

Scaling limits of sequential Monte Carlo genealogies

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Introduction

- The convergence theorem
- Sequential Monte Carlo (SMC): a class of numerical schemes for non-linear filtering with a wide range of applications [Del04].
- $(X_t, Y_t)_{t>1}$: a Markov chain in which Y_t is a noisy observation of X_t .
- $X_t|X_{t-1}$ has transition density p(x'|x) and $Y_t|X_t$ has density g(y|x).
- Interested in functionals of the *smoothing density* of $X_{1:T}|X_0, Y_{1:T}$:

 $P(x_1,\ldots,x_T) \propto \prod_{t=1}^{t} p(x_t|x_{t-1})g(y_t|x_t).$

- Particle filter with system size $N \in \mathbb{N}$ and proposal density q(x'|x):
 - Set $x_0^{(i)} \leftarrow x_0$ and $w_i \leftarrow 1/N$ for $i \in \{1, \ldots, N\}$.
 - 2 For each $t \in \{1, ..., T\}$:
 - **1** Sample $a_t^{(i)} \sim \text{Categorical}(w_1, \ldots, w_N)$ for $i \in \{1, \ldots, N\}$.

2 Sample $x_t^{(i)} \sim q(\cdot | x_{t-1}^{(a_t^{(i)})})$ for $i \in \{1, \dots, N\}$.

- **3** Set $\tilde{w}_i \leftarrow p(x_t^{(i)}|x_{t-1}^{(a_t^{(i)})})g(y_t|x_t^{(i)})/q(x_t^{(i)}|x_{t-1}^{(a_t^{(i)})})$ for $i \in \{1, \ldots, N\}$.
- A *P*-functional $f(x_1, \ldots, x_T)$ can be approximated as

 $\mathbb{E}_{P}[f(X_{1},\ldots,X_{T})] \approx \sum_{i=1}^{N} w_{i}f(x_{1}^{(a_{2}^{(i)})},\ldots,x_{T-1}^{(a_{T}^{(i)})},x_{T}^{(i)}).$

Path storage and degeneracy

- A naive implementation requires $O(N \times T)$ storage.
- But common ancestry induced by resampling (step 2.1 in the algorithm) means that many of these states are not evaluated in (1).

- Suppose Assumptions 1 and 2 hold, and that multinomial resampling is done at every time step.
- Then $(G_{\tau_N(t)}^{(n,N)})_{t\geq 0}$ converges to a Markov process $(G_t^{(n)})_{t\geq 0}$ as $N \to \infty$ when *n* is fixed.
- $(G_t^{(n)})_{t>0}$ admits only binary mergers.
- The rate at which blocks merge is bounded between two constants

$$0 < \frac{C_*}{C} \le 1 \le \frac{C}{C_*} < \infty$$

- C_* and C are determined by cumbersome bounds on joint moments of family sizes which hold under Assumption 2.
- If the vector of family sizes

 $(\nu_t^{(1)}, \dots, \nu_t^{(N)})$

is exchangeable at each time, then $(G_t^{(n)})_{t>0}$ is an *n*-coalescent with variable merger rate between C_*/C and C/C_* .

Consequences of the convergence theorem

- $T_N^{(n)}$: number of generations separating *n* leaves of the genealogical tree from their most recent common ancestor.
- Under Assumptions 1 and 2, the following bounds hold for any sufficiently large *N*:

$$\mathbb{E}\left[\frac{T_N^{(n)}}{N}\right] \leq \frac{2C}{C_*^2} \left(1 - \frac{1}{n}\right),$$
$$\mathbb{E}\left[\frac{T_N^{(n)}}{N}\right] \geq \frac{2C_*}{C^2} \left(1 - \frac{1}{n}\right) + O(N^{-1}),$$
$$\operatorname{Var}\left(\frac{T_N^{(n)}}{N}\right) \leq \left(\frac{4\pi^2}{3} - 12 + O(n^{-1})\right) \left(\frac{C}{C_*^2}\right)^2,$$
$$\operatorname{Var}\left(\frac{T_N^{(n)}}{N}\right) \geq \left(\frac{4\pi^2}{3} - 12 + O(n^{-1})\right) \left(\frac{C_*}{C^2}\right)^2 + O(N^{-1})$$

Simulation study: results





Figure 2: Averaged tree heights from 1 000 realisations for fixed N as a function of n on the left, and vice versa on the right.



- Hence the storage cost can be reduced.
- Common ancestry also means that times $t \ll T$ will be estimated using fewer than N realisations, increasing variance.
- Increased variance due to loss of paths is known as *path* degeneracy [LC95].
- This work identifies the asymptotic distribution of genealogical trees and hence provides the first tool for quantifying path degeneracy before running the algorithm.
- The limit is most conveniently expressed in terms of the *n*-coalescent [Kin82].

The *n*-coalescent and the genealogical process

- *n*-coalescent: a continuous-time process initialised from $\{\{1\}, \ldots, \{n\}\}$ in which each pair of blocks merges at rate 1.
- It terminates once one block remains, resulting in a random tree.
- A realisation is depicted in Figure 1.



Figure 1: A realisation of the 5-coalescent.

- The same encoding defines a genealogical process $(G_t^{(n,N)})_{t>T}$ of $n \leq N$ particles sampled uniformly from a particle filter.
- The initial state is $\{\{1\}, \ldots, \{n\}\}$.

- [JMR15] showed that $\mathbb{E}[T_N^{(N)}] = O(N \log N)$, also under Assumption 2.
- Our result provides an O(N) lower bound, showing their bound is tight up to a $\log N$ factor.
- $L_N^{(n)}$: total branch length of the tree connecting *n* leaves to their most recent common ancestor.
- Under Assumptions 1 and 2, the following bounds hold for any sufficiently large *N*:

$$\mathbb{E}\left[\frac{L_N^{(n)}}{N}\right] \leq \frac{2C}{C_*^2}(\log n + \gamma_{EM} + O(n^{-1})),$$
$$\mathbb{E}\left[\frac{L_N^{(n)}}{N}\right] \geq \frac{2C_*}{C^2}(\log n + \gamma_{EM} + O(n^{-1})) + O(N^{-1})$$
$$\operatorname{Var}\left(\frac{L_N^{(n)}}{N}\right) \leq \left(\frac{2\pi^2}{3} + O(n^{-1})\right) \left(\frac{C}{C_*^2}\right)^2,$$
$$\operatorname{Var}\left(\frac{L_N^{(n)}}{N}\right) \geq \left(\frac{2\pi^2}{3} + O(n^{-1})\right) \left(\frac{C_*}{C^2}\right)^2 + O(N^{-1}),$$

where $\gamma_{EM} \approx 0.577$ is the Euler-Mascheroni constant.

- All of these follow from elementary calculations for the *n*-coalescent on e.g. page 76 of [Wak09].
- In addition to contributing to SMC, this also extends the domain of attraction of the *n*-coalescent.
- Previous work has focused on *neutral* systems [Möh98], where family sizes do not depend on particle locations.
- Our theorem identifies the *n*-coalescent as the genealogical process

Figure 3: Variance of tree heights from 1 000 realisations for fixed N as a function of n on the left, and vice versa on the right.

Conclusions

- We have related genealogical trees of sequential Monte Carlo algorithms to the tractable *n*-coalescent.
- This enables *a priori* estimation of functionals of the tree.
- It also extends the domain of attraction of the *n*-coalescent.
- Simulation studies confirm that asymptotic results accurately describe algorithms with finite N.
- The strong assumptions do not appear to be necessary in practice.
- Our method only works when $n \ll N$, but the result seems to hold even when $n \approx N$.

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• Indices *i* and *j* belong to the same block in $G_t^{(n,N)}$ if particles *i* and *j* have a common ancestor t generations ago.

Assumptions and the time scale

- $\nu_t^{(i)}$: random number of offspring of particle *i* at time *t*.
- Assumption 1: Conditional on $(\nu_t^{(1)}, \ldots, \nu_t^{(N)})$, all valid assignments of offspring to parents are equally likely.
- Assumption 2: The densities p(x'|x), q(x'|x), and g(y|x) are bounded from above and away from 0.
- Numerical experiments suggest that neither is necessary.
- Assumption $1 \Rightarrow$ the marginal probability of two blocks merging in one generation at time *t* is

 $c_N(t) := \frac{1}{N(N-1)} \sum_{i=1}^N \mathbb{E}[\nu_t^{(i)}(\nu_t^{(i)}-1)].$

• The generalised inverse defines a time change

 $\tau_N(t) := \max\left\{s \ge 0 : \sum_{r=1}^s c_N(r) \ge t\right\},$

which is the correct rescaling for a non-trivial limiting genealogy.

of selective particle systems as well.

Simulation study: set up

- We conducted a simulation study to verify these bounds for finite N.
- The model was the discretised Ornstein-Uhlenbeck process

 $X_{t+1} = (1 - \Delta)X_t + \sqrt{\Delta}\xi_t,$ $X_0 \sim N(0, 1),$ $Y_t | X_t \sim N(X_t, \sigma^2),$

where $\xi_t \sim N(0, 1)$ is white noise, and with $\Delta = \sigma = 0.1$ as well as a time horizon T = 40960.

- We ran 1 000 realisations of a boostrap particle filter with q(x'|x) = p(x'|x) and stored the tree heights.
- Figures 2 and 3 show the corresponding estimates of the mean and variance of $T_N^{(n)}$.
- Assumption 2 fails for this experiment.
- Assumption 1 also fails for the three resampling schemes other than multinomial (see [DCM05] for details of these schemes).

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