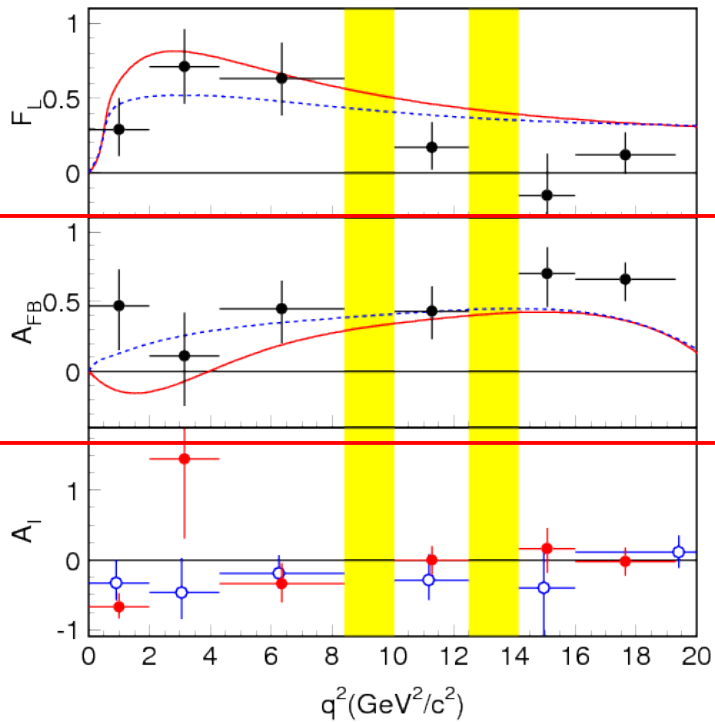
When Averages Get Difficult

- Experiments measure different parameters
- Badly behaved parameters, eg. due to
 - low statistics
 - choice of parametrisation
 - NB. “good” choice of parameters from a physics perspective may be a statistically “bad” choice
 - “badly behaved” could mean
 - Non-Gaussian (including non-linear correlations)
 - Dependence of uncertainty of one parameter on central value of another
- Complicated dependence on external nuisance parameters

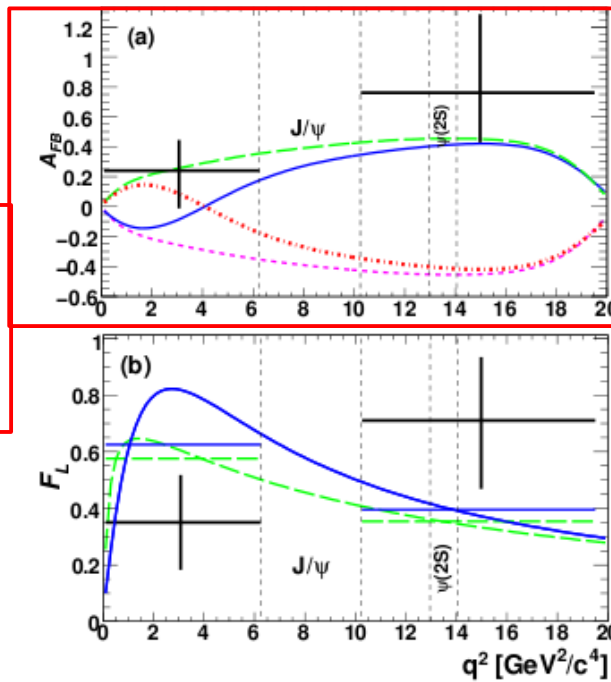
Example: A_{FB} ($B \rightarrow K^*II$) distributions

Experiments are using different binnings – cannot be combined

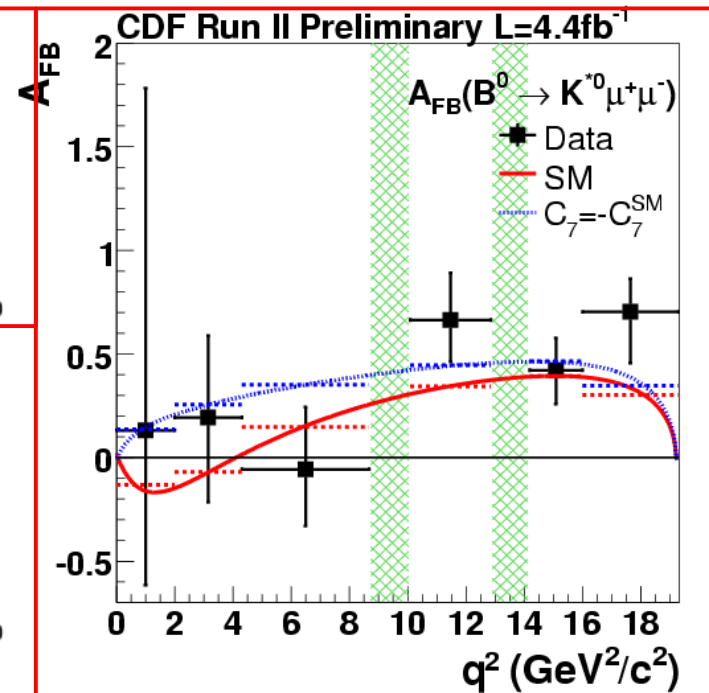
Belle PRL 103 (2009) 171801



BABAR PRD 79 (2009) 031102(R)



CDF note 09-11-12



Example: $B_s \rightarrow J/\psi\phi$

Differential decay rate:

$$\frac{d^4\Gamma(B_s^0 \rightarrow J/\psi\phi)}{dt d\cos\theta d\varphi d\cos\psi} \equiv \frac{d^4\Gamma}{dt d\Omega} \propto \sum_{k=1}^6 h_k(t) f_k(\Omega)$$

B_s

\bar{B}_s

k	$h_k(t)$	$\bar{h}_k(t)$	$f_k(\theta, \psi, \varphi)$
1	$ A_0(t) ^2$	$ \bar{A}_0(t) ^2$	$2\cos^2\psi(1 - \sin^2\theta\cos^2\varphi)$
2	$ A_{\parallel}(t) ^2$	$ \bar{A}_{\parallel}(t) ^2$	$\sin^2\psi(1 - \sin^2\theta\sin^2\varphi)$
3	$ A_{\perp}(t) ^2$	$ \bar{A}_{\perp}(t) ^2$	$\sin^2\psi\sin^2\theta$
4	$\Im\{A_{\parallel}^*(t)A_{\perp}(t)\}$	$\Im\{\bar{A}_{\parallel}^*(t)\bar{A}_{\perp}(t)\}$	$-\sin^2\psi\sin 2\theta\sin\varphi$
5	$\Re\{A_0^*(t)A_{\parallel}(t)\}$	$\Re\{\bar{A}_0^*(t)\bar{A}_{\parallel}(t)\}$	$\frac{1}{\sqrt{2}}\sin 2\psi\sin^2\theta\sin 2\varphi$
6	$\Im\{A_0^*(t)A_{\perp}(t)\}$	$\Im\{\bar{A}_0^*(t)\bar{A}_{\perp}(t)\}$	$\frac{1}{\sqrt{2}}\sin 2\psi\sin 2\theta\cos\varphi$

$A_0(0) \rightarrow$ CP even
 $A_{\parallel}(0) \rightarrow$ CP even
 $A_{\perp}(0) \rightarrow$ CP odd

\pm signs differ for B_s and \bar{B}_s

$$|\bar{A}_0(t)|^2 = |\bar{A}_0(0)|^2 e^{-\Gamma_s t} \left[\cosh\left(\frac{\Delta\Gamma_s t}{2}\right) - \cos\Phi \sinh\left(\frac{\Delta\Gamma_s t}{2}\right) - \sin\Phi \sin(\Delta m_s t) \right],$$

$$|\bar{A}_{\parallel}(t)|^2 = |\bar{A}_{\parallel}(0)|^2 e^{-\Gamma_s t} \left[\cosh\left(\frac{\Delta\Gamma_s t}{2}\right) - \cos\Phi \sinh\left(\frac{\Delta\Gamma_s t}{2}\right) - \sin\Phi \sin(\Delta m_s t) \right],$$

$$|\bar{A}_{\perp}(t)|^2 = |\bar{A}_{\perp}(0)|^2 e^{-\Gamma_s t} \left[\cosh\left(\frac{\Delta\Gamma_s t}{2}\right) + \cos\Phi \sinh\left(\frac{\Delta\Gamma_s t}{2}\right) + \sin\Phi \sin(\Delta m_s t) \right],$$

$$\Im\{\bar{A}_{\parallel}^*(t)\bar{A}_{\perp}(t)\} = |\bar{A}_{\parallel}(0)||\bar{A}_{\perp}(0)| e^{-\Gamma_s t} \left[-\cos(\delta_{\perp} - \delta_{\parallel}) \sin\Phi \sinh\left(\frac{\Delta\Gamma_s t}{2}\right) - \sin(\delta_{\perp} - \delta_{\parallel}) \cos(\Delta m_s t) + \cos(\delta_{\perp} - \delta_{\parallel}) \cos\Phi \sin(\Delta m_s t) \right],$$

$$\Re\{\bar{A}_0^*(t)\bar{A}_{\parallel}(t)\} = |\bar{A}_0(0)||\bar{A}_{\parallel}(0)| e^{-\Gamma_s t} \cos\delta_{\parallel} \left[\cosh\left(\frac{\Delta\Gamma_s t}{2}\right) - \cos\Phi \sinh\left(\frac{\Delta\Gamma_s t}{2}\right) - \sin\Phi \sin(\Delta m_s t) \right] \text{ and}$$

$$\Im\{\bar{A}_0^*(t)\bar{A}_{\perp}(t)\} = |\bar{A}_0(0)||\bar{A}_{\perp}(0)| e^{-\Gamma_s t} \left[-\cos\delta_{\perp} \sin\Phi \sinh\left(\frac{\Delta\Gamma_s t}{2}\right) - \sin\delta_{\perp} \cos(\Delta m_s t) + \cos\delta_{\perp} \cos\Phi \sin(\Delta m_s t) \right].$$

Example: $B_s \rightarrow J/\psi\phi$

- Very complicated expression
- Assumes no direct CP violation (full expression even more complicated!)
- Dependence of physical observables on φ_s goes as

- $\cos(\varphi_s) \sinh(\Delta\Gamma_s t/2)$
- $\sin(\varphi_s) \sin(\Delta m_s t)$

\pm signs differ for B_s and \bar{B}_s

- and similar expressions in interference terms with further dependence on strong phase differences

- Fit performed with free (physics) parameters

$$\varphi_s, \Delta\Gamma_s, R_{\perp}, R_{\parallel}, \delta_{\perp}, \delta_{\parallel} (\tau_s, \Delta m_s)$$

- **Non-Gaussian effects not surprising (unavoidable?)**

$\Phi_s (B_s \rightarrow J/\psi\phi)$

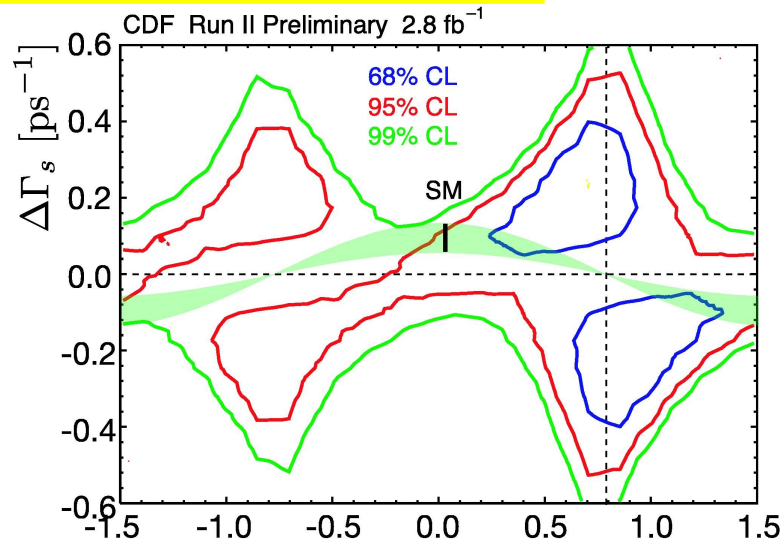
G.Punzi at EPS 2009

Tevatron measurements using tagged $B_s \rightarrow J/\psi\phi$

Angular analyses of vector-vector final state

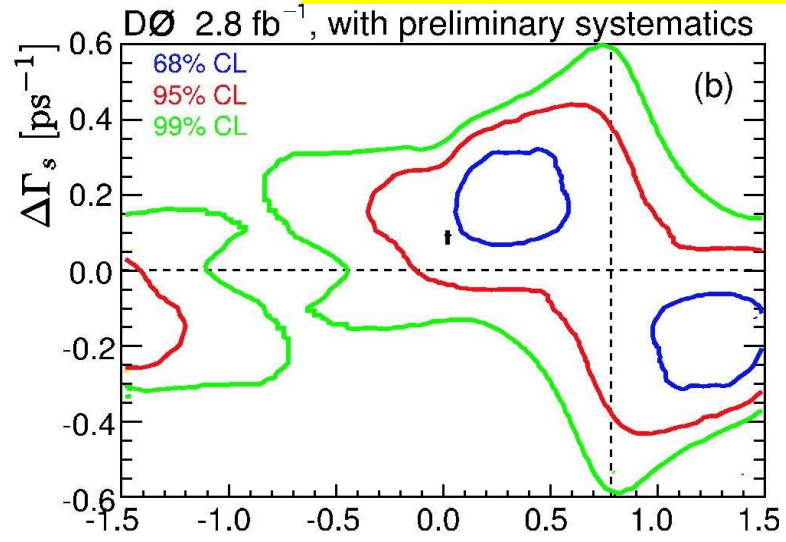
Results depend on $\Delta\Gamma$

CDF note 9787



$3166 \pm 56 B_s \rightarrow J/\psi\phi$ events

D0 5928-CONF

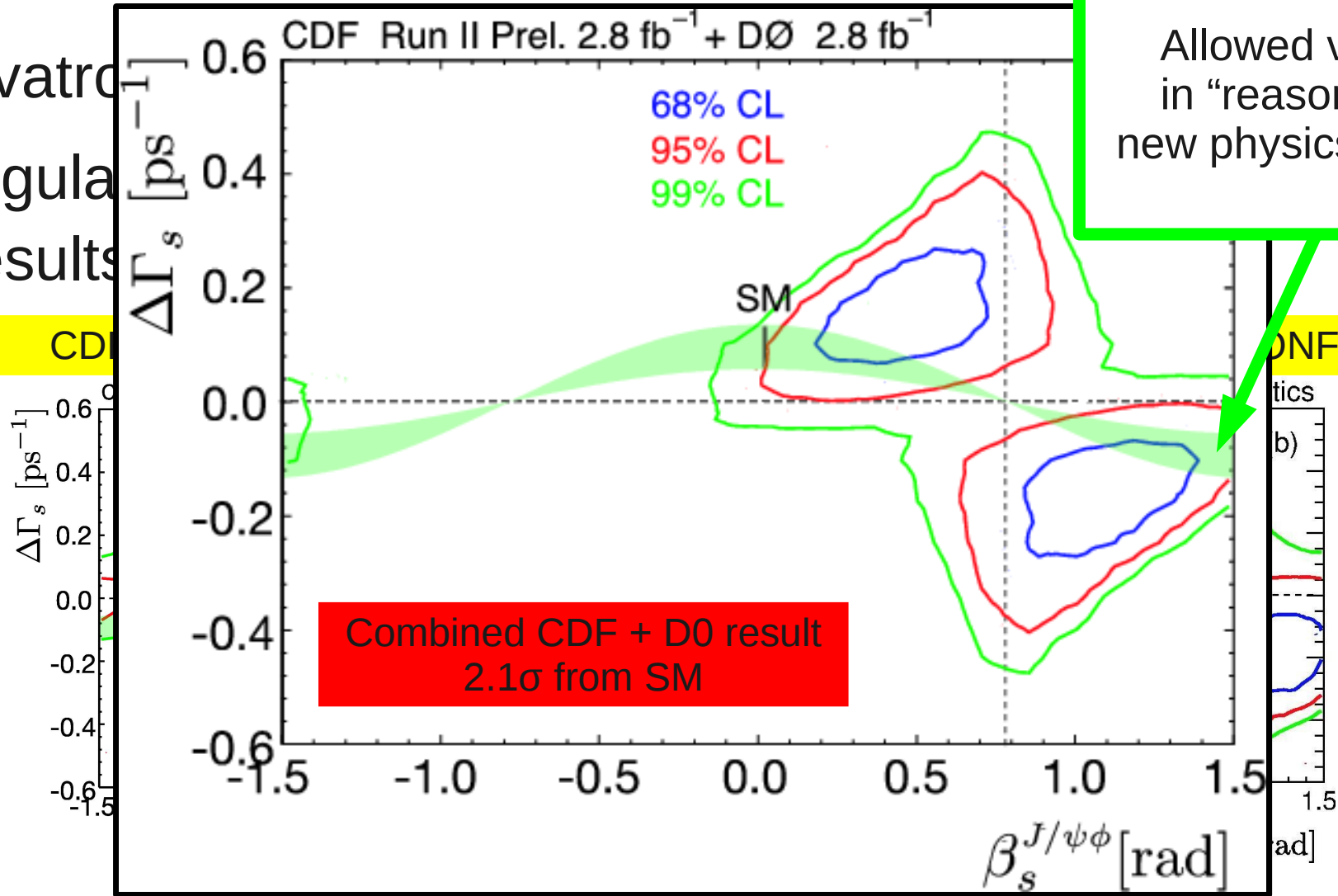


$1967 \pm 65 B_s \rightarrow J/\psi\phi$ events

$\Phi_s (B_s \rightarrow J/\psi\phi)$

Tevatron
Angular
Results

CD



68% CL interval: Φ_s in $[0.27, 0.59] \cup [0.97, 1.30]$ rad

95% CL interval: Φ_s in $[0.10, 1.42]$ rad

$B_s \rightarrow J/\psi\phi$: Latest Combination of results

Latest combination huge improvement on previous efforts

The two experiments perform very similar analyses

Two dimensional ($\Delta\Gamma_s$ vs. ϕ_s) log-likelihoods are added

But:

- Non-Gaussian regime
 - Uncertainty on ϕ_s strongly depends on value of $\Delta\Gamma_s$
- $B_s \rightarrow J/\psi\phi$ is not a two-dimensional problem
 - Consistency of results on other variables?
 - Higher dimensional combination would be better
 - Most practical way is simultaneous fit of both data sets
 - complicated reparametrisation could improve matters?
 - Work ongoing at the Tevatron ...

Example: $B \rightarrow DK, D \rightarrow K_S \pi^+ \pi^-$

- Three physics parameters (r_B, δ_B, γ)
- Dependence of observables as

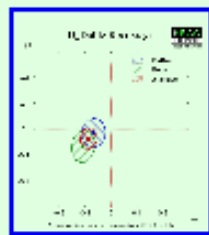
$$x_{\pm} = r_B \cos(\delta_B \pm \gamma), \quad y_{\pm} = r_B \sin(\delta_B \pm \gamma)$$

- Using these parameters addresses the problem that $\sigma(\gamma) \sim (r_B)^{-1}$

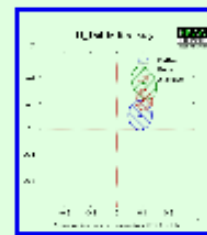
Mode	Experiment	x+	y+	x-	y-	Correlation	Reference
DK ⁻	BaBar N(BB)=383M	-0.067 ± 0.043 ± 0.014 ± 0.011	-0.015 ± 0.055 ± 0.006 ± 0.008	0.090 ± 0.043 ± 0.015 ± 0.011	0.053 ± 0.056 ± 0.007 ± 0.015	(stat) (syst) (model)	PRD 78 (2008) 034023
	Belle N(BB)=657M	-0.107 ± 0.043 ± 0.011 ± 0.055	-0.067 ± 0.059 ± 0.018 ± 0.063	0.105 ± 0.047 ± 0.011 ± 0.064	0.177 ± 0.060 ± 0.018 ± 0.054	(stat) (model)	arXiv:0803.3375
	Average No model error	-0.087 ± 0.032	-0.037 ± 0.041	0.104 ± 0.033	0.111 ± 0.042	(stat+syst)	HFAG correlated average $\chi^2 = 3.1/4$ dof (CL=0.54 ⇒ 0.6σ)

Figures:

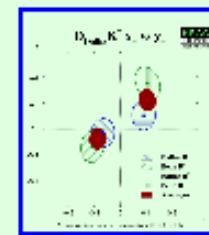
NB. The contours in these plots do not include model errors.



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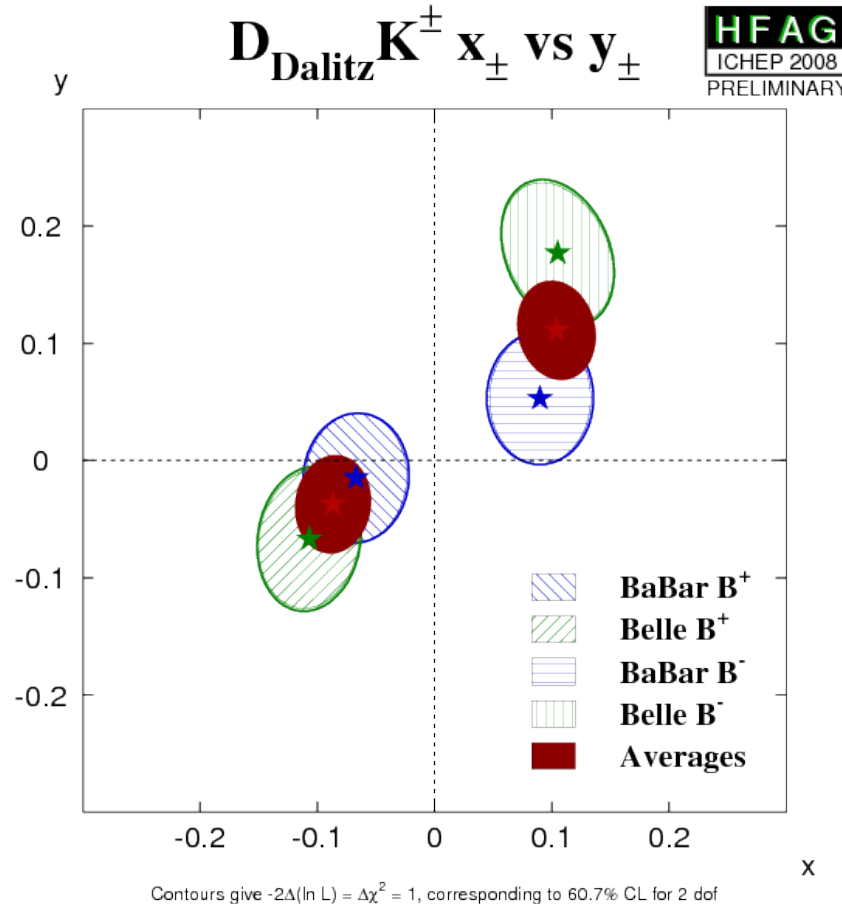
Example: $B \rightarrow DK, D \rightarrow K_S \pi^+ \pi^-$

- Three physics parameters (r_B, δ_B, γ)
- Dependence of observables as

- Using these

Mode	Experiment	$x \pm$
DK^-	BaBar N(BB)=383M	-0.067 ± 0.014
	Belle N(BB)=657M	-0.107 ± 0.011
	Average No model error	-0.087

Figures:
NB. The contours in these plots do not include model errors.



at $\sigma(y) \sim (r_B)^{-1}$

Reference
PRD 78 (2008) 034023
arXiv:0803.3375
HFAG correlated average $\chi^2 = 3.1/4$ dof (CL=0.54 \Rightarrow 0.6 σ)
eps.gz png

Example: $B \rightarrow DK$, $D \rightarrow K_S \pi^+ \pi^-$

- Problem is the complicated dependence on the Dalitz plot model
 - Effectively, a 4-dimensional nuisance parameter ...
(A typical nuisance parameter is 0-dimensional)
 - ... that depends on position in the (x_{\pm}, y_{\pm}) plane
 - Experiments use different models & assign different uncertainties
 - Ideally, HFAG should
 - Rescale results to a common model
 - Then perform the average
 - Assign a model uncertainty to the result of the average

Example: $B \rightarrow DK$, $D \rightarrow K_S \pi^+ \pi^-$

- Problem is the complicated dependence on the Dalitz plot model
 - Effectively, a 4-dimensional nuisance parameter ...
(A typical nuisance parameter is 0-dimensional)
 - ... that depends on position in the (x_{\pm}, y_{\pm}) plane
 - Experiments use different models & assign different uncertainties
 - Ideally, HFAG should
 - Rescale results to a common model
almost impossible – do nothing
 - Then perform the average
OK
 - Assign a model uncertainty to the result of the average
very difficult – do nothing



CKM 2010

<http://ckm2010.warwick.ac.uk/>

University of Warwick, UK, September 6-10, 2010

Please come!