

Outline 1. The leading philosophical approach to shared agency 2. Limits of this approach 3. (Building blocks for) an alternative approach 4. Motor representation 5. The emergence of mindreading



Shared Agency

Members of a flash mob simultaneously open their newspapers noisily

Two friends walk to the metro station together.

Merely Parallel Individual Agency

Onlookers simultaneously open their newspapers noisily (cf. Searle 1990: 92)

Two strangers walk the same route side-by-side.
(Gilbert 1990)

(Gilbert 2006, p. 5)

(Gilbert 2006, p. 5)

'The sine qua non of collaborative action is a joint goal [shared intention] and a joint commitment'

(Tomasello 2008, p. 181)

(Gilbert 2006, p. 5)

'The sine qua non of collaborative action is a joint goal [shared intention] and a joint commitment'

(Tomasello 2008, p. 181)

'the key property of joint action lies in its internal component [...] in the participants' having a "collective" or "shared" intention.'

(Alonso 2009, pp. 444-5)

(Gilbert 2006, p. 5)

'The sine qua non of collaborative action is a joint goal [shared intention] and a joint commitment'

(Tomasello 2008, p. 181)

'the key property of joint action lies in its internal component [...] in the participants' having a "collective" or "shared" intention.'

(Alonso 2009, pp. 444-5)

'Shared intentionality is the foundation upon which joint action is built.'

(Carpenter 2009, p. 381)

shared intention (or 'collective')

shared intention

<---->

action w. shared agency

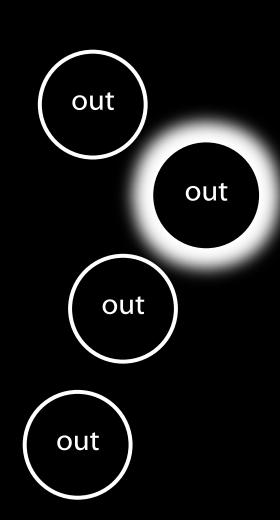
intention

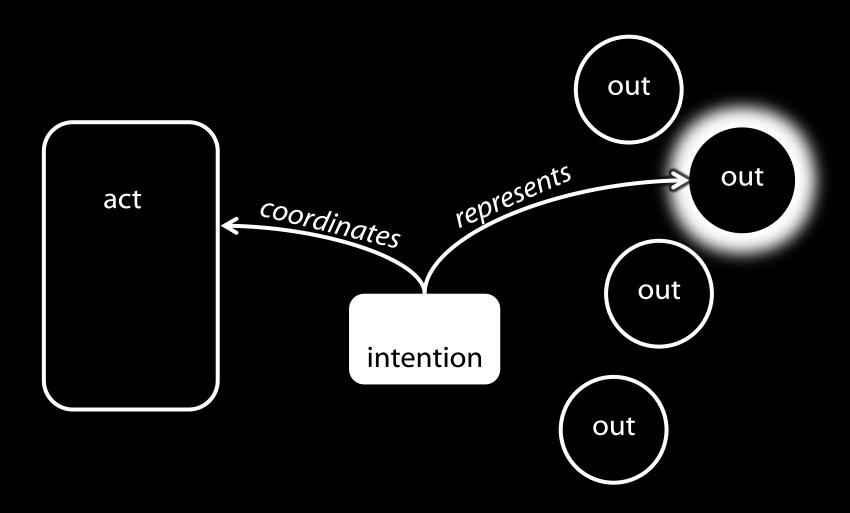
<---->

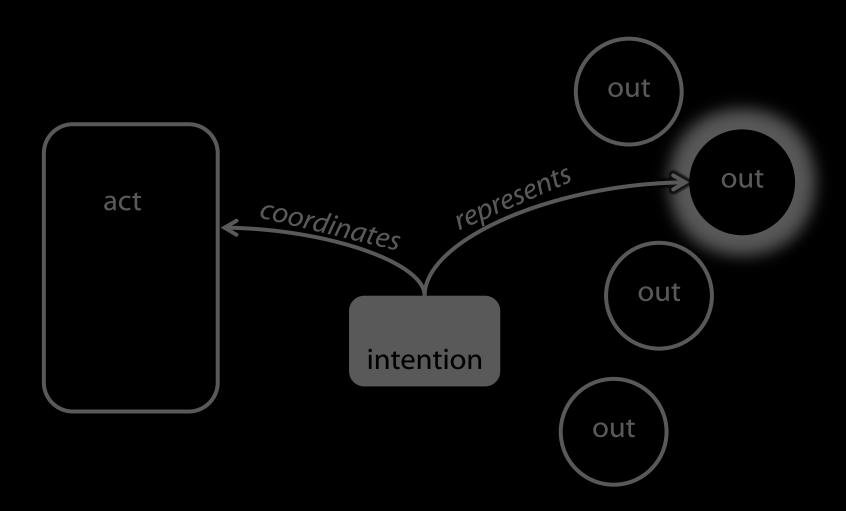
action w. individual agency What is the relation between a purposive outcome or outcomes to which it is directed?

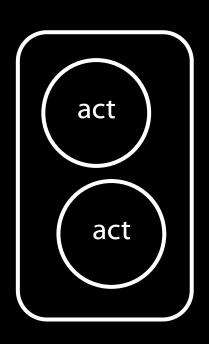
action and the

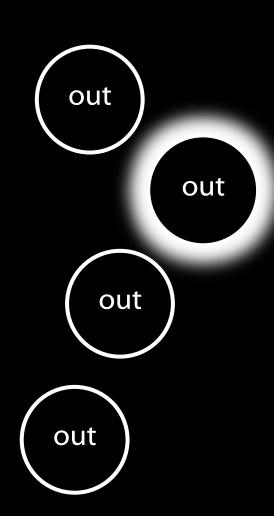
act

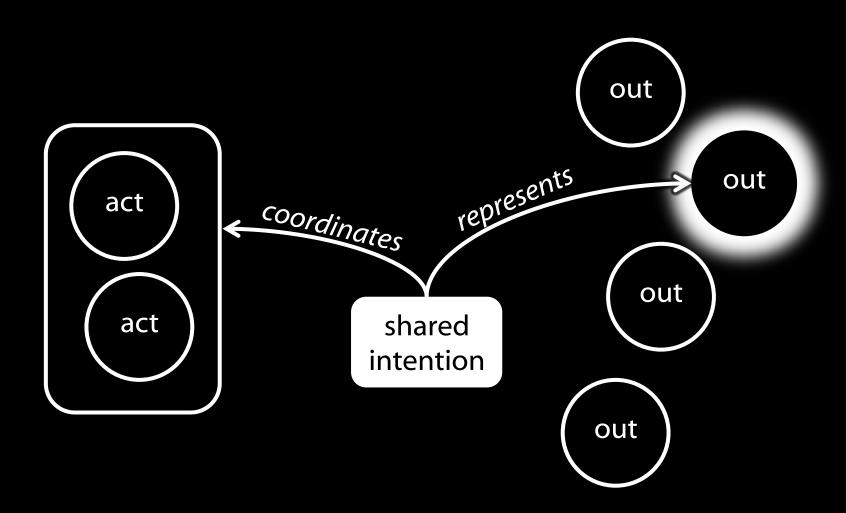


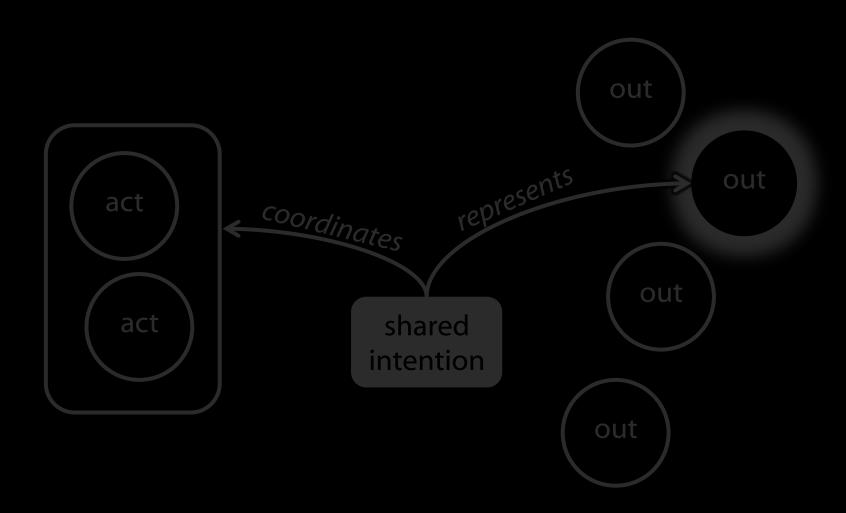












shared intention

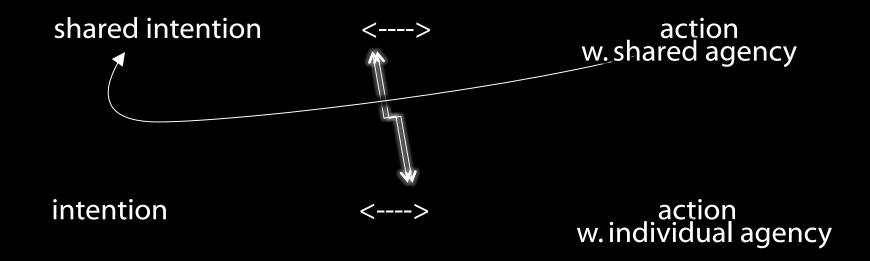
<---->

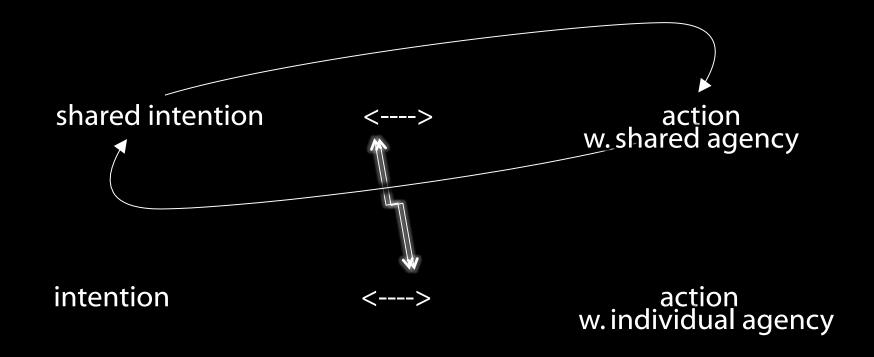
action w. shared agency

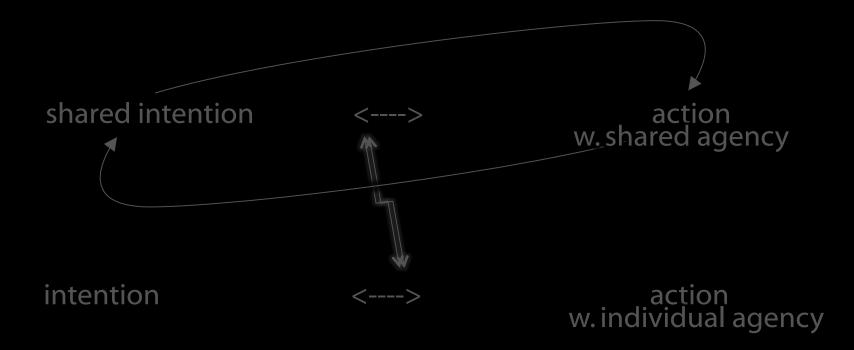
intention

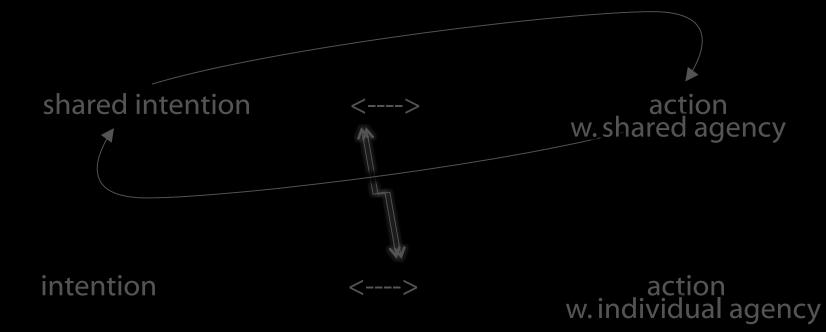
<---->

action w. individual agency











Functional characterisation

Substantial account



Functional characterisation shared intention serves to (a) coordinate activities, (b) coordinate planning and (c) structure bargaining

Substantial account



Functional characterisation shared intention serves to (a) coordinate activities, (b) coordinate planning and (c) structure bargaining

Substantial account

We have a shared intention that we J if

"1. (a) I intend that we J and (b) you intend that we J



Functional characterisation shared intention serves to (a) coordinate activities, (b) coordinate planning and (c) structure bargaining



Substantial account

We have a shared intention that we J if

"1. (a) I intend that we J and (b) you intend that we J

"2.I intend that we J in accordance with and because of la, lb, and meshing subplans of la and lb; you intend [likewise] ...

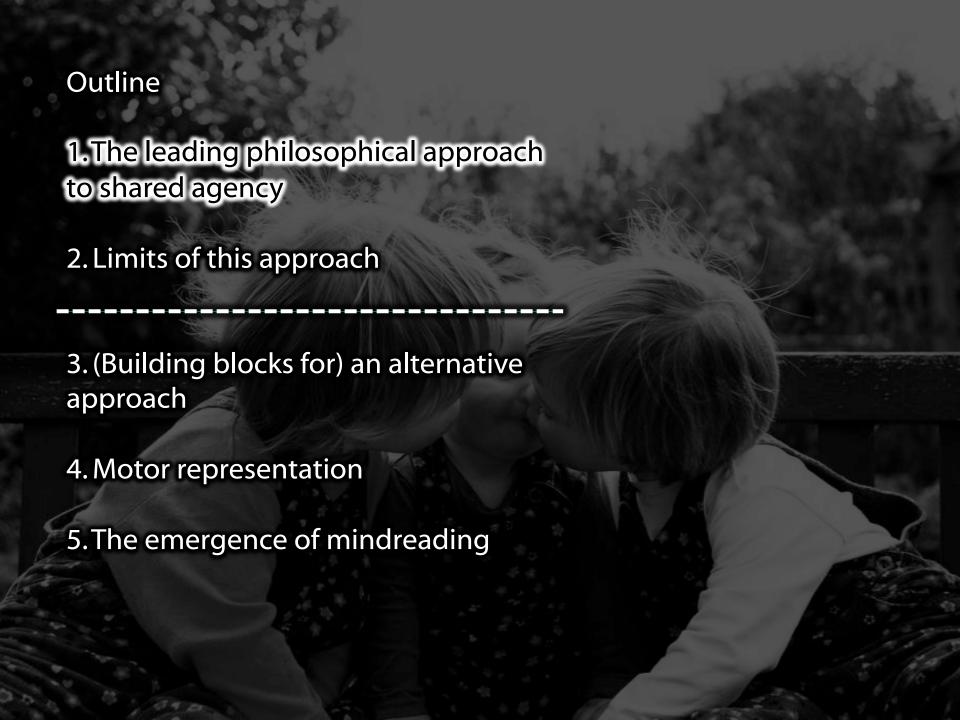
Functional characterisation shared intention serves to (a) coordinate activities, (b) coordinate planning and (c) structure bargaining



Substantial account

We have a shared intention that we J if

- "1. (a) I intend that we J and (b) you intend that we J
- "2.I intend that we J in accordance with and because of la, lb, and meshing subplans of la and lb; you intend [likewise] ...
- "3.1 and 2 are common knowledge between us"
 (Bratman 1993: View 4)



Outline

1. The leading philosophical approach to shared agency

2. Limits of this approach

- 3. (Building blocks for) an alternative approach
- 4. Motor representation
- 5. The emergence of mindreading

Functional characterisation shared intention serves to (a) coordinate activities, (b) coordinate planning and (c) structure bargaining



Substantial account

We have a shared intention that we J if

- "1. (a) I intend that we J and (b) you intend that we J
- "2.I intend that we J in accordance with and because of la, lb, and meshing subplans of la and lb; you intend [likewise] ...
- "3.1 and 2 are common knowledge between us"

 (Bratman 1993: View 4)

"the contribution of lower-level processes to social interaction has hardly been considered. This has led philosophers to postulate complex intentional structures that often seem to be beyond human cognitive ability in real-time social interactions."

(Knoblich & Sebanz 2008: 2022)

"2.I intend that we J in accordance with and because of la, lb, and meshing subplans of la and lb; you intend [likewise] ...



Functional characterisation shared intention serves to (a) coordinate activities, (b) coordinate planning and (c) structure bargaining

Intentions about intentions

Substantial account

We have a shared intention that we J if

"1. (a) I intend that we J and (b) you intend that we J

"2.I intend that we J in accordance with and because of la, lb, and meshing subplans of la and lb; you intend [likewise] ...

Functional characterisation shared intention serves to (a) coordinate activities, (b) coordinate planning and (c) structure bargaining

Intentions about intentions

Knowledge of others' knowledge of intentions about intentions

Substantial account

We have a shared intention that we J if

"1. (a) I intend that we J and (b) you intend that we J

"2.I intend that we J in accordance with and because of la, lb, and meshing subplans of la and lb; you intend [likewise] ...

Functional characterisation shared intention serves to (a) coordinate activities, (b) coordinate planning and (c) structure bargaining

Intentions about intentions

Knowledge of others' knowledge of intentions about intentions

Substantial account

We have a shared intention that we Jif

"1. (a) I intend that we J and (b) you intend that we J

"2.I intend that we J in accordance with and because of la, lb, and meshing subplans of la and lb; you intend [likewise] ...

Functional characterisation shared intention serves to (a) coordinate activities, (b) coordinate planning and (c) structure bargaining



Substantial account

We have a shared intention that we J if

- "1. (a) I intend that we J and (b) you intend that we J
- "2. I intend that we J in accordance with and because of la, lb, and meshing subplans of la and lb; you intend [likewise] ...
- "3.1 and 2 are common knowledge between us"

 (Bratman 1993: View 4)

Functional characterisation shared intention serves to (a) coordinate activities, (b) coordinate planning and (c) structure bargaining

'shared intentional agency consists, at bottom, in interconnected planning agency of the participants.'

(Bratman 2011, p. 11)

Substantial account

We have a shared intention that we J if

- "1. (a) I intend that we J and (b) you intend that we J
- "2. I intend that we J in accordance with and because of la, lb, and meshing subplans of la and lb; you intend [likewise] ...
- "3.1 and 2 are common knowledge between us"

 (Bratman 1993: View 4)

What is shared intention?

"the contribution of lower-level processes to social interaction has hardly been considered. This has led philosophers to postulate complex intentional structures that often seem to be beyond human cognitive ability in real-time social interactions."

(Knoblich & Sebanz 2008: 2022)

"2.I intend that we J in accordance with and because of la, lb, and meshing subplans of la and lb; you intend [likewise] ...

"3.1 and 2 are common knowledge between us"
(Bratman 1993: View 4)





"participation in cooperative, cultural interactions ... leads children to construct uniquely powerful forms of cognitive representation."

(Moll & Tomasello 2007)



"participation in cooperative, cultural interactions ... leads children to construct uniquely powerful forms of cognitive representation."

(Moll & Tomasello 2007)

"perception, action, and cognition are grounded in social interaction" (Sebanz & Knoblich 2008)



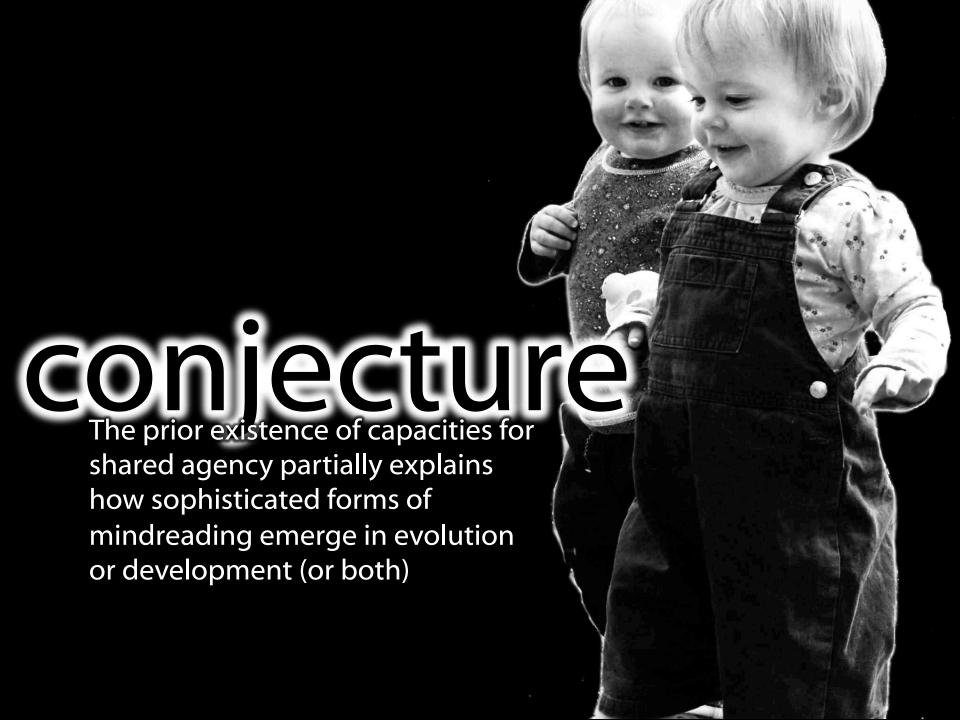
"participation in cooperative, cultural interactions ... leads children to construct uniquely powerful forms of cognitive representation."

(Moll & Tomasello 2007)

"perception, action, and cognition are grounded in social interaction" (Sebanz & Knoblich 2008)

"human cognitive abilities ... [are] built upon social interaction"

(Sinigaglia and Sparaci 2008)



2. Shared intention requires sophisticated mindreading.

Therefore:

2. Shared intention requires sophisticated mindreading.

Therefore:

2. Shared intention requires sophisticated mindreading.

Therefore:

shared intention

Shared intention requires sophisticated mindreading.

action w. shared agency

Therefore:

intention

 Shared agency could play no significant role in explaining how sophisticated forms of mindreading emerge. action w. individual agency

2. Shared intention requires sophisticated mindreading.

Therefore:

Outline

1. The leading philosophical approach to shared agency

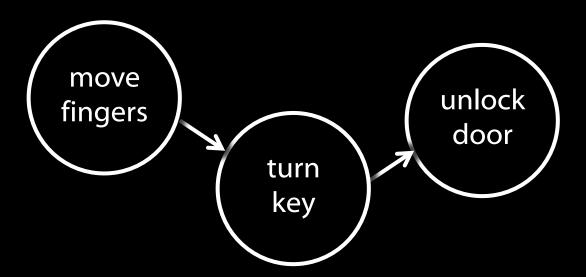
2. Limits of this approach

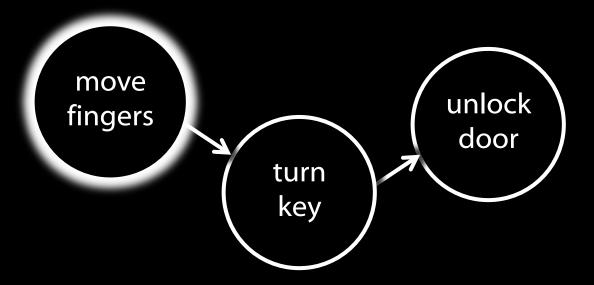
- 3. (Building blocks for) an alternative approach
- 4. Motor representation
- 5. The emergence of mindreading

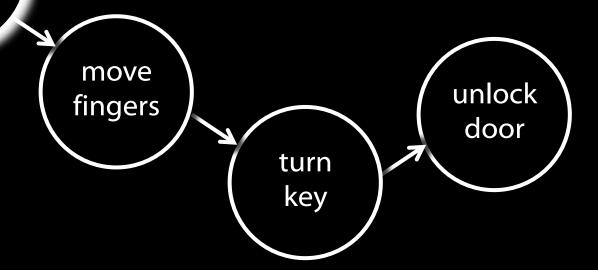
Outline

- 1. The leading philosophical approach to shared agency
- 2. Limits of this approach
- 3. (Building blocks for) an alternative approach
- 4. Motor representation
- 5. The emergence of mindreading

shared agency without shared intention







'our primitive actions, the ones we do not by doing something else, ... these are all the actions there are.' (Davidson 1971, p. 59).

tidying up the toys together
(Behne et al 2005)

cooperatively pulling handles in sequence to make a dog-puppet sing

(Brownell et al 2006)

bouncing a ball on a large trampoline together

(Tomasello & Carpenter 2007)

pretending to row a boat together unlock door

move fingers

turn key

'our primitive actions, the ones we do not by doing something else, ... these are all the actions there are.' (Davidson 1971, p. 59).

tidying up the toys together (Behne et al 2005)

cooperatively pulling handles in sequence to make a dog-puppet sing (Brownell et al 2006)

bouncing a ball on a large trampoline together

(Tomasello & Carpenter 2007)

pretending to row a boat together unlock

door

move fingers

turn key Joint action: an action with two or more

agents (Ludwig 2007)

my pulling dog's singing your pulling

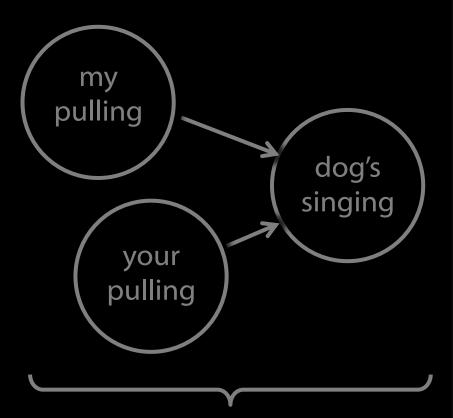
We make the dog sing

tidying up the toys together
(Behne et al 2005)

cooperatively pulling handles in sequence to make a dog-puppet sing (Brownell et al 2006)

bouncing a ball on a large trampoline together

(Tomasello & Carpenter 2007)



We make the dog sing

tidying up the toys together
(Behne et al 2005)

cooperatively pulling handles in sequence to make a dog-puppet sing

(Brownell et al 2006)

bouncing a ball on a large trampoline together

(Tomasello & Carpenter 2007)

- Joint action: an action with two or more agents (Ludwig 2007)
- Bodily movements 'are all the actions there are' (Davidson 1971, p. 59)
- In supposedly paradigm cases of joint action, there are no bodily movements with more than one agent.

4supposedly paradigm cases are not joint actions.

tidying up the toys together
(Behne et al 2005)

cooperatively pulling handles in sequence to make a dog-puppet sing

(Brownell et al 2006)

bouncing a ball on a large trampoline together

(Tomasello & Carpenter 2007)

- 1 Joint action: an action with two or more agents (Ludwig 2007)
- Bodily movements 'are all the actions there are' (Davidson 1971, p. 59)
- In supposedly paradigm cases of joint action, there are no bodily movements with more than one agent.

4supposedly paradigm cases are not joint actions.

too narro

up the toys together
(Behne et al 2005)

make a dog-puppet sing

(Brownell et al 2006)

bouncing a ball on a large trampoline together

(Tomasello & Carpenter 2007)

- Joint action:

 an action with two or more
 agents (Ludwig 2007)
- Bodily movements 'are all the actions there are' (Davidson 1971, p. 59)
- In supposedly paradigm cases of joint action, there are no bodily movements with more than one agent.

4supposedly paradigm cases are not joint actions.



up the toys together
(Behne et al 2005)

eratively pulling handles in sequence to make a dog-puppet sing

(Brownell et al 2006)

bouncing a ball on a large trampoline together

(Tomasello & Carpenter 2007)

- 1 Joint action: an action with two or more agents (Ludwig 2007)
- 2 Bodily movements 'are all the actions there are' (Davidson 1971, p. 59)
- In supposedly paradigm cases of joint action, there are no bodily movements with more than one agent.

4Supposedly paradigm cases are not joint actions.



up the toys together
(Behne et al 2005)

eratively pulling handles in sequence to make a dog-puppet sing

(Brownell et al 2006)

bouncing a ball on a large trampoline together

(Tomasello & Carpenter 2007)

- 1 Joint action: an action with two or more agents (Ludwig 2007)
- 2 Bodily movements 'are all the actions there are' (Davidson 1971, p. 59)
- In supposedly paradigm cases of joint action, there are no bodily movements with more than one agent.

As upposedly paradigm cases are not joint actions.

too narro

up the toys together
(Behne et al 2005)

weratively pulling nandles in sequence to make a dog-puppet sing

(Brownell et al 2006)

bouncing a ball on a large trampoline together

(Tomasello & Carpenter 2007)

Joint action: an action event with two or more agents (Ludwig 2007)

Grounding

events $D_1, ... D_n$ ground E, if:

 D_1 , ... D_n and E occur;

 $D_1, ... D_n$ are each (perhaps improper) parts of E; and every event that is a proper part of E but does not overlap $D_1, ... D_n$ is caused by some or all of $D_1, ... D_n$.

(Adapted from Pietroski 1998)

Grounding

events $D_1, ... D_n$ ground E, if:

 D_1 , ... D_n and E occur;

 $D_1, ... D_n$ are each (perhaps improper) parts of E; and every event that is a proper part of E but does not overlap $D_1, ... D_n$ is caused by some or all of $D_1, ... D_n$.

Agency

For an individual to be among the agents of an event is for there to be actions $a_1, ... a_n$ which ground this event where the individual is an agent of one or more of these actions.

(Adapted from Pietroski 1998)

Joint action: an action event with two or more agents (Ludwig 2007) Joint action: an action-event with two or more agents (Ludwig 2007)

my pulling dog's singing your pulling

We make the dog sing

tidying up the toys together (Behne et al 2005)

cooperatively pulling handles in sequence to make a dog-puppet sing (Brownell et al 2006)

bouncing a ball on a large trampoline together

(Tomasello & Carpenter 2007)

Joint action: an action event with two or more agents (Ludwig 2007)

tidying up the toys together
(Behne et al 2005)

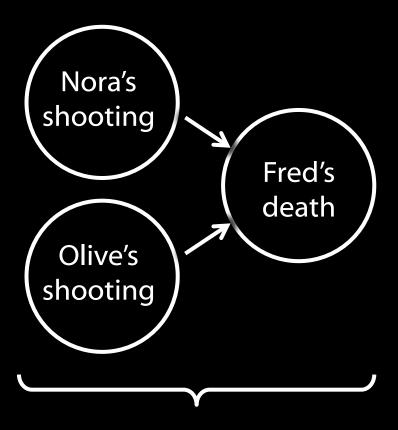
cooperatively pulling handles in sequence to make a dog-puppet sing

(Brownell et al 2006)

bouncing a ball on a large trampoline together

(Tomasello & Carpenter 2007)

Joint action: an action-event with two or more agents (Ludwig 2007)



Fred's killing

tidying up the toys together
(Behne et al 2005)

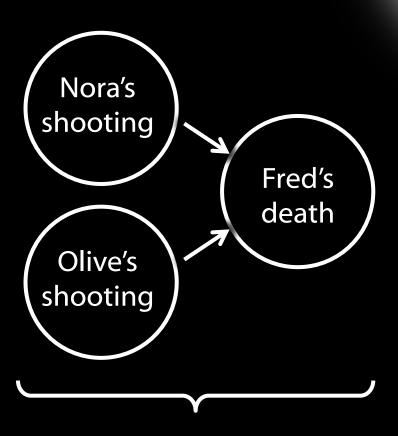
cooperatively pulling handles in sequence to make a dog-puppet sing

bouncing a ball on a large trampoline together

(Tomasello & Carpenter 2007)

(Brownell et al 2006)

Joint action: an action event with two or more agents (Ludwig 2007)



Fred's killing

too broad up the toys together
(Behne et al 2005)

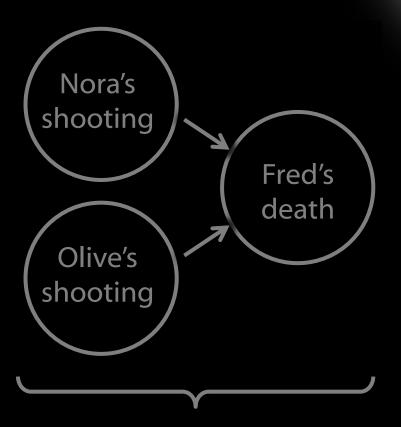
eratively pulling nandles in sequence to make a dog-puppet sing

(Brownell et al 2006)

bouncing a ball on a large trampoline together

(Tomasello & Carpenter 2007)

Joint action: an action event with two or more agents (Ludwig 2007)



Fred's killing

tidying up the toys together
broad

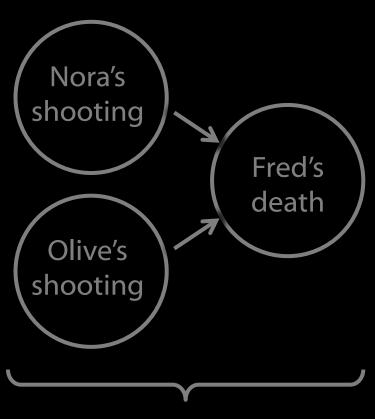
(Behne et al 2005)

cooperatively pulling
handles in sequence to
make a dog-puppet sing

(Brownell et al 2006)

bouncing a ball on a large trampoline together

(Tomasello & Carpenter 2007)

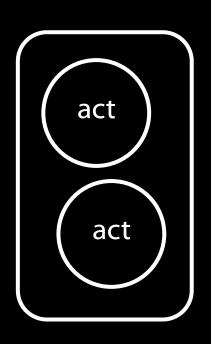


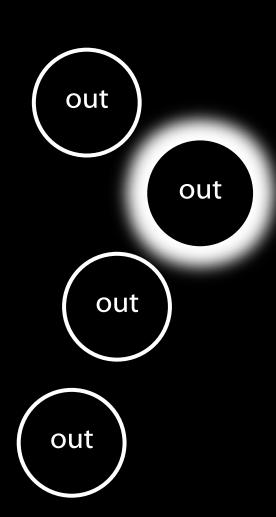
Fred's killing

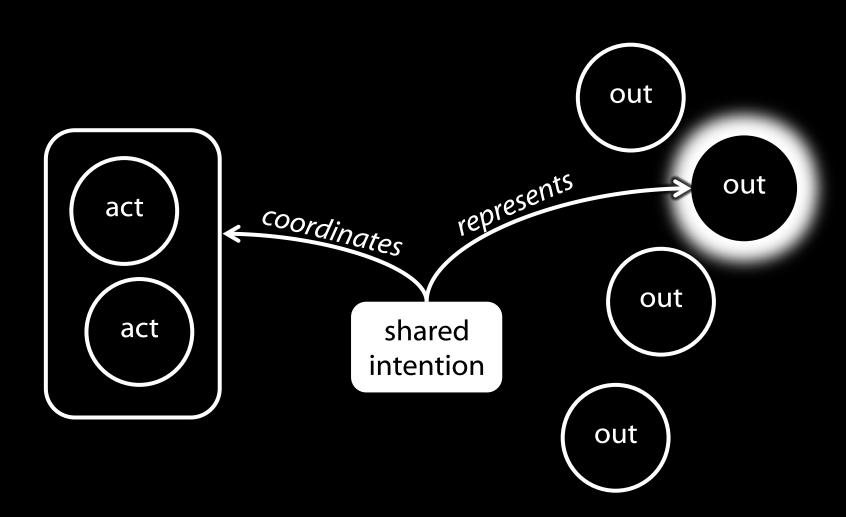
cooperatively pulling handles in sequence to make a dog-puppet sing (Brownell et al 2006)

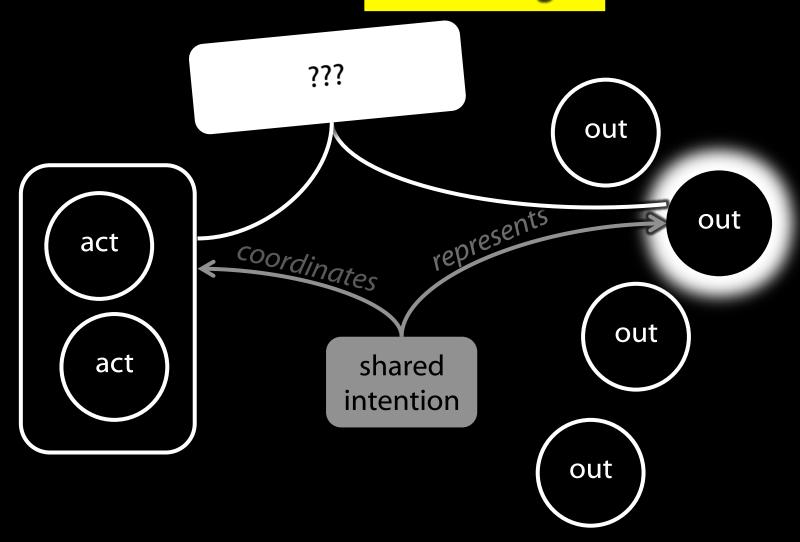
bouncing a ball on a large trampoline together

(Tomasello & Carpenter 2007)









<u>G is a distributive goal</u>: it is an outcome to which each agent's actions are individually directed and it is possible that: all actions succeed relative to this outcome.

Shared Agency

Members of a flash mob simultaneously open their newspapers noisily

Two friends walk to the metro station together.

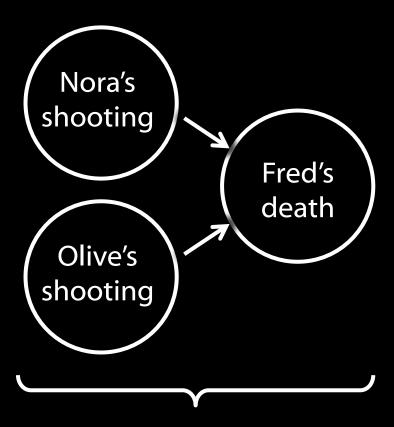
Merely Parallel Individual Agency

Onlookers simultaneously open their newspapers noisily (cf. Searle 1990: 92)

Two strangers walk the same route side-by-side.
(Gilbert 1990)

<u>G is a distributive goal</u>: it is an outcome to which each agent's actions are individually directed and it is possible that: all actions succeed relative to this outcome.

<u>G is a distributive goal</u>: it is an outcome to which each agent's actions are individually directed and it is possible that: all actions succeed relative to this outcome.



Fred's killing

<u>G is a distributive goal</u>: it is an outcome to which each agent's actions are individually directed and it is possible that: all actions succeed relative to this outcome.

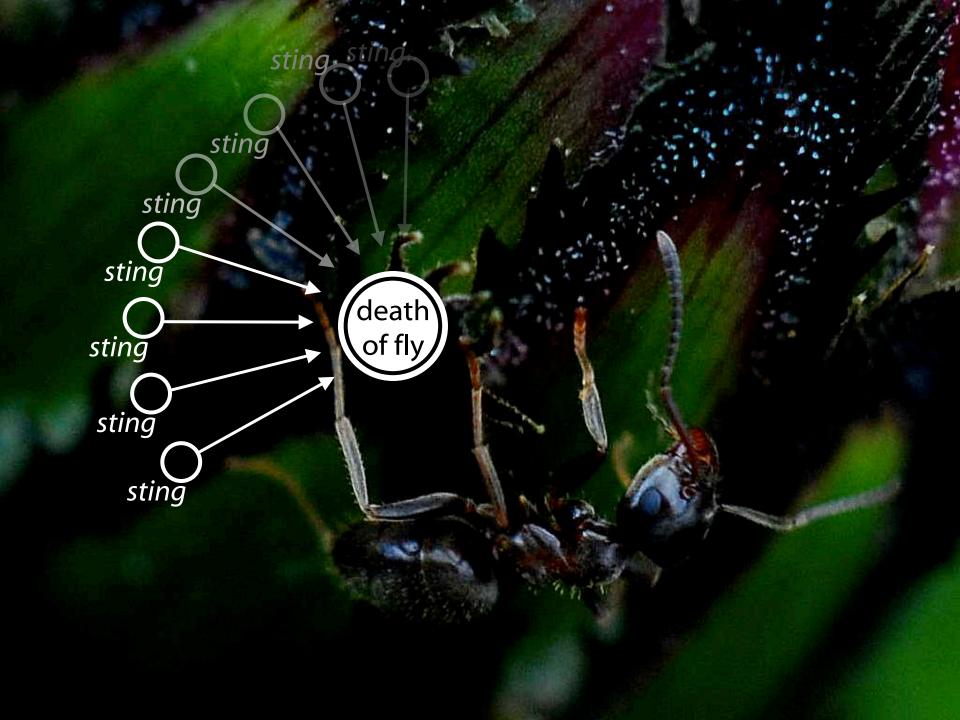
- (a) it is a distributive goal;
- (b) the actions are coordinated; and
- (c) coordination of this type would normally facilitate occurrences of outcomes of this type.

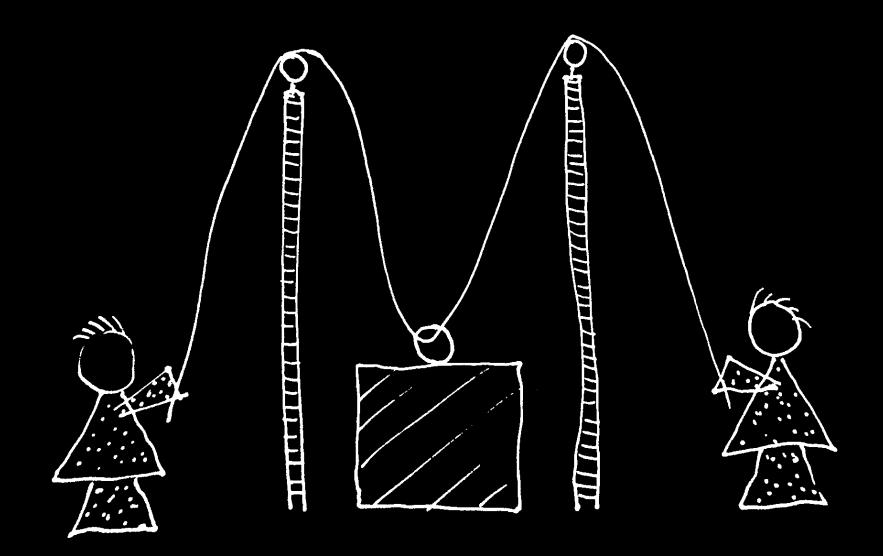
"It ... seems useful to draw a distinction between elementary or thin forms of joint action common to humans and other social mammals and sophisticated or thick forms of joint action, perhaps unique to the human species."

(Pacherie & Dokic 2006, 110)

- (a) it is a distributive goal;
- (b) the actions are coordinated; and
- (c) coordination of this type would normally facilitate occurrences of outcomes of this type.







"It ... seems useful to draw a distinction between elementary or thin forms of joint action common to humans and other social mammals and sophisticated or thick forms of joint action, perhaps unique to the human species."

(Pacherie & Dokic 2006, 110)

- (a) it is a distributive goal;
- (b) the actions are coordinated; and
- (c) coordination of this type would normally facilitate occurrences of outcomes of this type.

<u>G is a distributive goal</u>: it is an outcome to which each agent's actions are individually directed and it is possible that: all actions succeed relative to this outcome.

- (a) it is a distributive goal;
- (b) the actions are coordinated; and
- (c) coordination of this type would normally facilitate occurrences of outcomes of this type.

<u>G is a distributive goal</u>: it is an outcome to which each agent's actions are individually directed and it is possible that: all actions succeed relative to this outcome.

G is a shared goal

G is a collective goal

- (a) it is a distributive goal;
- (b) the actions are coordinated; and
- (c) coordination of this type would normally facilitate occurrences of outcomes of this type.

Each agent most wants and expects each of the other agents to perform activities directed to the goal.

<u>G is a distributive goal</u>: it is an outcome to which each agent's actions are individually directed and it is possible that: all actions succeed relative to this outcome.

G is a shared goal

G is a collective goal

- (a) it is a distributive goal;
- (b) the actions are coordinated; and
- (c) coordination of this type would normally facilitate occurrences of outcomes of this type.

Each agent most wants and expects each of the other agents to perform activities directed to the goal.

<u>G is a distributive goal</u>: it is an outcome to which each agent's actions are individually directed and it is possible that: all actions succeed relative to this outcome.

G is a shared goal

G is a collective goal

- (a) it is a distributive goal;
- (b) the actions are coordinated; and
- (c) coordination of this type would normally facilitate occurrences of outcomes of this type.

Each agent most wants and expects each of the other agents to perform activities directed to the goal.

<u>G is a distributive goal</u>: it is an outcome to which each agent's actions are individually directed and it is possible that: all actions succeed relative to this outcome.

G is a shared goal

G is a collective goal

- (a) it is a distributive goal;
- (b) the actions are coordinated; and
- (c) coordination of this type would normally facilitate occurrences of outcomes of this type.

Each agent most wants and expects each of the other agents to perform activities directed to the goal.

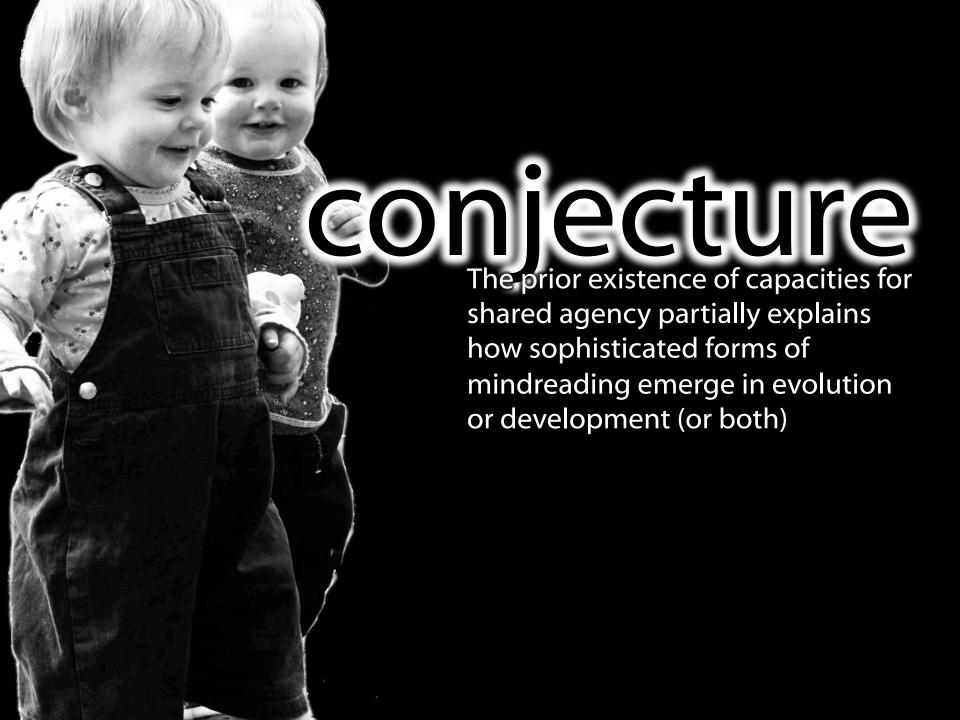
G is a distributive goal: it is an outcome to which each agent's actions are individually directed and it is possible and actions succeed relative to this outcome.

G is a shared goal

G is a collective goal

- (a) it is a distributive goal;
- (b) the actions are coordinated; and
- (c) coordination of this type would normally facilitate occurrences of outcomes of this type.

Each agent most wants and expects each of the other agents to perform activities directed to the goal.



1. All shared agency involves shared intention.

2. Shared intention requires sophisticated mindreading.

Therefore:

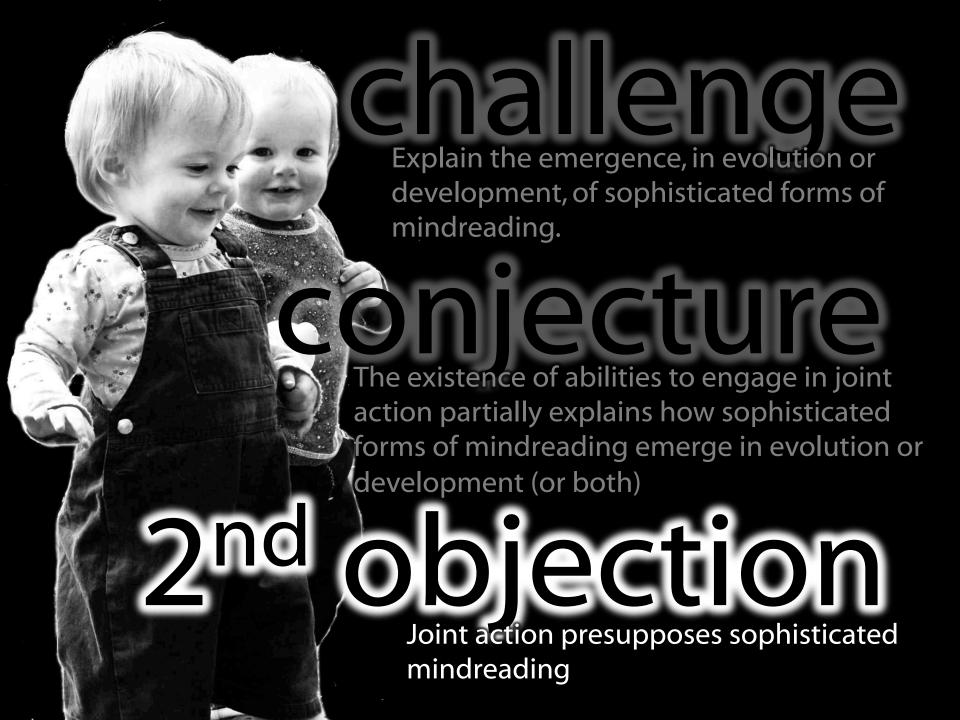
3. Shared agency could play no or development (or both) significant role in explaining how sophisticated forms of mindreading emerge.

The prior existence of capacities for

shared agency partially explains

mindreading emerge in evolution

how sophisticated forms of



tidying up the toys together
(Behne et al 2005)

cooperatively pulling handles in sequence to make a dog-puppet sing

(Brownell et al 2006)

bouncing a ball on a large trampoline together

(Tomasello & Carpenter 2007)

painting a house together
(Bratman 1992)

lifting a heavy sofa together
(Velleman 1997)

preparing a hollandaise sauce together

(Searle 1990)

going to Chicago together
(Kutz 2000)

walking together (Gilbert 1990)

tidying up the toys together
(Behne et al 2005)

cooperatively pulling handles in sequence to make a dog-puppet sing

(Brownell et al 2006)

bouncing a ball on a large trampoline together

(Tomasello & Carpenter 2007)